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Theory and observation of electromagnetic ion cyclotron triggered emissions in the magnetosphere

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[1] We develop a nonlinear wave growth theory of electromagnetic ion cyclotron (EMIC) triggered emissions observed in the inner magnetosphere. We first derive the basic wave equations from Maxwell's equations and the momentum equations for the electrons and ions. We then obtain equations that describe the nonlinear dynamics of resonant protons interacting with an EMIC wave. The frequency sweep rate of the wave plays an important role in forming the resonant current that controls the wave growth. Assuming an optimum condition for the maximum growth rate as an absolute instability at the magnetic equator and a self-sustaining growth condition for the wave propagating from the magnetic equator, we obtain a set of ordinary differential equations that describe the nonlinear evolution of a rising tone emission generated at the magnetic equator. Using the physical parameters inferred from the wave, particle, and magnetic field data measured by the Cluster spacecraft, we determine the dispersion relation for the EMIC waves. Integrating the differential equations numerically, we obtain a solution for the time variation of the amplitude and frequency of a rising tone emission at the equator. Assuming saturation of the wave amplitude, as is found in the observations, we find good agreement between the numerical solutions and the wave spectrum of the EMIC triggered emissions.

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1. Introduction

[2] Waves in Earth's space environment known as Pc1-2 pulsations (with frequencies from 0.1 to 5 Hz) have long been observed both on the ground [*Troitskaya*, 1961; *Tepley*, 1961] and in space (e.g., by satellites such as GEOS-2 [*Roux et al.*, 1982], AMPTE CCE [*Anderson et al.*, 1992a, 1992b], Viking [*Erlandson et al.*, 1990, 1996; *Mursula et al.*, 1997], Freja [*Mursula et al.*, 1994], Polar

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[Mursula et al., 2001; Arnoldy et al., 2005], and Cluster [Engebretson et al., 2007]). These waves are now known as electromagnetic ion cyclotron (EMIC) waves, and are understood to originate as a result of instabilities in the ion distributions that populate Earth's magnetosphere. Pitchangle scattering by EMIC waves in the outer radiation belt can induce significant loss of relativistic electrons under certain conditions [e.g., Lorentzen et al., 2000; Summers and Thorne, 2003; Summers et al., 2007].

[3] The most common class of Pc1 waves observed at mid- and low latitudes on the ground, so-called "pearl pulsations," is characterized by a sequence of highly structured wave packets with a repetition period on the order of minutes. Many early ground-based studies of Pc1-2 waves noted their highly structured, dispersive appearance in Fourier spectrograms, and attributed the observed temporal repetition to the existence of bouncing wave packets that, although generated near the magnetic equator and guided along the magnetic field, would reflect from the ionosphere and return equatorward to be re-amplified (e.g., as summarized by *Kangas et al.* [1998]).

[4] However, several satellite studies have called that picture into question (e.g., as reviewed by *Fraser et al.* [2006] and *Mursula* [2007]). The repetitive nature of the waves observed in space can in many cases be attributed to modulation by simultaneously observed longer period

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waves, and observations of the dispersive structure in space are quite rare. In addition, all observational studies of the propagation of these waves in space have shown unidirectional propagation of wave energy toward the ionosphere, and never away from it. Loto 'aniu et al. [2005], who provided the most comprehensive recent observational study of this issue, used both magnetic and electric field data from the CRRES satellite in the L range from 3.5 to 8.0 to determine Poynting vector directions for all Pc1-2 wave events observed during that spacecraft's ~15-month lifetime. They found unidirectional energy propagation away from the equator for all events located above 11° MLAT, but bidirectional propagation, both away and toward the equator, for events observed below 11° MLAT. Observations of propagation by Erlandson et al. [1990, 1996] using Viking satellite data at $\sim 3R_E$ altitude far from the magnetic equator also showed purely downward propagation (toward the ionosphere), as did those by Mursula et al. [2001] and Arnoldy et al. [2005] using Polar satellite data near 25° and -22° MLAT, respectively, and by Engebretson et al. [2007] using data from Cluster above 12° MLAT.

[5] These studies suggest that the few instances of dispersive, intermittent Pc1 waves observed in space cannot be attributed to the same mechanism that generates the dispersive, repetitive pearl structures observed so commonly on the ground. A recent study of Cluster data by *Pickett et al.* [2010] reports the observation of coherent rising tone emissions that emerge from nearly constant frequency EMIC waves. We believe the rising tones shown in Figure 8 of *Mursula* [2007] may be examples of this same phenomenon, which can be denoted as EMIC triggered emission, and for which we provide a quantitative physical model.

[6] Figure 1 displays about 1 min 20 s of Cluster 4 data on the 30th of March 2002. Figures 1a and 1b display the magnetic and electric field fluctuation spectrograms measured respectively by the STAFF-SC [Cornilleau-Wehrlin et al., 2003] and the EFW [Gustafsson et al., 2001] instruments. Figures 1c and 1d show wave parameters estimated for the most energetic part of the magnetic fluctuation spectrogram with the Prassadco software [Santolik et al., 2003a]. From Figures 1a and 1b one can notice an almost constant electromagnetic activity at about 1.5 Hz, the Pc1 waves, and an electromagnetic rising tone emission starting from the Pc1 waves up to 3 Hz. In Figures 1c and 1d, the magnetic fluctuations are analyzed in the polarization plane given by the singular value decomposition (SVD) method. Figure 1c shows that the sense of polarization (defined in equation (4) of Santolik et al. [2001]) is clearly negative for the rising tone, indicating the left-handed polarization. The sense of polarization of the Pc1 waves is not well defined (both positive and negative values). It can be either indicative of a linear polarization or of no polarization. A low coherency value [Santolik and Gurnett, 2002; Santolik et al., 2002] in Figure 1d indicates that there are random phase shifts between the two components in the polarization plane. The high coherency level of the rising tone is a confirmation of its high degree of polarization. The left handed electromagnetic rising tone emission has a different origin. Pickett et al. [2010] demonstrate that the rising tone emission arrives from the magnetic equator.

[7] The spectra show the bursty nature of the emissions rising to higher frequencies. This bursty nature cannot be

explained by the linear theory. The linear growth rate due to the temperature anisotropy of energetic protons maximizes near the helium cyclotron frequency of the lower helium band and the cut-off frequency of the upper proton band. Further, the linear growth rate decreases as the frequency approaches the proton gyrofrequency [Gendrin et al., 1984]. The bursty nature of the EMIC emissions requires much higher growth rates than the linear growth rates in the higher frequency range. A similar bursty wave growth is often observed in the inner magnetosphere as whistler-mode chorus emissions in a much higher frequency range [Santolik et al., 2003b]. Trakhtengerts and Demekhov [2007] applied the backward wave oscillator (BWO) model to Pc1 pulsations. The BWO model has also been applied to whistler-mode chorus emissions. In this model, a step-like velocity distribution is assumed, which causes an absolute cyclotron instability around the magnetic equator.

[8] As the generation mechanism of whistler-mode chorus emissions, *Omura et al.* [2008, 2009] have shown that there occurs a nonlinear absolute instability of coherent whistlermode waves due to the formation of an electromagnetic electron hole [*Omura and Summers*, 2006] in the velocity phase space. Since L-mode EMIC triggered emissions have certain characteristics quite similar to whistler-mode chorus emissions, we study the generation mechanism of them based on the nonlinear wave growth theory that assumes the formation of an electromagnetic proton hole.

[9] We first derive a set of wave equations for EMIC waves in section 2. We then study the nonlinear dynamics of protons interacting with an EMIC wave in section 3. We obtain the nonlinear growth rate of EMIC waves in section 4. Taking into account the inhomogeneous magnetic field around the equator, we determine a threshold for self-sustaining emissions of EMIC waves and obtain a set of non-linear equations that describe an EMIC rising tone emission in section 5. In section 6 we compare the numerical solutions of the nonlinear equations with the observations by the Cluster spacecraft. In section 7 we present the summary and discussion.

2. EMIC Wave Equations

[10] We assume a coherent EMIC wave propagating parallel to a dipole magnetic field \mathbf{B}_0 of the inner magnetosphere. We measure a distance *h* along the magnetic field line from the magnetic equator, and denote it as the *h*-axis with the direction of the static magnetic field. The wave fields are in the transverse plane containing the *x*- and *y*-axes, where the coordinates (x, y, h) form a right-handed system. We express the electric and magnetic field vectors of the wave with amplitudes E_w and B_w and phases ψ_E and ψ_B in the transverse plane by the complex numbers $\vec{E}_w = E_w \exp(i\psi_E)$ and $\vec{B}_w = B_w \exp(i\psi_B)$ in the complex plane, respectively. For an L-mode wave propagating in the positive *h* direction, the frequency ω and wavenumber *k* are defined by the following equations:

$$\omega = -\frac{\partial \Psi_B}{\partial t},\tag{1}$$

$$k = \frac{\partial \Psi_B}{\partial h}.$$
 (2)



Figure 1. Dynamic power spectra of (a) magnetic, (b) electric field in a frequency range of 0.5–4.0 Hz, observed by Cluster 4 during the time 07:56:44.795–07:57:56.475 on 30 March 2002. (c) Polarization and (d) coherency analyses. The spectra are from the STAFF-SC and EFW instruments and the magnetic field measurements from the FGM instrument.

The electromagnetic field of the wave should satisfy Maxwell's equations expressed as

$$i\frac{\partial \vec{E}_w}{\partial h} = -\frac{\partial \vec{B}_w}{\partial t},\tag{3}$$

$$i\frac{\partial \vec{B}_w}{\partial h} = \mu_0 \vec{J},\tag{4}$$

where \vec{J} is the conduction current due to motion of charged particles, and we have neglected the displacement current because we assume the phase velocity, $V_p = \omega/k$, is much smaller than the speed of light *c*. We neglect the inertia term of the electron momentum equation, which is expressed as

$$\vec{E}_w - i\vec{V}_e B_0 = 0, \tag{5}$$

where \vec{V}_e is the velocity of the cold electron motion supporting the EMIC wave propagation, and B_0 is the absolute value of the static magnetic field. The electron motion contributes to the transverse wave field as the transverse electron current density $\vec{J}_e = -en_e \vec{V}_e$, where *e* and n_e are the absolute value of electron charge and the electron density, respectively. From (5), we have

$$\vec{J}_e = -i \frac{\epsilon_0 \omega_{pe}^2}{\Omega_e} \vec{E}_w, \tag{6}$$

where ϵ_0 , ω_{pe} , and Ω_e are the electric permittivity of vacuum, the electron plasma frequency, and the electron cyclotron frequency, respectively.

[11] The momentum equation of ions of species "s" is written as

$$\frac{\partial \vec{V}_s}{\partial t} = \frac{q_s}{m_s} \left(\vec{E}_w - i \vec{V}_s B_0 \right),\tag{7}$$

where \vec{V}_s , q_s , and m_s are the velocity of the motion, charge, and mass of ion species "s". The motion of each ion species contributes to the transverse wave field by a current density of species "s" given by $\vec{J}_s = q_s n_s \vec{V}_s$, where n_s is the charge density of species "s". From (7), we obtain

$$\frac{\partial J_s}{\partial t} \exp\left(i\psi_{Js}\right) + i(\Omega_s - \omega)\vec{J}_s = \epsilon_0 \omega_{ps}^2 \vec{E}_w,\tag{8}$$

where ω_{ps} is the plasma frequency of species "s". We assume the amplitudes of electromagnetic fields and current densities of particle species vary slowly compared with the wave phase variation represented by ω and k. Namely, assuming $(\partial J_s/\partial t) \ll (\Omega_s - \omega) J_s$, we have

$$J_s \exp\left(i\psi_{Js}\right) \sim -i\frac{\epsilon_0\omega_{ps}^2}{\Omega_s - \omega} E_w \exp\left(i\psi_E\right),\tag{9}$$

which results in approximate relations

$$J_s \sim \frac{\epsilon_0 \omega_{ps}^2}{\Omega_s - \omega} E_w \tag{10}$$

and

$$\exp\left(i\psi_{Js}\right) \sim -i\exp\left(i\psi_{E}\right). \tag{11}$$

Substituting (10) and (11) into the first term of (8), which is much smaller than the other terms, we obtain

$$-i\frac{\epsilon_0\omega_{ps}^2}{\Omega_s-\omega}\frac{\partial E_w}{\partial t}\exp\left(i\psi_E\right)+i(\Omega_s-\omega)\vec{J}_s=\epsilon_0\omega_{ps}^2\vec{E}_w.$$
 (12)

After dividing (12) by $(\Omega_s - \omega)$, we take a sum for all ion species to obtain

$$-i\sum_{s}\frac{\epsilon_{0}\omega_{ps}^{2}}{(\Omega_{s}-\omega)^{2}}\frac{\partial E_{w}}{\partial t}\exp\left(i\psi_{E}\right)+i\sum_{s}\vec{J}_{s}=\sum_{s}\frac{\epsilon_{0}\omega_{ps}^{2}}{\Omega_{s}-\omega}\vec{E}_{w}.$$
 (13)

[12] We decompose the current density \vec{J} in (4) into three components, \vec{J}_e for electrons, $\sum_s \vec{J}_s$ for non-resonant ions, and \vec{J}_R for resonant ions, namely,

$$\vec{J}_e + \sum_s \vec{J}_s + \vec{J}_R = \frac{i}{\mu_0} \frac{\partial \vec{B}_w}{\partial h}.$$
 (14)

From (6), (13), and (14), we obtain

$$-i\sum_{s} \frac{\epsilon_0 \omega_{ps}^2}{(\Omega_s - \omega)^2} \frac{\partial E_w}{\partial t} \exp\left(i\psi_E\right) - \frac{1}{\mu_0} \frac{\partial \vec{B}_w}{\partial h} - i\vec{J}_R = \epsilon_0 \Pi_c \vec{E}_w, \quad (15)$$

where we have introduced an angular frequency Π_c defined by

$$\Pi_c = \sum_s \frac{\omega_{ps}^2}{\Omega_s - \omega} - \frac{\omega_{pe}^2}{\Omega_e}.$$
(16)

We decompose the resonant current \vec{J}_R into \vec{J}_E and \vec{J}_B parallel to the wave electric field \vec{E}_w and the wave magnetic field \vec{B}_w , respectively. Noting that $\exp(i\psi_B) = i \exp(i\psi_E)$, we have

$$\vec{J}_R = (J_E + iJ_B) \exp\left(i\psi_E\right). \tag{17}$$

We differentiate both sides of (15) neglecting the derivatives of the amplitudes and phases that are higher than the first order. Using (3) and (17), we obtain

$$-\sum_{s} \frac{\epsilon_{0}\omega\omega_{ps}^{2}}{(\Omega_{s}-\omega)^{2}} \frac{\partial E_{w}}{\partial t} \exp\left(i\psi_{E}\right) + \frac{i}{\mu_{0}} \left[2ik\frac{\partial E_{w}}{\partial h}\exp\left(i\psi_{E}\right) - k^{2}\vec{E}_{w}\right]$$
$$= \epsilon_{0}\Pi_{c} \left[\frac{\partial E_{w}}{\partial t}\exp\left(i\psi_{E}\right) - i\omega\vec{E}_{w}\right] + \omega(J_{E} + iJ_{B})\exp\left(i\psi_{E}\right). \tag{18}$$

Multiplying (18) by $exp(-i\psi_E)$, and separating the real and imaginary parts, we obtain

$$\epsilon_0 \left[\Pi_c + \omega \sum_s \frac{\omega_{ps}^2}{(\Omega_s - \omega)^2} \right] \frac{\partial E_w}{\partial t} + \frac{2k}{\mu_0} \frac{\partial E_w}{\partial h} = -\omega J_E \qquad (19)$$

and

$$\left(-\frac{k^2}{\mu_0} + \omega\epsilon_0 \Pi_c\right) E_w = \omega J_B.$$
⁽²⁰⁾

Noting that (3) gives $E_w = (\omega/k)B_w$, (19) and (20) are rewritten as

$$\frac{\partial B_w}{\partial t} + V_g \frac{\partial B_w}{\partial h} = -\frac{\mu_0 V_g}{2} J_E \tag{21}$$

and

$$c^2k^2 - \omega\Pi_c = -\mu_0 c^2 k \frac{J_B}{B_w},\tag{22}$$

where V_g is the group velocity given by

$$V_g = 2c^2 k \left[\Pi_c + \omega \sum_s \frac{\omega_{ps}^2}{\left(\Omega_s - \omega\right)^2} \right]^{-1}.$$
 (23)

The wave equations (21) and (22) take essentially the same forms as the wave equations for a whistler-mode wave [*Omura and Matsumoto*, 1982; *Omura et al.*, 2009]. A generalized derivation of the wave equations for whistler and Alfven mode cyclotron masers is found by *Trakhtengerts and Rycroft* [2008].

[13] We evaluate the magnitude of the resonant currents J_E and J_B in terms of the growth rate ω_i . Neglecting the convective term in (21), we have

$$\omega_i B_w = -\frac{\mu_0}{2} V_g J_E. \tag{24}$$

Since \vec{J}_E and \vec{J}_B are projections of the resonant current \vec{J}_R , we can assume $|\vec{J}_E| \sim |\vec{J}_B|$. From (24), we obtain

$$\frac{J_B}{B_w} \sim \pm \frac{2\omega_i}{\mu_0 V_g}.$$
(25)

Using (25), we rewrite the nonlinear dispersion relation given by (22) as

$$c^{2}k^{2}\left(1\pm 2\frac{V_{p}}{V_{g}}\frac{\omega_{i}}{\omega}\right) = \omega\Pi_{c}.$$
(26)

Assuming $\omega_i \ll \omega$ and $V_p \sim V_g$, we find that (26) is reduced to the cold plasma dispersion relation

$$c^2 k^2 = \omega \Pi_c, \tag{27}$$

which gives an expression of the phase velocity as a function of ω ,

$$V_p = c \sqrt{\frac{\omega}{\Pi_c}}.$$
 (28)

Differentiating (27) with respect to *t*, and noting that $\partial k/\partial t = -\partial \omega/\partial h$, we obtain

$$\frac{\partial\omega}{\partial t} + V_g \frac{\partial\omega}{\partial h} = 0.$$
(29)

Along with (21), (29) describes a wave packet of an EMIC wave propagating at the group velocity V_g with a constant wave frequency ω and an evolving wave amplitude B_w due to the resonant current J_E . This indicates that the essential physical process of the frequency variation takes place only

at the source of the emissions near the magnetic equator as analyzed in the following sections.

3. Nonlinear Dynamics of Resonant Protons

[14] We study the dynamics of energetic protons interacting with an EMIC wave through cyclotron resonance. We calculate partial derivatives of variables in preparation for the calculation of the second-order cyclotron resonance condition. Differentiating (27) with respect to h, we obtain

$$2c^2k\frac{\partial k}{\partial h} = \frac{\partial\omega}{\partial h}\Pi_c + \omega\frac{\partial\Pi_c}{\partial h}.$$
(30)

We assume that the densities of ions and electrons vary proportionally with the intensity of the ambient magnetic field, i.e., $\omega_{ps}^2 \propto \Omega_s$ and $\omega_{pe}^2 \propto \Omega_e$. From (16), we obtain

$$\frac{\partial \Pi_c}{\partial h} = \sum_{s} \left[\frac{\omega_{ps}^2}{(\Omega_s - \omega)^2} \left(\frac{\partial \omega}{\partial h} - \frac{\omega}{\Omega_s} \frac{\partial \Omega_s}{\partial h} \right) \right].$$
 (31)

Substituting (31) into (30), and using (23) and (29), we obtain

$$\frac{\partial k}{\partial h} = -\frac{1}{V_g^2} \frac{\partial \omega}{\partial t} + \frac{\omega}{\Omega_H} \left(\frac{\Pi_c}{2c^2k} - \frac{1}{V_g}\right) \frac{\partial \Omega_H}{\partial h}.$$
 (32)

From the cyclotron resonance condition the resonance velocity is given by

$$V_R = \frac{\omega - \Omega_H}{k}.$$
 (33)

Using (32), we calculate time variation of V_R seen by a proton moving with a parallel velocity v_{\parallel} as

$$\frac{\mathrm{d}V_R}{\mathrm{d}t} = \frac{1}{k} \left(1 - \frac{v_{\parallel}}{V_g} \right) \left(1 - \frac{V_R}{V_g} \right) \frac{\partial\omega}{\partial t} - \frac{v_{\parallel}}{k} \left[1 + \frac{\omega V_R}{\Omega_H} \left(\frac{\Pi_c}{2c^2k} - \frac{1}{V_g} \right) \right] \frac{\partial\Omega_H}{\partial h}.$$
(34)

[15] We define a relative phase ζ between the phase ϕ of the perpendicular velocity $\vec{V}_{\perp 0}$ of a proton and the phase ψ_B of the wave magnetic field \vec{B}_w . Noting that the proton undergoes cyclotron motion with a cyclotron radius $r_c = V_{\perp 0}/\Omega_H$ and accelerated by the mirror force due to the radial component of the nonuniform magnetic field $B_r = -(r_c/2)\partial B_0/\partial h$, we can write the equation of motion as

$$\frac{\mathrm{d}v_{\parallel}}{\mathrm{d}t} = -\Omega_w V_{\perp 0} \sin\zeta - \frac{V_{\perp 0}^2}{2\Omega_H} \frac{\partial\Omega_H}{\partial h},\tag{35}$$

where $\Omega_w = eB_w/m_H$.

[16] We calculate the first-order phase variation

$$\frac{\mathrm{d}\zeta}{\mathrm{d}t} = \frac{\mathrm{d}\phi}{\mathrm{d}t} - \frac{\mathrm{d}\psi_B}{\mathrm{d}t} = -\Omega_H - \left(kv_{\parallel} - \omega\right). \tag{36}$$

Using the resonance velocity V_R defined by (33), we have

$$\frac{\mathrm{d}\zeta}{\mathrm{d}t} = -k\left(v_{\parallel} - V_R\right). \tag{37}$$



Figure 2. Trajectories of resonant protons in the $(\theta - \zeta)$ phase space for the inhomogeneity ratio S = 0.4. The phase angle ζ_0 is the center of trapping motion, while ζ_1 is the saddle point and ζ_2 is the boundary of the trapping region at $\theta = 0$.

Assuming $v_{\parallel} \sim V_R$, we calculate the second-order phase variation from (37)

$$\frac{\mathrm{d}^2\zeta}{\mathrm{d}t^2} = -k\frac{\mathrm{d}}{\mathrm{d}t}\left(v_{\parallel} - V_R\right). \tag{38}$$

Using (34) and (35), we obtain the second-order nonlinear ordinary differential equation for the phase angle ζ ,

$$\frac{\mathrm{d}^2\zeta}{\mathrm{d}t^2} = \omega_{tr}^2(\sin\zeta + S),\tag{39}$$

where ω_{tr} is the trapping frequency given by $\omega_{tr} = \sqrt{kV_{\perp 0}\Omega_w}$. The parameter S is the inhomogeneity ratio given by

$$S = \frac{1}{s_0 \omega \Omega_w} \left(s_1 \frac{\partial \omega}{\partial t} + V_p s_2 \frac{\partial \Omega_H}{\partial h} \right), \tag{40}$$

where

$$s_0 = \frac{V_{\perp 0}}{V_p},\tag{41}$$

$$s_1 = \left(1 - \frac{V_R}{V_g}\right)^2,\tag{42}$$

$$s_{2} = \left(\frac{V_{\perp 0}^{2}}{2V_{p}^{2}} + \frac{V_{R}^{2}}{V_{p}V_{g}} - \frac{V_{R}^{2}}{2V_{p}^{2}}\right)\frac{\omega}{\Omega_{H}} - \frac{V_{R}}{V_{p}}.$$
 (43)

If we assume that the densities of cold ions and electrons are constant along the magnetic field line in the derivation above, the third term in the brackets of (43) disappears. [17] If |S| < 1, the second-order resonance condition

$$\frac{\mathrm{d}^2\zeta}{\mathrm{d}t^2} = 0 \tag{44}$$

is satisfied by a resonant proton with $v_{\parallel} = V_R$ and $\zeta = -\sin^{-1} S$.

4. Nonlinear Wave Growth

[18] We assume the parabolic variation of the dipole magnetic field near the equator expressed as $\Omega_H = \Omega_{H0}(1 + ah^2)$, where $a = 4.5/(LR_E)^2$, corresponding to the Earth's approximate dipole magnetic field. Noting that $\partial \Omega_H / \partial h = 2a\Omega_{H0}h$, we consider a distance h_c at which the first and second terms of the r.h.s. of (40) become equal. Equating the two terms, we obtain the critical distance h_c as

$$h_c = \frac{1}{2aV_p\Omega_{H0}} \left(\frac{s_1}{s_2}\right) \frac{\partial\omega}{\partial t}.$$
(45)

The distance h_c is used in identifying the dominant terms of the inhomogeneity ratio S in the following sections.

[19] From the analysis of trajectories of resonant ions as described by the second-order equation, it is found that the maximum value of J_E is realized when |S| = 0.4 [*Omura et al.*, 2008]. The magnitude of J_E is calculated by assuming a velocity distribution function in the velocity phase space in the presence of a coherent EMIC wave as

$$g(v_{\parallel},\zeta) = g_0(v_{\parallel}) - Qg_{tr}(v_{\parallel},\zeta)$$
(46)

and we have

$$J_E = eQV_{\perp 0}^2 \int_0^{2\pi} \int_{-\infty}^{\infty} g_{tr}(v_{\parallel},\zeta) \sin \zeta dv_{\parallel} d\zeta, \qquad (47)$$

where we have assumed a delta function for the perpendicular velocity at $v_{\perp} = V_{\perp 0}$. The functions $g_0(v_{\parallel})$ and $g_{tr}(v_{\parallel}, \zeta)$ are the unperturbed velocity distribution function, and the part of g_0 that is trapped by the wave, respectively. Since the separatrix of the trapping wave potential is closed, entrapping of new particles does not take place unless the wave amplitude increases. Therefore, there arises an electromagnetic proton hole in the velocity phase space as shown in Figure 2, where we have introduced the new variable $\theta = k(v_{\parallel} - V_R)$. We assume a factor Q that represents the depth of the proton hole. If Q = 1 the proton hole is completely void. If 50% of trapped ions are lost from the trapping wave potential, Q = 0.5. Assuming that $g_{tr}(v_{\parallel}, \zeta) = 0$ outside it, we rewrite (47) as

$$J_E = J_0 \int_{\zeta_2}^{\zeta_1} [\cos \zeta_1 - \cos \zeta + S(\zeta - \zeta_1)]^{1/2} \sin \zeta d\zeta, \qquad (48)$$

where $J_0 = (2e)^{3/2} (m_H k)^{-1/2} V_{\perp 0}^{5/2} QGB_w^{1/2}$, and *e* and m_H are the charge and rest mass of a proton. The phase angles ζ_1 and ζ_2 are the boundary of the trapping wave potential as defined in Figure 2. The current J_E is a function of *S* and it

maximizes at S = 0.4. The maximum value is $J_E/J_0 = 0.975 \sim 1$. We thus have

$$J_{E,\max} = (2e)^{3/2} (m_H k)^{-1/2} V_{\perp 0}^{5/2} B_w^{1/2} QG.$$
(49)

[20] Writing the right-hand side of (21) as dB_w/dt we obtain

$$\frac{\mathrm{d}B_w}{\mathrm{d}t} = \frac{\mu_0 V_g}{2} \left(2e\right)^{3/2} \left(\frac{V_p}{m_H \omega}\right)^{1/2} V_{\perp 0}^{5/2} B_w^{1/2} QG, \tag{50}$$

where we have eliminated the wave number k using (28). We assume that the velocity distribution function of hot energetic protons is given in terms of the velocities parallel and perpendicular to the ambient magnetic field as

$$f(v_{\parallel}, v_{\perp}) = \frac{n_h}{(2\pi)^{3/2} V_{t\parallel} V_{\perp 0}} \exp\left(-\frac{v_{\parallel}^2}{2V_{t\parallel}^2}\right) \Delta(v_{\perp} - V_{\perp 0}), \quad (51)$$

where $\Delta(v_{\perp})$ is the Dirac delta function. The distribution function $f(v_{\parallel}, v_{\perp})$ is normalized to the density of hot protons n_h . Integrating over v_{\perp} , we obtain the magnitude *G* of the unperturbed distribution function $g(v_{\parallel}, \zeta)$ averaged over v_{\perp} at the resonance velocity V_R ,

$$G = \frac{n_h}{(2\pi)^{3/2} V_{l\parallel} V_{\perp 0}} \exp\left(-\frac{V_R^2}{2V_{l\parallel}^2}\right).$$
 (52)

Combining (50) and (52), we obtain

$$\frac{\mathrm{d}B_w}{\mathrm{d}t} = \Gamma_{NL}B_w,\tag{53}$$

where

$$\Gamma_{NL} = \omega_{ph}^2 \frac{Q}{2} \left(\frac{V_p}{c\Omega_w \omega} \right)^{1/2} \frac{V_g}{V_{t\parallel}} \left(\frac{V_{\perp 0}}{c\pi} \right)^{3/2} \exp\left(-\frac{V_R^2}{2V_{t\parallel}^2} \right)$$
(54)

and where we have normalized the wave magnetic field in terms of the proton cyclotron frequency by defining $\Omega_w = eB_w/m_H$, and ω_{ph} is the plasma frequency of hot protons defined by $\omega_{ph}^2 = n_h e^2/(m_H \epsilon_0)$. It is noted that Γ_{NL} is the nonlinear growth rate [*Omura et al.*, 2009] defined in analogy with the linear growth rate.

5. Self-Sustaining Rising Tone Emission

[21] We derive a necessary condition for an EMIC triggered rising tone emission to be amplified through propagation from the equator to the higher latitude region. Separating the derivative of (53) into temporal and spatial derivatives, we obtain

$$\frac{\partial B_w}{\partial t} + V_g \frac{\partial B_w}{\partial h} = \Gamma_{NL} B_w.$$
(55)

For the triggered emission to grow at the equator, the temporal growth rate should be positive, i.e., $\partial B_w/\partial t > 0$. From (55) we obtain

$$\frac{\partial \Omega_w}{\partial h} < \frac{\Gamma_{NL}}{V_g} \Omega_w, \tag{56}$$

where we assume that EMIC waves propagate in the positive direction, i.e., $V_g > 0$.

[22] We have found that whistler-mode chorus elements with rising tones are generated at the equator [*Katoh and Omura*, 2007; *Omura et al.*, 2008]. The linear growth rate of the L-mode EMIC wave instability also maximizes at the equator because the absolute value of the resonance velocity takes the lowest value, and thus the flux of the resonant protons maximizes at the equator. Therefore, the wave amplitude grows fastest, reaching the threshold value for the nonlinear wave growth at the equator.

[23] At the equator the inhomogeneity of the magnetic field is zero, and the second term on the r.h.s. of (40) vanishes. Since the maximum nonlinear wave growth takes place with S = 0.4, we have the relation between the frequency sweep rate and the wave amplitude at the equator Ω_{w0} from (40)

$$\frac{\partial\omega}{\partial t} = \frac{0.4s_0\omega}{s_1}\Omega_{w0}.$$
(57)

As indicated by (29), the frequency does not change in the frame of reference moving with the group velocity V_{g} .

[24] As the triggered emission propagates significantly away from the equator to the distance $h (\gg h_c)$, the second term of the inhomogeneity ratio (40) becomes much greater than the first term. For the triggered emission to keep the maximum growth at this distance, the negative resonant current J_E must be formed with S = 0.4. Neglecting the first term on the r.h.s. of (40) and setting S = 0.4, we obtain

$$\Omega_w = \frac{V_p s_2}{0.4 s_0 \omega} \frac{\partial \Omega_H}{\partial h}.$$
(58)

Taking the spatial derivative, we obtain

$$\frac{\partial\Omega_w}{\partial h} = \frac{V_p s_2}{0.4 s_0 \omega} \frac{\partial^2 \Omega_H}{\partial h^2} = \frac{5V_p a s_2 \Omega_{H0}}{s_0 \omega}.$$
(59)

Since the spatial gradient of the wave amplitude $\partial \Omega_w / \partial h$ is a constant in the parabolic magnetic field, formation of the constant spatial gradient of the wave amplitude from the generation point near the magnetic equator to the spatial limit of the maximum wave growth is a sufficient condition for the self-sustaining nonlinear wave growth. The spatial gradient does not depend on the wave amplitude itself. When the optimum self-sustaining wave growth is realized, the gradient of the wave amplitude should be close to the value given by (59).

[25] Inserting (59) into (56), we obtain

$$\Omega_w > \frac{5V_p a s_2 \Omega_{H0} V_g}{s_0 \omega \Gamma_{NL}}.$$
(60)



Figure 3. Dispersion relation for L-mode EMIC waves with frequency $\omega/(2\pi) = f$ and wave number $k/(2\pi) = 1/\lambda$.

Using the normalized parameters, $\tilde{V}_{\perp 0} = V_{\perp 0}/c$, $\tilde{\omega} = \omega/\Omega_{H0}$, $\tilde{a} = ac^2/\Omega_{H0}^2$, and likewise for $\tilde{V}_{t\parallel}$, $\tilde{\omega}_{ph}$, and Ω_{w0} , we rewrite (60) as

$$\tilde{\Omega}_{w0} = \frac{B_w}{B_0} > \tilde{\Omega}_{th}, \tag{61}$$

where

$$\tilde{\Omega}_{th} = \frac{100\pi^3 \tilde{V}_p^3}{\tilde{\omega} \tilde{\omega}_{ph}^4 \tilde{V}_{\perp 0}^5} \left(\frac{\tilde{a}s_2 \tilde{V}_{t\parallel}}{Q} \right)^2 \exp\left(\frac{\tilde{V}_R^2}{\tilde{V}_{t\parallel}^2} \right).$$
(62)

[26] As is obvious from (58), the self-sustaining mechanism only works for h > 0. Namely the nonlinear wave growth takes place when the wave propagates away from the equator with an amplitude satisfying (61).

[27] The nonlinear wave growth is due to the formation of a resonant current as described by the second-order resonance condition, while the linear wave growth is caused by particle motion along the diffusion curve at the resonance velocity defined by the first-order resonance condition. The Poynting vector analysis for the EMIC waves [Pickett et al., 2010] indicates that the triggering EMIC wave at 1.5 Hz seems to show some positive divergence in the equatorial region. The triggering EMIC wave is likely to be excited near the equator due to the linear growth driven by the temperature anisotropy. As shown by the linear dispersion analysis in the following section, the triggering wave at 1.5 Hz is close to the cut-off frequency at 1.3 Hz (see Figure 3). The spatial linear growth rate takes the maximum value near the wave cut-off frequency [Gendrin et al., 1984]. The coherent component of the triggering wave forms an electromagnetic proton hole in the velocity phase space. Once the amplitude of the coherent wave exceeds the threshold value for self-sustaining emissions, nonlinear wave growth sets in driven by the second-order phase variation $\partial \omega / \partial t$ corresponding to the maximum value of the resonant current J_E .

[28] We evaluate the temporal variation of the wave amplitude by assuming that the spatial derivative of the wave amplitude in (55) takes the threshold value for the selfsustaining wave growth given by (59). Assuming the minimum spatial gradient of the growing wave amplitude in (59), and inserting into (55), we obtain

$$\frac{\partial \tilde{\Omega}_{w0}}{\partial \tilde{t}} = \tilde{V}_g \left[\frac{\mathcal{Q} \tilde{\omega}_{ph}^2}{2 \tilde{V}_{t\parallel}} \left(\frac{\tilde{V}_{\perp 0}}{\pi} \right)^{3/2} \left(\frac{\tilde{V}_p \tilde{\Omega}_{w0}}{\tilde{\omega}} \right)^{1/2} \exp\left(-\frac{\tilde{V}_R^2}{2 \tilde{V}_{t\parallel}^2} \right) - \frac{5 \tilde{V}_p s_2 \tilde{a}}{s_0 \tilde{\omega}} \right].$$
(63)

Rewriting (57) we obtain

$$\frac{\partial \tilde{\omega}}{\partial \tilde{t}} = \frac{2s_0}{5s_1} \tilde{\omega} \tilde{\Omega}_{w0}.$$
(64)

The temporal evolution of an EMIC triggered emission at the equator is determined by a set of equations (63) and (64). Since these equations are essentially the same as the chorus equations derived for whistler-mode chorus emissions [*Omura et al.*, 2009], we call them the EMIC chorus equations in the following.

6. Numerical Solutions of EMIC Chorus Equations and Comparison With Observations

[29] We first determine the linear dispersion relation for the EMIC triggered emission event observed by the Cluster spacecraft on 30 March 2002 as shown in Figure 1. In the absence of the measurement of the low energy thermal ions, we make use of the cut-off frequencies of the L-mode EMIC wave dispersion. The cut-off frequency is obtained by assuming k = 0 in (27). The spacecraft identified three distinct ion species, H⁺, He⁺ and O⁺. Writing $\Pi_c = 0$ explicitly, we obtain

$$\frac{\omega_{pH}^2}{\Omega_H - \omega} + \frac{\omega_{pHe}^2}{\Omega_{He} - \omega} + \frac{\omega_{pO}^2}{\Omega_O - \omega} = \frac{\omega_{pe}^2}{\Omega_e},$$
(65)

where $(\omega_{pH}, \omega_{pHe}, \omega_{pO})$ and $(\Omega_H, \Omega_{He}, \Omega_O)$ are the plasma frequencies and cyclotron frequencies of the H⁺, He⁺, and O⁺ ions, respectively. Normalizing the densities of proton, helium, and oxygen ions by the electron density as $\tilde{n}_H = n_H/n_e$, $\tilde{n}_{He} = n_{He}/n_e$, $\tilde{n}_O = n_O/n_e$, we obtain from (65)

$$\frac{\tilde{n}_H}{1-\tilde{\omega}} + \frac{\tilde{n}_{He}}{1-4\tilde{\omega}} + \frac{\tilde{n}_O}{1-16\tilde{\omega}} = 1,$$
(66)

where we use the relations $\Omega_{He} = \Omega_{H}/4$ and $\Omega_{O} = \Omega_{H}/16$. The charge neutrality condition gives

$$\tilde{n}_H + \tilde{n}_{He} + \tilde{n}_O = 1. \tag{67}$$

[30] The frequency spectra shown in Figure 1 indicate that the cut-off frequency of the upper L-mode EMIC mode bounded by the proton cyclotron frequency is ~1.3 Hz. The magnetic field measurement indicates that the proton cyclotron frequency is ~3.7 Hz. The particle measurement indicates that the densities of helium and oxygen ions are nearly equal. Setting $\tilde{\omega} = 1.3/3.7$ and $\tilde{n}_{He} = \tilde{n}_O$ in (66) and (67), we obtain $\tilde{n}_H = 0.81$ and $\tilde{n}_{He} = \tilde{n}_O = 0.095$. The



Figure 4. (a) The resonance velocity V_R and (b) the group velocity V_g of L-mode EMIC waves as functions of a frequency f.

WHISPER and EFW instruments of the Cluster spacecraft can determine the electron density as $n_e \sim 178/cc$, and thus we can estimate that $n_H = 144/cc$, $n_{He} = 17/cc$, and $n_O = 17/cc$. We plot the dispersion relation of the L-mode EMIC waves in Figure 3. As the frequency f increases from 1.5 Hz to 3.0 Hz, the wavelength λ decreases from 370 km to 63 km. In Figure 4, we plot the cyclotron resonance velocity V_R given by (33) and the group velocity V_g given by (23). It is noted that the group velocity is ~150 km/s, and it is the velocity of the wave packet generated around the magnetic equator. The resonance velocity varies as -800 km/s for f =1.5 Hz, -500 km/s for f = 1.7 Hz, and -120 km/s for f =2.5 Hz. The ratio of V_R/V_g appears in (42) and controls the frequency sweep rate (64).

[31] Figure 5 shows the cross sections of the measured velocity distribution functions at different times during the EMIC triggered emission event. Figure 5 (top) shows enhanced temperature anisotropies in the velocity range below 1000 km/s. We can find enhanced proton flux around $v_{\perp} = 800$ km/s. Therefore, we assume $V_{\perp 0} = 800$ km/s and $V_{t\parallel} = 600$ km/s so that the unperturbed velocity distribution

function has some temperature anisotropy that can excite the EMIC waves with a positive linear growth rate.

[32] We solve equations (63) and (64) numerically for the realistic parameters observed by Cluster 4 at L = 4.27. Based on the analysis presented above, we assumed $\omega_{pH} = 679 \Omega_{H0}$, $\omega_{pO} = 58.3\Omega_{H0}^{1}, \ \omega_{pHe} = 117\Omega_{H0}, \ V_{t\parallel} = 0.002c, \ V_{\perp 0} = 0.00267c, \ \text{and} \ Q = 0.5.$ We integrate the wave amplitude B_{w} and the frequency ω from $\omega = 0.4\Omega_{H0}$ starting with the observed initial wave amplitude of 0.5 nT. We tried numerical integration with different values of the energetic proton density n_h that forms the distribution function assumed in (51). With $n_h/n_H = 0.05$, we find a solution that grows in time with the longest time duration, while the wave damps out in time with a lower density. With the same density $n_h/n_H = 0.05$, we varied the initial wave amplitude as shown in Figure 6. The time duration of the emission becomes longest when the wave amplitude is just above the threshold wave amplitude, which is computed as 0.48 nT from (62). Once the wave amplitude B_w exceeds the threshold, it increases rapidly because of the strong nonlinear wave growth mechanism.

[33] We have assumed that a wave with a positive phase velocity interacts with resonant protons with negative parallel velocities. As the wave amplitude increases, the trapping velocity V_{tr} , which is the width of the electromagnetic proton hole [*Omura et al.*, 2008], also increases. As the frequency increases, the absolute value of the resonance velocity decreases. If the velocity range of the proton hole $(v_{\parallel} = V_R \pm V_{tr})$ overlaps with that of the cold protons $(v_{\parallel} = 0)$ supporting the wave propagation, the motion of the cold protons becomes highly nonlinear, invalidating the linear dispersion relation assumed in the present theory. Therefore, the following condition has to be satisfied as an extreme limit of the nonlinear wave growth:

$$V_R + V_{tr} < 0, \tag{68}$$

where

$$V_{tr} = \frac{2\omega_{tr}}{k} = 2\sqrt{\frac{V_{\perp 0}\Omega_{w0}}{k}}.$$
(69)

The condition is written for the normalized wave amplitude as

$$\tilde{\Omega}_{w0} \le \frac{\tilde{V}_p}{4\tilde{V}_{\perp 0}} \frac{(1-\tilde{\omega})^2}{\tilde{\omega}}.$$
(70)

[34] We have followed the time evolution of the wave amplitude Ω_{w0} by integrating (55) as far as the inequality (70) is satisfied. Once the inequality is violated by the growing wave amplitude, we regard the wave amplitude as saturated. The frequency evolution is followed by integrating (64) even after the saturation of the wave amplitude as shown in Figure 6. Because of the large amplitude ~ 10 nT that gives a large frequency sweep rate as indicated by (64), the time scale of the rising tones is much shorter than the observations.

[35] The detailed analysis of the wave amplitude and phase shown in Figure 7 indicates that there occurs a saturation of the wave amplitude at ~ 2.5 nT. In integrating the







Figure 6. Solutions of the EMIC chorus equations for different initial wave amplitudes indicated by different colors: 0.3 (black), 0.4 (magenta), 0.5 (red), 0.6 (green), and 0.7 (blue) nT. (a) Wave amplitudes and (b) frequencies.

wave amplitude based on (63), we stop the integration once the amplitude exceeds the saturation level of 2.5 nT to model the observed saturation. We integrate the frequency ω further by using the saturated wave amplitude up to the maximum wave frequency ~3 Hz observed in the wave spectrum. The results with different initial wave amplitudes are shown in Figure 8. The time scale of the emission is increased to about 40 seconds, which agrees well with the observed rising tone emission shown in Figures 1 and 7. The solutions plotted in Figure 8 show that the frequency sweep rate increases as the frequency increases, while it slightly decreases at higher frequencies in the observation shown in Figure 1. This is due to the variation of the group velocity shown in Figure 4b. The observed triggered emission should have propagated over some distance from the generation point near the magnetic equator. The smaller group velocity at the higher frequency makes the frequency sweep rate smaller.

[36] Using (64), we rewrite (45) as

$$\tilde{h}_c = \frac{s_0 \tilde{\omega} \Omega_{w0}}{5 s_2 \tilde{a} \tilde{V}_p}.$$
(71)

In the present case, $h_c = 320$ km for the initial wave amplitude 0.5 nT and the wave frequency 1.5 Hz. With the saturated wave amplitude 2.5 nT and the wave frequency 3.0 Hz, $h_c = 3700$ km. Therefore, the nonlinear wave growth driven by the rising frequency takes place over quite a large range of distance from the magnetic equator. Even beyond h_c , triggered wave packets can grow due to the gradient of the magnetic field as far as there exists a sufficient flux of resonant protons along the magnetic field line.

7. Summary and Discussion

[37] We have investigated the nonlinear wave growth mechanism of EMIC rising tone emissions triggered by Pc1 waves. Figure 1c shows that the Pc1 waves at 1.5 Hz consist of either right or left handed polarization. This is typical of the Pc1 waves observed during 07:55–08:20 UT on 30 March 2002 [*Pickett et al.*, 2010]. In Figures 1a and 1b, we find a decrease of the Pc1 wave amplitude at 1.5 Hz by one order of magnitude just before 07:57. This is the time when the polarization (Figure 1c) switched from right to left-handed. As the amplitude of the Pc1 wave increased again as the L-mode EMIC wave, the rising tone emission was triggered.

[38] From the condition of the absolute instability, in which the wave grows at a fixed position along the magnetic field line, we have derived the amplitude threshold condition for the nonlinear wave growth to take place in the inhomogeneous magnetic field that is approximated by a parabolic function. The triggering EMIC wave modifies the velocity distribution function of the energetic protons to



Figure 7. Amplitude and frequency analyses of the B_y (spin plane) magnetic field waveform measured by Cluster 4.



Figure 8. Solutions of the EMIC chorus equations with the wave amplitude saturation at 2.5 nT for different initial wave amplitudes indicated by different colors: 0.3 (black), 0.4 (magenta), 0.5 (red), 0.6 (green), and 0.7 (blue) nT. (a) Wave amplitudes and (b) frequencies.

form an electromagnetic proton hole in the equatorial region. When the amplitude threshold condition is satisfied by a coherent L-mode EMIC wave component forming the proton hole, the frequency increases progressively at the magnetic equator so that the maximum nonlinear growth rate Γ_{NL} is realized. We have shown that the coherent wave packets generated at different frequencies propagate with the group velocity at fixed frequencies.

[39] The nonlinear mechanism for the wave growth is exactly the same as for whistler-mode chorus emissions. Nonlinear growth of chorus emissions has been demonstrated to take place by using an electron hybrid simulation [*Katoh and Omura*, 2007; *Omura et al.*, 2008], and a full-particle simulation [*Hikishima et al.*, 2009a, 2009b]. The seeds of EMIC triggered emissions are generated at the magnetic equator, and the wave packets propagate with the group velocity. The nonlinear wave growth is driven by the frequency sweep rate $\partial f/\partial t$ around the magnetic equator. Beyond a critical distance h_c , given by (71), the nonlinear wave growth is driven by the spatial inhomogeneity $\partial B_0/\partial h$.

[40] We have derived the EMIC chorus equations that describe the variation of the wave amplitude and frequency at the magnetic equator. Using the ambient magnetic field intensity, the electron density, and the wave spectra measured by the Cluster spacecraft, we first determined the densities of H^+ , He^+ , and O^+ ions so that the wave dispersion relation agrees with the cut-off frequency of the observed wave spectra. Based on the dispersion relation, we calculated the resonance velocity of the triggering EMIC wave at f = 1.5 Hz. Taking into account the resonance velocity, we estimated the average perpendicular velocity $V_{\perp 0}$, and the parallel thermal velocity $V_{t||}$ from the particle measurement of energetic protons. Using these parameters, we solved the EMIC chorus equations for different initial wave amplitudes. In the solution we also assumed that the proton hole in the phase space stays in the negative range of the parallel velocity. This gives the saturation of the wave amplitude. However, the time scale of the rising tones did not agree with that of the observed rising emissions.

[41] In the detailed analysis of the wave phase and amplitude of the observed wave form, we found that the nonlinear growth of the wave amplitude saturates at ~2.5 nT as shown in Figure 7. We reintegrated the EMIC chorus equations incorporating the observed saturation level of 2.5 nT, and found a slower variation of the wave frequency that agrees well with the observation. The exponential wave growth for ~15 seconds and the gradual frequency increase over 40 seconds found in the case presented in Figure 7 are well reproduced as the solution of the EMIC chorus equations in Figure 8.

[42] The saturation mechanism can be explained by the decreasing resonance velocity due to the increasing wave frequency of the emission. The particle velocity distribution function may not be represented properly by an assumed Maxwellian in the lower parallel velocity range. Because of the acceleration of trapped resonant particles to higher pitch angles, as observed for resonant electrons in the whistlermode chorus emission [Hikishima et al., 2009b], the proton hole may well be filled by these accelerated resonant protons at the lower resonance velocity. With the proton hole being filled, Q in (54) and (63) approaches zero, quenching the nonlinear wave growth. There may also be an effect of oblique propagation, because the polarization analysis of the EMIC triggered emission as shown in Figure 1 reveals that there arises a significant compressional component $B_{w\parallel}$ ~0.26 B_w at the end of the nonlinear growth, while the constant Pc1 wave (~1.5 Hz) remains almost purely transverse. Such effects of the varying Q value and the oblique propagation on the nonlinear wave growth are beyond the scope of the present theoretical analysis, and it is left as a future study.

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