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Cascades and dissipation ratio in rotating magnetohydrodynamic turbulence at low magnetic Prandtl number

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A phenomenology of isotropic magnetohydrodynamic (MHD) turbulence subject to both rotation and applied magnetic field is presented. It is assumed that the triple correlation decay time is the shortest between the eddy turn-over time and the ones associated to the rotating frequency and the Alfvén wave period. For $\text{Pm} = 1$ it leads to four kinds of piecewise spectra, depending on four parameters: injection rate of energy, magnetic diffusivity, rotation rate, and applied field. With a shell model of MHD turbulence (including rotation and applied magnetic field), spectra for $\text{Pm} \leq 1$ are presented, together with the ratio between magnetic and viscous dissipations.

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I. INTRODUCTION

Magnetohydrodynamic (MHD) turbulence in natural objects is often subject to global rotation or applied magnetic field or both. In the Earth's core the turbulence occurs under the fast rotation of the planet and is embedded in the dipolar magnetic field produced by dynamo action. Such double effect is currently studied in an experiment with liquid sodium [1]. Waves of different types have been measured that might be attributed to either Alfvén or Rossby waves or a combination of both. The frequency spectra show a series of bumps, attributed to wave frequencies, in addition to piecewise slopes. A proper understanding of such rotating MHD turbulence would require a nonisotropic formalism. Several ones have been developed for fast rotation [2–4]. Phenomenological approaches relying on three-wave [5] or four-wave [6] resonant interactions have been developed for an applied field and documented numerically [7].

In the present paper we come back to the phenomenology of Iroshnikov [8] and Kraichnan [9] for isotropic MHD turbulence. They argued that the destruction of phase coherence by the Alfvén waves traveling in opposite directions introduces a new time scale τ_A . It might control the energy transfer, provided it is shorter than the eddy turn-over time scale τ_K . Applying the same idea, Zhou [10] suggested that due to global rotation the kinetic-energy spectrum is affected through phase scrambling, leading to a third time scale τ_Ω associated with the rotation frequency. The generalization to both global rotation and applied magnetic field is therefore straightforward (see Sec. II), the energy transfers being controlled by the shortest time scale between τ_K , τ_A , and τ_Ω .

An advantage of assuming isotropy is that it can be tested against simulations with shell models. Shell models are toy models that mimic the original Navier-Stokes and induction equations projected in the Fourier space within shells which are logarithmically spaced. There are only two complex variables per shell—one corresponding to the velocity and the other to the magnetic field [11,12]. Depending on the model, the energy transfers may be considered as local or not [13]. Such models allow for simulations at realistically low vis-

cosity ν and magnetic Prandtl number $\text{Pm} = \nu / \eta$ [14], where η is the magnetic diffusivity. The time dependency of the solutions is strongly chaotic, eventually leading to intermittency. Therefore, though all geometrical details of velocity and magnetic fields are lost, shell models give relevant information on spectral quantities such as energies, helicities, energy transfers, etc. In Sec. III we introduce such a shell model of rotating MHD turbulence, taking care to keep the terms corresponding to rotation and applied magnetic field as simple as possible. For $\text{Pm} \leq 1$ we calculate the spectra for different values of rotation Ω and applied field V_A . We also calculate the ratio of the joule dissipation over the viscous dissipation, which cannot be estimated from scaling laws.

II. PHENOMENOLOGY

A. Time scales

Following [9] (see also [10,15]), we assume that for homogeneous isotropic statistically steady turbulence the decay of triple correlations, occurring in a time scale $\tau_3(k)$, is responsible for the turbulent spectral transfer ε from wave numbers lower than k to higher wave numbers. This implies $\tau_3(k) \sim \varepsilon$. Assuming in addition that ε depends only on the wave number k and the kinetic-energy spectral density $E(k)$, a simple dimensional analysis leads to

$$\varepsilon \sim \tau_3(k) E^2(k) k^4. \quad (1)$$

The kinetic-energy spectral density is defined as $E(k) = k^{-1} u^2(k)$, where $u(k)$ is the characteristic velocity of eddies at scale k .

In the absence of applied magnetic field and rotation, the time scale for $\tau_3(k)$ is the eddy turn-over time,

$$\tau_K(k) = [ku(k)]^{-1}, \quad (2)$$

leading to the Kolmogorov turbulence energy spectrum $E(k) \sim \varepsilon^{2/3} k^{-5/3}$.

For fully developed MHD turbulence at $\text{Pm} = 1$ the same Kolmogorov spectrum is assumed for both kinetic and magnetic energies provided that the system is much above the

onset for dynamo action [12]. In that case $E(k)$ denotes either the kinetic or magnetic energy spectral density. In the presence of an applied magnetic field \mathbf{B}_0 another possible time scale for $\tau_3(k)$ is the Alfvén time scale,

$$\tau_A(k) = [kV_A]^{-1}, \quad (3)$$

leading to the Alfvén turbulence energy spectrum $E(k) \sim V_A^{1/2} \varepsilon^{1/2} k^{-3/2}$.

Finally, for rotating turbulence caused by uniform rotation Ω a third possible time scale for $\tau_3(k)$ is the rotating frequency

$$\tau_\Omega = \Omega^{-1}, \quad (4)$$

leading to the rotating turbulence energy spectrum $E(k) \sim \Omega^{1/2} \varepsilon^{1/2} k^{-2}$.

The value of $\tau_3(k)$ is naturally defined by

$$\tau_3(k) = \min\{\tau_K(k), \tau_A(k), \tau_\Omega\}. \quad (5)$$

It corresponds to the fastest way to transfer energy to smaller scales between nonlinear eddy cascade, Alfvén wave interactions, and phase scrambling due to rotation. In addition we define the magnetic dissipation time scale by

$$\tau_\eta(k) = (k^2 \eta)^{-1}. \quad (6)$$

The dissipation range corresponds to $k \geq k_\eta$ with k_η defined by $\tau_3(k_\eta) = \tau_\eta(k_\eta)$.

Therefore, at each scale k^{-1} , we have to compare the four time scales $\tau_K(k)$, $\tau_A(k)$, τ_Ω and $\tau_\eta(k)$ to figure out what kind of turbulence occurs.

B. Spectra for $\text{Pm}=1$

At $k \ll 1$, $\tau_\Omega < \min\{\tau_K(k), \tau_A(k), \tau_\eta(k)\}$ implying that $\tau_3(k) = \tau_\Omega$ unless $\Omega=0$. This corresponds to a rotating turbulence with $E(k) = \Omega^{1/2} \varepsilon^{1/2} k^{-2}$. For larger k , $\tau_K(k)$, $\tau_A(k)$ and $\tau_\eta(k)$ decrease while τ_Ω stays constant. Therefore, provided that the dissipation is not too strong, a first transition occurs at a scale for which $\tau_\Omega = \min\{\tau_K(k), \tau_A(k)\}$. This scale is either (i) $k_1 = (\Omega^3/\varepsilon)^{1/2}$ if $\varepsilon \geq \Omega V_A^2$ or (ii) $k_1 = \Omega/V_A$ if $\varepsilon \leq \Omega V_A^2$. This transition leads to either (i) a Kolmogorov $E(k) = \varepsilon^{2/3} k^{-5/3}$ or (ii) an Alfvén $E(k) = V_A^{1/2} \varepsilon^{1/2} k^{-3/2}$ turbulence. This transition does not occur if the dissipation overcomes the Kolmogorov and Alfvén turbulences, namely, if (i) $\eta \geq \varepsilon/\Omega^2$ and (ii) $\eta \geq V_A^2/\Omega$. In that case the dissipation scale is given by $k_\eta = (\Omega/\eta)^{1/2}$.

In case (i) provided again that dissipation is not too strong, a second transition occurs at $k_2 = \varepsilon/V_A^3$. This transition leads to an Alfvén turbulence $E(k) = V_A^{1/2} \varepsilon^{1/2} k^{-3/2}$ until the dissipation becomes dominant for $k \geq k_\eta$ with $k_\eta = V_A/\eta$. If $V_A^4 \leq \eta \varepsilon$ the dissipation overcomes the Alfvén turbulence and the dissipation scale is given by $k_\eta = \varepsilon^{1/4} \eta^{-3/4}$.

In case (ii) a second transition toward a Kolmogorov turbulence is not possible. Indeed, it would occur at $k = \varepsilon/V_A^3$ which cannot be larger than k_1 from the condition $\varepsilon \leq \Omega V_A^2$. In that case the Alfvén turbulence simply extends to the dissipation scale given by $k_\eta = V_A/\eta$.

The four possible types of inertial regimes are sketched in Fig. 1 in which the spectral energy density is plotted versus k

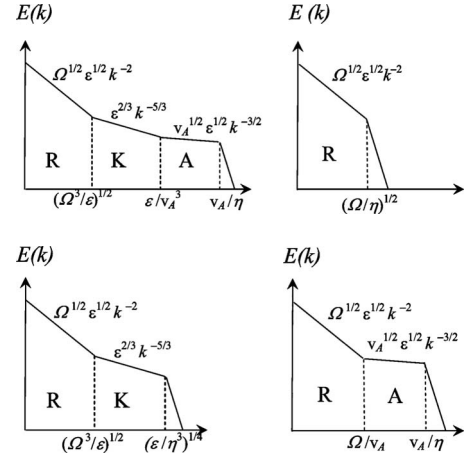


FIG. 1. Possible inertial regimes of energy spectral density in rotating MHD turbulence for $\text{Pm}=1$. The capital letters R, A, and K denote a rotating, Alfvén, or Kolmogorov turbulence.

for $\text{Pm}=1$. The slopes and characteristic wave numbers are indicated. The conditions to get one of these four possible inertial regimes are summarized in the plane (V_A, Ω) in Fig. 2. The case without rotation corresponds to the abscissa axis. Then, two regimes, KA or K, are possible depending whether $\eta/V_A^2 \leq V_A^2/\varepsilon$ or not. The case without applied magnetic field corresponds to the vertical axis. Then, the two regimes, R or RK, are possible depending whether $\eta\Omega/\varepsilon \geq \Omega^{-1}$ or not. Without both rotation and applied magnetic field a K type of turbulence is found.

From our analysis we note that inertial regimes of type AK or RAK are never possible. On the other hand, inertial regimes of type KA, A, or K are possible provided the forcing scale is sufficiently small. In Fig. 1 it corresponds to begin the spectra at a larger wave number. For $\text{Pm} < 1$ the inertial range of the kinetic-energy spectrum prolongates at scales smaller than k_η with either an R, K, or RK spectrum.

III. SHELL MODEL

A. Model

The equations of MHD turbulence for an incompressible fluid embedded in an external uniform magnetic field \mathbf{B}_0 and subject to rotation Ω write

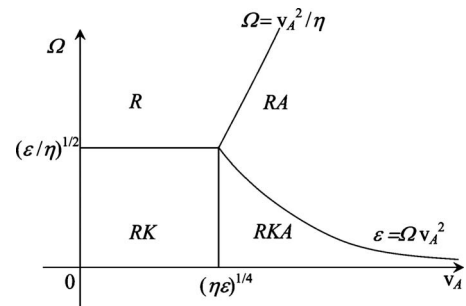


FIG. 2. The four possible turbulent inertial regimes given in the map (V_A, Ω) .

$$\begin{aligned} \partial \mathbf{u} / \partial t + (\mathbf{u} \cdot \nabla) \mathbf{u} - [(\mathbf{B} + \mathbf{v}_A) \cdot \nabla] \mathbf{B} + 2\boldsymbol{\Omega} \times \mathbf{u} \\ = \nu \nabla^2 \mathbf{u} + \mathbf{F} - \nabla P_t, \end{aligned} \quad (7)$$

$$\partial \mathbf{B} / \partial t + (\mathbf{u} \cdot \nabla) \mathbf{B} - [(\mathbf{B} + \mathbf{v}_A) \cdot \nabla] \mathbf{u} = \eta \nabla^2 \mathbf{B}, \quad (8)$$

$$\nabla \cdot \mathbf{u} = \nabla \cdot \mathbf{B} = 0, \quad (9)$$

in which $\mathbf{v}_A = \mathbf{B}_0 / \sqrt{\mu \rho}$ is the Alfvén velocity (where μ and ρ are the fluid magnetic permeability and density, respectively) and \mathbf{B} is given in unit of $V_A = |\mathbf{v}_A|$. The total pressure $P_t = P + b^2/2$ is a functional of \mathbf{u} and \mathbf{B} owing to incompressibility condition (9). The forcing \mathbf{F} insures the fluid motion.

From Eqs. (7)–(9) we derive the following shell model:

$$\begin{aligned} \dot{U}_n = ik_n [Q_n(U, U) - Q_n(B, B)] + ik_n V_A(t) B_n + i\Omega(t) U_n \\ - \nu k_n^2 U_n + F_n(t), \end{aligned} \quad (10)$$

$$\dot{B}_n = ik_n [Q_n(U, B) - Q_n(B, U)] + ik_n V_A(t) U_n - \eta k_n^2 B_n, \quad (11)$$

where

$$\begin{aligned} Q_n(X, Y) = \lambda^2 (X_{n+1} Y_{n+1} + X_{n+1}^* Y_{n+1}^*) - X_{n-1}^r Y_n - X_n Y_{n-1}^r \\ + i\lambda (2X_n^* Y_{n-1}^i + X_{n+1}^r Y_{n+1}^i - X_{n+1}^i Y_{n+1}^r) + X_{n-1} Y_{n-1} \\ + X_{n-1}^* Y_{n-1}^* - \lambda^2 (X_{n+1}^r Y_n + X_n Y_{n+1}^r) + i\lambda (2X_n^* Y_{n+1}^i \\ + X_{n-1}^r Y_{n-1}^i - X_{n-1}^i Y_{n-1}^r), \end{aligned} \quad (12)$$

represents the nonlinear transfer rates and F_n represents the turbulence forcing. This model is based on wavelet decomposition [16]. Compared to other shell models [17–19] it has the advantage that helicities are much better defined like those based on helical wave decomposition [20–22]. It has been introduced in its hydrodynamic form to study spectral properties of helical turbulence [23] and in its MHD form to study cross-helicity effect on cascades [24]. The parameter λ is the geometrical factor from which the wave number is defined $k_n = k_0 \lambda^n$. As explained in [13] an optimum shell spacing is the golden number $\lambda = (1 + \sqrt{5})/2$. The terms involving Ω and V_A were already introduced in several previous papers dealing with either rotation [25,26] or applied magnetic field [27,28].

B. Conservative quantities

Expressions for the kinetic energy and helicity, E_U and H_U , magnetic energy and helicity, E_B and H_B , and cross-helicity H_C , are given by

$$E_U = \sum_n E_U(n), \quad E_U(n) = \frac{1}{2} |U_n|^2, \quad (13)$$

$$H_U = \sum_n H_U(n), \quad H_U(n) = \frac{i}{2} k_n [(U_n^*)^2 - U_n^2], \quad (14)$$

$$E_B = \sum_n E_B(n), \quad E_B(n) = \frac{1}{2} |B_n|^2, \quad (15)$$

TABLE I. In 3D MHD turbulence, conservation properties of total energy E , cross helicity H_C , and magnetic helicity H_M depending on global rotation Ω and applied field V_A .

Ω	$=0$	$\neq 0$	$=0$	$\neq 0$
V_A	$=0$	$=0$	$\neq 0$	$\neq 0$
E	Y	Y	Y	Y
H_C	Y	N	Y	N
H_M	Y	Y	N	N

$$H_B = \sum_n H_B(n), \quad H_B(n) = \frac{i}{2} k_n^{-1} ((B_n^*)^2 - B_n^2), \quad (16)$$

$$H_C = \sum_n H_C(n), \quad H_C(n) = \frac{1}{2} (U_n B_n^* + B_n U_n^*). \quad (17)$$

In the inviscid and nonresistive limit ($\nu = \eta = 0$), the total energy $E = E_U + E_B$, magnetic helicity, and cross helicity must be conserved ($\dot{E} = \dot{H}_B = \dot{H}_C = 0$). Here, with the additional Coriolis and Alfvénic terms the properties of conservation are not necessarily satisfied. A summary of these properties is given in Table I for three-dimensional (3D) MHD turbulence. In the case of pure hydrodynamic turbulence (without magnetic field) the kinetic energy and helicity must be conserved ($\dot{E}_U = \dot{H}_U = 0$) even with the Coriolis forces.

C. Time scales

In Eqs. (10) and (11) the forcing $F_{n_F}(t)$ (applied at some scale $k_{n_F}^{-1}$), the global rotation $\Omega(t)$, and the applied field $V_A(t)$ have constant intensities $|F_{n_F}|$, Ω , and V_A . Only their sign may change after a period of time t_F , t_Ω , and t_{V_A} , the probability of changing from one period to the next being random. Such a trick allows us to control the two characteristic times $\tau_\Omega \approx t_\Omega$ and $\tau_{V_A} \approx t_{V_A}$. In the simulations we take $t_\Omega = 1/\Omega$ and $t_{V_A} = 1/(k_{n_F} V_A)$. It is in the same spirit as the one used in [25,28] though much simpler. Incidentally, the random change of sign of $\Omega(t)$ ensures that there is no injection of kinetic helicity on average. Taking a random sign in $F_{n_F}(t)$ we ensure that the forcing intensity satisfies $|F_{n_F}| \approx \sqrt{2\varepsilon/t_F}$. It is also important that t_F is the shortest among all other characteristic times of the problem τ_K , τ_Ω , and τ_{V_A} (and of course τ_η). We choose $t_F \leq \frac{1}{10} \min\{\tau_K, \tau_\Omega, \tau_{V_A}\}$.

D. No injection of cross helicity

In addition, it is important to control the injection of cross helicity as was shown in [24]. Indeed, any spurious injection of cross helicity may lead to a supercorrelation state where $U_n \approx B_n$ implying equality not only in intensity (as in equipartition) but also in phase. In that case the flux of kinetic energy is depleted, implying an accumulation of energy at large scale and steeper spectral slopes. In order to compare the results to the phenomenological approach we impose the

injection of cross helicity to be zero. For that we could use the forcing

$$\frac{F_{n_F}}{|F_{n_F}|} = \pm i \frac{B_{n_F}}{|B_{n_F}|}, \quad (18)$$

where again the sign is randomly changed after each period of time t_F . This forcing is however ill-defined as soon as $|B_{n_F}| \ll |U_{n_F}| \approx 1$. To fix this problem we use the following forcing:

$$\frac{F_{n_F}}{|F_{n_F}|} = \frac{ae^{i\varphi} \pm i\zeta \frac{B_{n_F}}{|B_{n_F}|}}{a + \zeta}, \quad (19)$$

with $\zeta = |B_{n_F}|/|U_{n_F}|$, in which φ is a phase randomly changed after each period of time t_F and a is an additional parameter. In the case $\zeta \gg a$, Eq. (18) is recovered, and the phase of F_{n_F} is mainly determined by the phase of B_{n_F} so that it corresponds to zero injection of cross helicity. In the case $\zeta \ll a$ the phase of F_{n_F} is controlled by the random phase φ . Since B_{n_F} is small there is no cross-helicity injection too. The value $a = 10^{-6}$ provides a robust forcing with always a low level of cross helicity.

E. Dissipations

We define the dissipation of U and B at scale k_n by $D_U(k_n) = \nu k_n^2 |U_n|^2$ and $D_B(k_n) = \eta k_n^2 |B_n|^2$. From the phenomenological formalism above we expect the total dissipation to be equal to the injection rate of energy at the forcing scale $\varepsilon_\nu + \varepsilon_\eta = \varepsilon$, with $\varepsilon_\nu = \sum_n D_U(k_n)$ and $\varepsilon_\eta = \sum_n D_B(k_n)$. Equivalently in pure HD we would have $\varepsilon_\nu = \varepsilon$. On the other hand, the ratio of both dissipations $\rho = \varepsilon_\eta / \varepsilon_\nu$ cannot be predicted. It can only be calculated numerically.

IV. RESULTS

A. Spectra for $\text{Pm}=1$

In Fig. 3 the spectra are plotted for $\nu = 10^{-7}$ and $\text{Pm}=1$ in the three cases $V_A=0$, $\Omega=0$, and $V_A\Omega \neq 0$. For $V_A=0$, the horizontal and $k^{1/3}$ dashed lines disclose a RK regime. For $\Omega=0$, the dashed line $k^{1/6}$ disclose a KA regime. For $V_A\Omega \neq 0$, the $k^{-1/2}$ and horizontal dashed lines disclose a RA regime. In each case the transition between two power laws is rather smooth and occurs over a scales range of about two orders of magnitude.

For $\varepsilon \approx 1$ and taking the numerical values for Ω , V_A , and η given in Fig. 2 we find that the three sets of spectra found with the shell model belong indeed to the three parts RK , $(R)KA$, and RA of Fig. 2. We tried to track the transition from one part to the other, varying Ω and V_A . It is however not possible to handle it numerically as the spectral slopes are not so well defined at the neighborhood of the frontiers delimiting the four parts of Fig. 2.

B. Spectra for $\text{Pm} < 1$

In Fig. 4 the kinetic and magnetic spectra are plotted for $\nu = 10^{-7}$ and several values of Pm for the three previous cases.

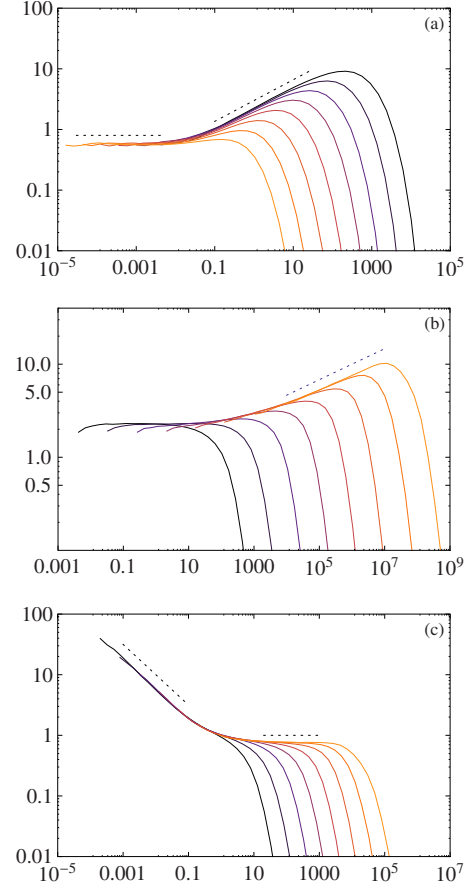


FIG. 3. (Color online) Normalized spectra for $\nu=10^{-7}$ and $\text{Pm}=1$. Curves (a) are shown for $V_A=0$ and $\Omega=12.5, 25, 50, 10, 200, 400, 800$, and 1600 (from right to left, from darker to lighter). Curves (b) are shown for $\Omega=0$ and $V_A=0.16, 0.32, 0.64, 1.28, 2.56, 5.12, 10.24$, and 20.48 (from left to right, from darker to lighter). Curves (c) are shown for $(V_A, \Omega)=(0.16, 800); (0.32, 400); (0.64, 200); (1.28, 100); (2.56, 50); (5.12, 25); (10.24, 12.5);$ and $(20.48, 6.25)$ (from left to right, from darker to lighter).

For $V_A=0$ [(a) and (b)] increasing Pm decreases the magnetic dissipation scale while the viscous scale is not significantly changed. This is in agreement with a simple Kolmogorov phenomenology [14], the ratio of dissipation scales being given by $k_\nu/k_\eta \propto \text{Pm}^{-3/4}$. For $\text{Pm} \geq 10^{-2}$ the effect of rotation is visible in the spectra flatness. At smaller values of Pm it is however difficult to determine any slope at all.

For $\Omega=0$ and $V_A=1.28$ [(c) and (d)] both kinetic and magnetic spectra are almost the same whatever the value of Pm . The effect of an applied magnetic field is to correlate both fields as expected in the Alfvén waves. In particular, the dissipation scale is governed by the magnetic diffusivity, with $k_\nu \approx k_\eta$. The same conclusions are found for $(V_A, \Omega)=(0.32, 400)$ (e) and $(V_A, \Omega)=(20.48, 6.25)$ (f). In these two cases the horizontal slopes are due to rotation (e) and applied magnetic field (f).

We note that for $\Omega=0$ and $V_A=1.28$ (d) the normalized curves are not horizontal. They correspond to spectral energy density slopes between $k^{-5/3}$ and $k^{-3/2}$. The latter is obtained for values of V_A about ten times larger.

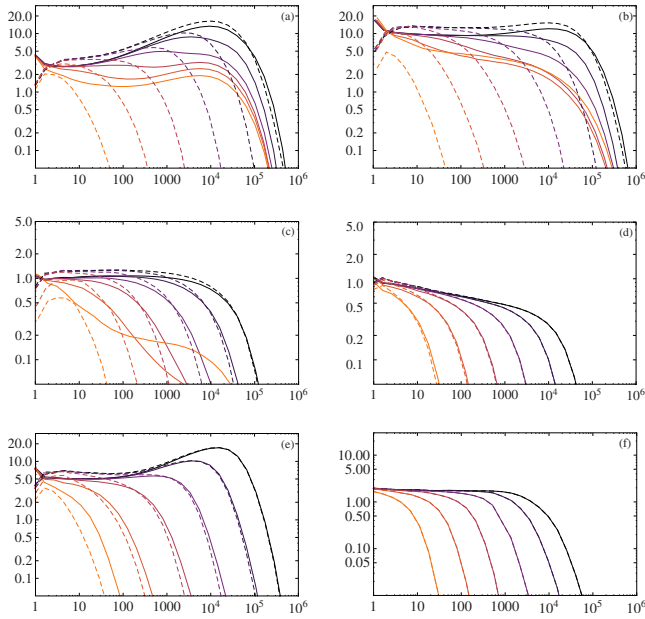


FIG. 4. (Color online) Normalized kinetic (full) and magnetic (dashed) spectra for $\nu=10^{-7}$: (a) $(V_A, \Omega)=(0, 100)$, (b) $(V_A, \Omega)=(0, 1600)$, (c) $(V_A, \Omega)=(0.08, 0)$, (d) $(V_A, \Omega)=(1.28, 0)$, (e) $(V_A, \Omega)=(0.32, 400)$, and (f) $(V_A, \Omega)=(20.48, 6.25)$. For each set of curves for $Pm=10^{-5}, 10^{-4}, 10^{-3}, 10^{-2}, 10^{-1}$, and 1 (from lighter to darker). Note that the kinetic and magnetic spectra are superposed in the case (f).

C. Dissipation ratio

In Fig. 5 the ratio $\rho = \varepsilon_\eta / \varepsilon_\nu$ is plotted versus Pm for $V_A = \Omega = 0$ (a), $V_A = 0$ (b), $\Omega = 0$ (c), and $V_A \Omega \neq 0$ (d). In the limit $Pm \rightarrow 0$ the dynamo action does not occur, implying $\rho \rightarrow 0$. For $Pm = 1$ both kinetic and magnetic spectra are identical, implying $\varepsilon_\nu = \varepsilon_\eta = \varepsilon / 2$, and then $\rho = 1$. We always find an intermediate value of Pm for which ρ reaches a maximum. This is related to a superequipartition state in which the magnetic energy is higher than the kinetic energy at large scales. Varying V_A and Ω we find that this maximum value can increase by several orders of magnitude and that it does not occur at the same Pm . For the two last cases an asymptotic curve $\rho = O(Pm^{-1})$ is obtained for large values of V_A . This is a direct consequence of the equipartition regime $|U_n| \approx |B_n|$ obtained at any scale (see Fig. 4). In that cases the definition of ρ directly implies the scaling $O(Pm^{-1})$.

V. DISCUSSION

For $Pm = 1$ both approaches, phenomenological and shell model, give consistent results in terms of inertia regimes.

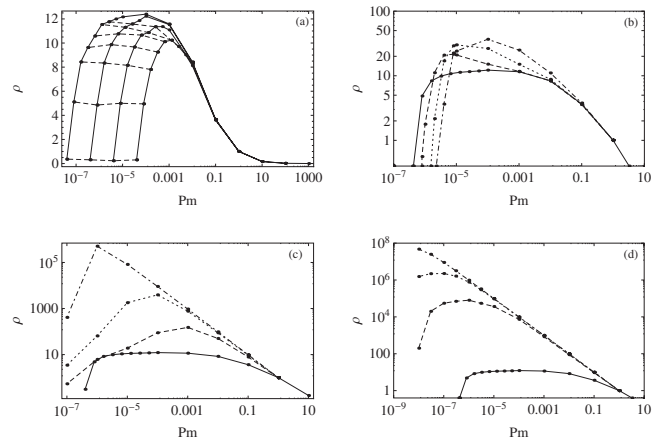


FIG. 5. Dissipation ratio versus Pm . On panel (a) $V_A = \Omega = 0$ and the full curves from right to left correspond to $\nu = 10^{-5}, 10^{-6}, 10^{-7}$, and 10^{-8} . The dashed curves from bottom to top correspond to $\eta = 1/4, 1/8, 1/16, 1/32, 1/64, 1/128$, and $1/256$. On panel (b) $V_A = 0$, $\nu = 10^{-7}$, and the curves correspond to $\Omega = 0$ (full curve), 100 (dashed), 400 (dotted), and 1600 (dotted-dashed). On panel (c) $\Omega = 0$, $\nu = 10^{-7}$, and the curves correspond to $V_A = 0$ (full curve), 0.08 (dashed), 0.32 (dotted), and 1.28 (dotted-dashed). On panel (d) $\nu = 10^{-7}$ and the curves from bottom to top correspond to $(V_A, \Omega) = (0, 0), (0.32, 400), (2.56, 50)$, and $(20.48, 6.25)$.

They are controlled by the shortest time scale corresponding either to rotation, applied magnetic field, inertia, or a combination of them. For $Pm < 1$ the magnetic dissipation occurs at a scale larger than the viscous scale implying that the different regimes are not so easy to discriminate. However, for a sufficiently strong applied magnetic field, both kinetic and magnetic energy spectra are merged, implying a strong increase of the viscous dissipation scale. Whether this is due to our isotropic assumption is not clear and cannot be answered with our models. A consequence is that, for a strong applied field, the ratio of magnetic to kinetic dissipation scales like $O(Pm^{-1})$ and can reach very high values for $Pm \ll 1$. Without the applied field, this ratio is also maximum for some value of $Pm \ll 1$, depending on the fluid viscosity and global rotation.

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