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# Automatic detection of the thermal electron density from the WHISPER experiment onboard CLUSTER-II mission with neural networks

N. Gilet<sup>1</sup>, E. De Leon<sup>1</sup>, R. Gallé<sup>1</sup>, X. Vallières<sup>1</sup>, J-L. Rauch<sup>1</sup>, K. Jegou<sup>1</sup>, L. Bucciardini<sup>1</sup>, V. Savreux<sup>1</sup>, P. Décreau<sup>1</sup> and P. Henri<sup>1,2</sup>

<sup>1</sup>Laboratoire de Physique et Chimie de l'Environnement et de l'Espace (LPC2E), CNRS, Université d'Orléans, Orléans,

France

<sup>2</sup>Laboratoire Lagrange, OCA, UCA, CNRS, Nice, France

## Key Points:

- We have applied self-learning methods to predict the key plasma regions crossed by the CLUSTER-II spacecraft in the Earth magnetosphere using the WHISPER instrument
- The extraction of the thermal electron density from WHISPER active (sounding mode) and natural (passive mode) electric field spectra is automatically done in the free solar wind, in the magnetosheath region and in the plasmasphere
- Such automatic procedure could be used for future data processing of electric field experiments onboard space missions (for instance AM<sup>2</sup>P onboard BepiColombo or MIME onboard JUICE)

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Corresponding author: Nicolas GILET, [nicolas.gilet@cnrs-orleans.fr](mailto:nicolas.gilet@cnrs-orleans.fr)

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**Abstract**

The WHISPER (Waves of HIgh frequency and Sounder for Probing Electron density by Relaxation) instrument has been monitoring the bulk properties of the plasma environment around Earth for more than twenty years. Onboard the 3-D Earth magnetospheric CLUSTER-II mission, this experiment delivers active and natural electric field spectra, in a frequency interval ranging respectively from 3.5 to 82 kHz, and from 2 to 80 kHz. The thermal electron density, a key parameter of scientific interest and major driver for the calibration of particles instrument, is derived from spectra.

Until recently, the extraction of the thermal electron density required a manual intervention. To automate this process, self-learning algorithms based on Multilayer Neural Networks have been implemented. The evaluation of the thermal electron density from WHISPER spectra depends on the plasma region encountered by the spacecraft. First, a fully-connected neural network has been implemented to predict the plasma region, using only the active spectra measured by the WHISPER instrument. Secondly, a specific neural network has been implemented to predict the thermal electron density for each plasma region. The model reaches up to 98% prediction accuracy for some plasma regimes. Two thermal electron density prediction models were trained, a first one to process data from the free solar wind and magnetosheath regions, and a second one for the plasmasphere region. The prediction accuracy can reach up to 95% in the free solar wind and magnetosheath regimes, and 75% in the plasmasphere.

**1 Introduction**

The CLUSTER-II mission has been successfully monitoring the plasma bulk properties of the Earth magnetosphere for more than twenty years (Escoubet et al., 1997). Launched in July and August 2000, this ESA mission is the first to study the ionized medium in near-Earth space in three dimensions, thanks to a tetrahedral configuration of four identical spacecraft (Escoubet et al., 2015). Each spacecraft follows polar orbits around the Earth, with a  $\sim 57$  h period. The elliptic orbits have been changed throughout the operations, from a closest perigee at 250 km to a farthest apogee at 120,000 km, which, together with the local time drift of the orbit plane throughout a year allows the spacecraft to cross the different plasma regions of the Earth magnetosphere. The payload is identical for each satellite, consisting of 11 experiments dedicated to the measurements of the surrounding plasma, including five instruments from the Wave Experiment Consortium (WEC, Lefeuvre et al. (1993)), among which the WHISPER (Waves of High frequency and Sounder for Probing Electron density by Relaxation; (D  cr  au et al., 1997))

50 instrument. The WHISPER instrument makes use of the two far double sphere electric anten-  
51 nas either in active (sounding) mode or in passive (natural) mode to characterize the plasma  
52 bulk properties such as the thermal electron density, the magnetic field amplitude as well as  
53 to provide useful information about the electron velocity distribution function (evdf) (Trotignon  
54 et al., 2001). In sounding mode, an active spectrum is built on-board by local excitation of the  
55 surrounding plasma at a frequency sweeping the 3.5-82 kHz range. In passive mode, the trans-  
56 mitter is switched off and the (electric) antennas are left at floating potential. The instrument  
57 becomes a natural wave receiver and spectrum analyser, delivering spectrograms over the 2-  
58 80 kHz frequency range (Décréau et al., 1997). The plasma bulk properties can be extracted,  
59 under certain conditions, from the active and natural electric field spectrograms measured by  
60 the WHISPER experiments. In particular, the thermal electron density can be deduced from  
61 the characteristics of natural waves in natural mode and from the plasma resonances triggered  
62 in active mode (Trotignon et al., 2003). The thermal electron density is one of the key datasets  
63 provided by the WHISPER experiment which is used for scientific interest (Canu et al., 2001;  
64 Darrouzet et al., 2008; El-Lemdani Mazouz et al., 2009; Kouglénou et al., 2011; Sandhu et  
65 al., 2016) and is the main driver of the calibration of the particles experiments (Johnstone et  
66 al., 1997; Trotignon et al., 2010). However, the extraction of the electron density requires a  
67 careful analysis of active and/or natural spectra and can be tricky in some plasma regions (Trotignon  
68 et al., 2001). Indeed, the location of plasma resonances in the electric field spectrograms, re-  
69 lated to the plasma parameters, strongly depends on the plasma conditions such as the mag-  
70 netic field or the evdf (Gilet et al., 2017). The presence and frequency position of plasma res-  
71 onances are documented in theoretical works (Bernstein, 1958). They are also revealed by nu-  
72 merical modeling of the experimental responses (Chassériaux et al., 1972; Wattiaux et al., 2019).  
73 However, a study of the resonances patterns of both active and natural spectra measured by  
74 the experiment is required (Trotignon et al., 1986, 2001). In the case of the WHISPER instru-  
75 ment, the thermal electron density is extracted via a semi-automatic pipeline, and sometimes  
76 fully manually, e.g. for cross-calibration purposes or detailed scientific analysis (Trotignon et  
77 al., 2010).

78 Fully-automatic algorithms, based on Machine Learning and Deep Learning methods,  
79 are developing quickly and some are already implemented in order to simplify data process-  
80 ing of space experiments. For instance, such algorithms have been implemented to detect space  
81 weather events (e.g. space weather forecasting, Camporeale et al. (2018)), to extract plasma  
82 parameters from space experiments (Zhelavskaya et al., 2016) or to predict the plasma regions

83 in near-Earth regions (Nguyen et al., 2019; Breuillard et al., 2020). In order to automate the  
84 extraction of the thermal electron density from the electric field spectra measured by the WHIS-  
85 PER experiment, we propose to implement neural network methods (LeCun et al., 2015; Good-  
86 fellow et al., 2016). As explained above, the detection of the thermal electron density strongly  
87 depends on the plasma regime, mainly driven by the magnetic field strength (Trotignon et al.,  
88 2010). Therefore, the implemented pipeline proceeds in two steps. The first one is to deter-  
89 mine the plasma region to separate (i) regions where the electron plasma frequency is the only  
90 resonance in the frequency bands (i.e. electron cyclotron frequency is neglected), typically cor-  
91 responding to the solar wind and the magnetosheath, and (ii) regions where the electron plasma  
92 frequency is of the order of the electron cyclotron frequency, typically corresponding to the  
93 plasmasphere. To this purpose, we have implemented a fully-connected (dense) neural network  
94 classifying WHISPER spectra into three classes: free solar wind, magnetosheath and other plasma  
95 regions, including the plasmasphere, the tail and the cusp. The prediction accuracy can reach  
96 up to 98% for some plasma regimes. The second step is to automatically extract the thermal  
97 electron density from WHISPER electric field spectra using neural networks specifically im-  
98 plemented for each plasma region or group of plasma regions. In the free solar wind and the  
99 magnetosheath regions, we chose a recurrent (GRU) neural network architecture (Cho et al.,  
100 2014) to predict the electron plasma frequency from which the thermal electron density is de-  
101 rived. The prediction accuracy reaches up to 95% with a tolerance of one frequency bin (i.e.  
102 162.8 Hz, the difference between two scanned frequencies). For the plasmasphere region, the  
103 upper hybrid frequency, which is more easily detected in active spectra than the plasma fre-  
104 quency, is predicted, then the thermal electron density is derived using the electron cyclotron  
105 frequency (obtained from the magnetic field measurement). The corresponding self-learning  
106 model is a fully-connected (dense) neural network. The prediction accuracy reaches up to 75%  
107 with a tolerance of one frequency bin.

108 A pipeline based on the self-learning algorithms detailed in this study is currently un-  
109 der development, to deliver the thermal electron density from the free solar wind and the mag-  
110 netosheath region to the Cluster Science Archive (Laakso et al., 2010). The efficiency of the  
111 automatic detection of the thermal electron density shows that such automated methods could  
112 be used to extract the plasma bulk properties from future experiments such as mutual impedance  
113 experiments onboard BepiColombo (PWI/AM<sup>2</sup>P) (Trotignon et al., 2006) and JUICE (RPWI/MIME)  
114 missions (Grasset et al., 2013).

115 This paper is organized as follows. First, the WHISPER experiment and its correspond-  
116 ing dataset are described in Sect 2. Secondly, we give a high-level description of the neural  
117 networks in Sect. 3. Thirdly, we detail the methods used to predict the plasma region encoun-  
118 tered by the spacecraft from WHISPER spectra and we explain the results given by the best  
119 neural network in Sect. 4. In Sect. 5, we describe the predictions of thermal electron density  
120 applied in different plasma regimes. In Sect 6, we discuss the applicability of such methods  
121 in the data processing of the WHISPER instrument and future electric field experiments such  
122 as PWI/AM<sup>2</sup>P and the RPWI/MIME onboard respectively BepiColombo and JUICE missions.  
123 Finally, we conclude our study in Sect 7.

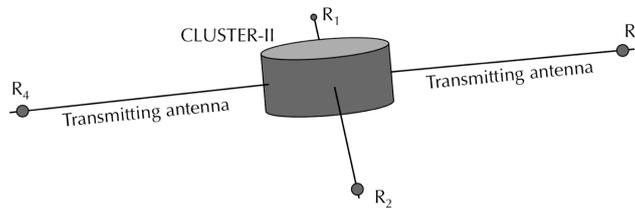
## 124 **2 Instrumentation and data**

125 In this section, we first summarize the main characteristics of the WHISPER instrument  
126 (Sect 2.1). Then, we introduce its key datasets mainly composed of active and natural elec-  
127 tric field spectra and of the thermal electron density (Sect 2.2). Finally, we give an overview  
128 of the semi-automatic algorithms currently used to extract the thermal electron density from  
129 the WHISPER spectra (Sect 2.3).

### 130 **2.1 WHISPER instrument**

131 As part of the Wave Experiment Consortium (WEC, Lefeuvre et al. (1993)), the Waves  
132 of High frequency and Sounder for Probing Electron density by Relaxation (WHISPER) in-  
133 strument is a relaxation sounder that monitors the *in situ* space plasma bulk properties such  
134 as the thermal electron density (Décréau et al., 1997). Such instruments have been previously  
135 deployed in several space missions which operated in various ionized environments such as  
136 near Earth (GEOS-1 & 2, ISEE-1, Viking) or in the interplanetary medium (Ulysses) (Décréau  
137 et al., 1978; Harvey et al., 1979; Bahnsen et al., 1986; Stone et al., 1992). The WHISPER prin-  
138 ciple is based on electric coupling between pairs of electric dipole antennas embedded in the  
139 surrounding plasma. This specific experiment consists of a pair of receivers and transmitters  
140 associated with parts of two WEC instruments: the sensors of the Electric Field and Wave (EFW,  
141 Gustafsson et al. (1997)) experiment and the data processing capability of the Digital Wave  
142 Processing (DWP, Woolliscroft et al. (1997)) experiment. Figure 1 shows the WHISPER ex-  
143 periment configuration, which consists of four orthogonal wire booms carrying spherical sen-  
144 sors (8 cm in diameter) at the tips and deployed around the spacecraft. The electric antennas  
145 have sphere-to-sphere separations of 88 m. Further information on the WHISPER electron-

146 ics (operational features and performances) are described in detail in Décr  au et al. (1997).  
 147 Note that the WHISPER instrument is identical on each of the four CLUSTER-II spacecraft.



**Figure 1.** Illustration of the WHISPER relaxation sounder configuration, identical for the four CLUSTER-II spacecraft, using the EFW electric field antennas as transmitters and two of the four spherical booms  $R_i$  (8 cm in diameter) at the end of each antenna as receivers. The electric antennas have sphere-to-sphere separations of 88 m.

148 Two operational modes are used alternatively.

149 First, in sounding (active) mode, transmitters emit a sinusoidal signal from one antenna  
 150 pair, at a given time  $t$  and frequency  $f$ , during a short time duration ( $\sim 1$  ms). Each train pulse  
 151 covers a frequency band of 976.6 Hz centered on the given frequency  $f$ . Next, the signal is  
 152 received on the EFW probes of a receiving pair ( $R_1R_2$  or  $R_3R_4$ ) at  $t+\delta t$ . Using onboard Fourier  
 153 analysis of the instrument response around the transmitted frequency and by sweeping the trans-  
 154 mitted frequency over the 3.5-82 kHz frequency range, a 162.8 Hz frequency resolution (512  
 155 bins) E-field spectrum is constructed on-board.

156 Secondly, in passive (natural) mode, transmitters are switched off. The WHISPER ex-  
 157 periment becomes a simple electric receiver and performs a Fourier analysis to acquire a nat-  
 158 ural spectrum in the 2 to 80 kHz frequency range, with a frequency resolution of 162.8 Hz,  
 159 corresponding to 512 bins (D  cr  au et al., 1997).

160 The sounding mode is operated alternately with the natural wave mode, with all four space-  
 161 craft following the same timeline. The WHISPER instrument is highly configurable and a num-  
 162 ber of operational parameters can be set by telecommand from ground. The resulting time res-  
 163 olution, depending on these parameters, varies from 0.3 to 3.4 s in natural mode and is gen-  
 164 erally of 1.5 s in active mode. The typical operational pattern includes 3 s of active mode, fol-  
 165 lowed by 49 s of natural mode.

166 The relaxation sounder is based on the resonance principle of the propagation of plasma  
 167 eigenmodes (Krall & Trivelpiece, 1973). Basically, the plasma characteristic frequencies of

168 the surrounding medium are triggered when these frequencies are in the emitted frequency range.  
 169 When the transmitted pulse frequency is close to some plasma characteristic frequencies, very  
 170 intense echoes are received. These stimulated signals are called plasma resonances. The WHIS-  
 171 PER experiment operates close to the plasma characteristic frequencies which are typically found  
 172 in the radio frequency (RF) range in Earth magnetospheric plasma. This effect allows the ex-  
 173 traction of characteristic frequencies, which are directly related to the plasma bulk properties.  
 174 In natural mode, only the natural electric emissions are monitored. Plasma bulk properties can  
 175 thus be inferred from the analysis of active and natural spectra, among which:

*The electron plasma frequency*, noted  $f_{pe}$ , which is directly related to the thermal electron den-  
 sity as follows:

$$f_{pe} = \frac{1}{2\pi} \sqrt{\frac{n_e e^2}{\epsilon_0 m_e}}, \quad (1)$$

176 where  $n_e$  is the thermal electron density,  $e$  is the electric charge,  $\epsilon_0$  is the vacuum permittiv-  
 177 ity and  $m_e$  the electron mass. The formula can be simplified as follows:  $f_{pe}[\text{kHz}] \sim 9 \sqrt{n_e[\text{cm}^{-3}]}$ .

*The electron cyclotron frequency and its harmonics*, noted  $n f_{ce}$ , reads:

$$f_{ce} = \frac{1}{2\pi} \frac{e B_0}{m_e}, \quad (2)$$

178 where  $B_0$  is the magnetic field amplitude. The formula can be simplified as follows:  $f_{ce} [\text{kHz}]$   
 179  $\sim 0.028 B_0 [\text{nT}]$ . Note that the electron cyclotron frequency can be extracted using the mea-  
 180 surement of the magnetic field amplitude given by the magnetometer onboard the CLUSTER-  
 181 II spacecraft (Balogh et al., 1997).

*The upper hybrid frequency*  $f_{uh}$ , related to  $f_{ce}$  and  $f_{pe}$ , and defined as follows:

$$f_{uh} = \sqrt{f_{pe}^2 + f_{ce}^2}, \quad (3)$$

182 *Bernstein frequencies*: in magnetized plasma, Bernstein frequencies, noted  $f_{qn}$ , can occasion-  
 183 ally be measured by the WHISPER experiment. They satisfy the following conditions:  $f_{qn} >$   
 184  $2f_{ce}$  and  $n f_{ce} < f_{qn} < (n+1)f_{ce}$  (Bernstein, 1958). The frequency location of Bernstein modes  
 185 has been tabulated in the Hamelin diagram for a plasma at thermal equilibrium (Hamelin, 1978;  
 186 Trotignon et al., 2001). A shift between the tabulated frequency and the observed  $f_{qn}$  can re-  
 187 veal the presence of a non-maxwellian evdf, e.g. two-electron-temperature plasma (Belmont,  
 188 1981). Note that the lower hybrid frequency can be observed in specific cases (e.g. deep plas-  
 189 masphere, Kougl  n  u et al. (2011)). This characteristic frequency is mainly driven by the mo-  
 190 tion coupling of ions and electrons which allows to constrain the plasma ion composition.

## 2.2 WHISPER dataset

Both active/natural electric field spectra and the derived thermal electron density compose the key science datasets of the WHISPER experiment. The active and natural spectrograms show typical signatures encountered by the spacecraft in the different key plasma regions of the Earth magnetosphere. The characteristic signature of waves indicates the nature of the plasma region and, combined with the spacecraft position, reveals the different magnetospheric boundaries and regions. Figure 2 illustrates an example of several plasma region crossings by C3 (SAMBA) spacecraft from 18 Feb 2007 at 09:43 UT to 19 Feb 2007 at 09:53 UT associated with the frequency/time WHISPER active and natural spectra (second and third panels), the variation of the electron cyclotron frequency  $f_{ce}$  derived from the FGM measurement (fourth panel) and the variation of the electron plasma frequency  $f_{pe}$  extracted by *ad hoc* methods (fifth panel). The satellite evolved from the free solar wind at large distances from Earth ( $\sim 17.0 R_e$ ), then crossed the bow shock at  $\sim 16.3 R_e$  around 17:23 UT on 18 Feb 2007 and penetrated the magnetosheath until around 00:06 UT on 19 Feb 2007 at  $\sim 10.7 R_e$ . This plasma region crossing is well identified by a strong increase of the electron plasma frequency  $f_{pe}$  (here from  $\sim 20$  kHz to  $\sim 30$  kHz). Then, the spacecraft entered the inner magnetosphere region in the cusp region (around 00:10 UT). Note that  $f_{pe}$  was not extracted using *ad hoc* methods due to a low signal-to-noise ratio. Finally, C3 spacecraft crossed the plasmasphere (characterized by higher  $f_{ce}$  values) a few minutes later.

Figure 3 shows typical active (black curves) and natural (red dotted curves) electric field individual spectra measured by the WHISPER experiment in the key plasma regions with their corresponding plasma resonances extracted by *ad hoc* methods (see Sect. 2.3). The spectra have been expressed in dB and normalized between 0 and 1. First and second panels show the active and natural spectra measured *in situ* respectively in the free solar wind and in the magnetosheath regime. In this regime, the electron temperature and the magnetic field amplitude are low, leading to the excitation of only one resonance usually triggered at, or close to, the electron plasma frequency  $f_{pe}$  (shown by blue vertical dotted bars), from which the thermal electron density is derived. For instance, in the free solar wind (resp. magnetosheath regime),  $f_{pe} \sim 21.1$  kHz, (resp.  $f_{pe} \sim 48.2$  kHz) corresponding to  $n_e \sim 5.51$  cm $^{-3}$  (resp.  $n_e \sim 28.76$  cm $^{-3}$ ). Third panel shows the spectra measured by WHISPER in the plasmasphere regime. In this region, the electron cyclotron frequency  $f_{ce}$  ( $\sim 5.5$  kHz) and its harmonics (green) can be measured by the WHISPER instrument as well as Bernstein resonances (magenta) and the upper hybrid frequency  $f_{uh}$  ( $\sim 29.4$  kHz) (yellow).  $f_{pe}$  is then derived from  $f_{uh}$  and  $f_{ce}$  ( $\sim 28.9$  kHz).

224 The WHISPER dataset used for the self-learning algorithms presented in this paper consist of  
225 active/natural electric field spectra which have been processed by *ad hoc* methods to extract  
226 the thermal electron density. We briefly discuss this pipeline in the following section.

### 227 **2.3 *Ad hoc* methods**

228 In order to provide scientific analysis support and dissemination of high-level data, sev-  
229 eral semi-automatic algorithms have been developed to extract the thermal electron density  
230 (Trotignon et al., 2010). They are based on a manual analysis of the plasma region (a reso-  
231 nance pattern) based on WHISPER active and natural spectra, EFW spacecraft potential mea-  
232 surements and FGM magnetic field measurements, coupled with an automatic extraction of  
233 spectral features (resonance, low cutoff, ...) from WHISPER active and/or natural spectra. The  
234 algorithms are specific to (i) the plasma region and (ii) the operational mode (active and nat-  
235 ural). In the free solar wind and the magnetosheath, the extraction of the electron plasma fre-  
236 quency is usually performed by (i) identifying the frequency position at maximum amplitude  
237 for active spectra or, (ii) identifying the low frequency cut-off for natural spectra. When nat-  
238 ural signatures are unclear, a proxy can also be derived, obtained from the cross-calibration  
239 of the EFW spacecraft potential and the electron plasma frequency obtained from WHISPER  
240 active spectra analysis. In the plasmasphere, the thermal electron density is extracted by (i)  
241 the location of the upper hybrid frequency or by (ii) manual analysis. For each plasma regime,  
242 the extraction process includes a manual selection of the frequency band which contains the  
243 desired characteristic frequencies, with the risk of a bad selection.

244 This study aims to a fully-automatic electron density production on the easiest regions  
245 to analyze (i.e. solar wind and magnetosheath regimes) in order to deliver data faster and re-  
246 duce manpower and subjectivity due to the manual operations. For this purpose, we have im-  
247 plemented automatic routines based on neural networks. First, the region determination is the  
248 key to apply the appropriate algorithm for density calculation. Therefore, we have implemented  
249 a neural network which predicts the plasma regime. Secondly, we have applied a specific neu-  
250 ral network to determine the thermal electron density for the solar wind/magnetosheath region  
251 (for production tool) and for the plasmasphere region (for specific events). We detail the main  
252 stages of neural network process in the next section.

### 3 Multilayer neural networks

In this section, we provide a general description of neural networks of direct interest to this study. Such methods are derived from a simplified model of the neural system based on the dynamical electrochemical properties of biological neurons and their inter-connections (McCulloch & Pitts, 1943).

Rosenblatt (1957) was the first to implement such a biological architecture, called Perceptron, to solve simple linear problems dealing with two classes of signals. This model was composed of a single layer of artificial neurons which is fully-connected to the input and the output layers. Each modern neural network is based on this model (Lecun & Bengio, 1995; Goodfellow et al., 2016). We provide a functional description of an artificial neuron in Sect 3.1. Then, we give the basic aspects of the architecture of the neural network based on a stack of artificial neuron layers (Sect. 3.2). Finally, we introduce the implementation of such tools in Sect 3.3.

#### 3.1 Artificial neuron

An artificial neuron is an information-processing unit that produces an output  $y$  from an input signal  $x$  (Haykin, 1999). The neuron is the basic unit component of any neural network method. The input signal is typically expressed by a vector:

$$x = (x_1, \dots, x_m) \in \mathbb{R}^m$$

The signal  $x$  of dimension  $m$  is connected to the neuron  $k$  by a set of synapses characterized by the synaptic weight, also expressed by a vector of dimension  $m$ :

$$w_k = (w_{k,1}, \dots, w_{k,m}) \in \mathbb{R}^m$$

The signal  $x$  is multiplied by the synaptic weights which is represented in mathematical terms by a scalar product between the vectors  $x$  and  $w_k$ , called  $u_k$ :

$$u_k = \sum_{j=1}^m w_{k,j} x_j$$

Note that a bias, called  $b_k$ , can be added to  $u_k$ . This bias allows the scalar product  $u_k$  to deviate from 0, that can lead to a better updates of the synaptic weights during the learning phase. Then, an operation to  $u_k$  is performed by an activation function called  $\varphi$ . This function allows to (i) limit the amplitude range of the output signal and to (ii) introduce a non-linearity leading to a more complex transformation of the input data. The popular activation functions used on artificial neurons are (i) the hyperbolic tangent function, that is differentiable, continuous

and delivering output values ranging from -1 to 1, (ii) the *ReLU* function ( $ReLU(x) = \max(x, 0)$ ) which is not differentiable at 0 but fast to compute, and (iii) the sigmoid function defined as  $\varphi(x) = 1/(1 + \exp(-x))$  for which the output value ranges from 0 to 1 and the derivative is non-null which allows the neural network to make some progress at every step. The output  $y_k$  of the artificial neuron is then expressed by:

$$y_k = \varphi(u_k + b_k)$$

Figure 4 summarizes the architecture of such artificial neuron with an  $m$ -dimensional signal input and  $m$  synaptic weights. Note that artificial neurons can be more elaborated, such as for recurrent neural network (Hochreiter & Schmidhuber, 1997; Cho et al., 2014) from which the output  $y_k$  depends on the previous state of the neuron, or for convolutional network (LeCun et al., 2015) where each neuron performs a filtering operation (i.e. discrete convolution) on a specific part of the data. We discuss the architecture of the artificial neural network composed of several neuron layers in the following section.

### 3.2 Artificial Neural Networks

The main idea of neural networks is to extract linear combinations of input data as derived features, and then model the output as a nonlinear function of these features. These supervised methods are mainly used for classification and/or regression tasks (Goodfellow et al., 2016). As illustrated in Figure 5, a neural network is composed of several layers of artificial neurons that are interconnected with neurons from the previous and the following layer. The classical layers from literature (LeCun et al., 2015) are:

*Input layer:* This layer is composed of the content of the input dataset. In term of mathematical representation, each component of the dataset, called  $X_i$ , is expressed as a vector of the size of the data (here  $m$ ) and the entire dataset composed of  $n$  data, is expressed by a matrix  $\mathbf{X}$ :

$$\mathbf{X} = (X_1, \dots, X_m) \in \mathbb{R}^{m,n}$$

*Hidden layers:* The intermediate layers are called hidden layers and are composed of a set of artificial neurons (see Sect 3.1). These layers allow the neural network to learn complex tasks by extracting progressively more meaningful features from the input dataset.

*Output layer:* Neural networks produce a predicted output for a given input  $X_i$  defined by a vector called  $y_i^*$  as follows:

$$y_i^* = (y_1, \dots, y_N)$$

The output  $y_i^*$  can be expressed as a function depending on the input  $X_i$  and the free parameters (i.e. synaptic weights + additional parameters) as follows:

$$y_i^* = f(X_i; \mathbf{W})$$

where  $\mathbf{W}$  is the whole synaptic weights  $w_{i,j}$ .  $f$  can be seen as a combination of functions of the following form:

$$f(x) = \mathbf{f}^{(d)}(\dots \mathbf{f}^{(i)}(\dots (\mathbf{f}^{(2)}(\mathbf{f}^{(1)}(x))) \dots) \dots)$$

283 where  $d$  is the number of hidden layers and  $f^{(i)} = (f_1^{(i)}, f_2^{(i)}, \dots, f_w^{(i)})$ , where  $f_w^{(i)}$  is the acti-  
 284 vation function  $\varphi_{w,i}$  associated to the  $i^{\text{th}}$ -artificial neuron on the  $w^{\text{th}}$  hidden layer. Usually, for  
 285 a single classification task, the sigmoid function is chosen as the activation function of the last  
 286 layer. Then, the predicted coordinates  $y_i$  of the output  $y_i^*$  are expressed between 0 and 1 and  
 287 their sum equals to 1. Therefore, the output  $y_i^*$  can be seen as a probability of belonging to  
 288 a class. Moreover, the corresponding classifier of the input data  $X_i$  is defined as  $C(X_i) = \text{argmax}(y_i^*)$ .

289 Neural networks are defined in a way that each neuron is structured and connected to  
 290 each other. This architecture (i.e. structure) strongly depends on the problem to solve. In lit-  
 291 erature, there exist several categories of neural network architectures. In a first category, the  
 292 connection between artificial neurons can flow only in one direction from the input layer to  
 293 the output layer. Note that the neurons can be fully or partially interconnected. This architec-  
 294 ture, called multilayer feedforward network, is the simplest neural network architecture. The  
 295 hidden layers are seen as feature extractions of the input dataset. In a second category, the re-  
 296 current neural network differs from the feedforward neural network in that neurons can have  
 297 backward pointing connections that can be understood as a form of memory. This architec-  
 298 ture is useful when the input data are related in time. Such methods are commonly used for  
 299 the data processing of temporal series. In this study, we have implemented both architectures.

To predict the class of the input data, the neural network needs to be trained, i.e. the synap-  
 tic weights  $\mathbf{W}$  need to be updated. The training step of the neural network can be seen as an  
 optimisation problem. First, the free parameters  $\mathbf{W}$  are randomly initialized and a computa-  
 tion of current  $y^*$  is realized. Then, the accuracy of the prediction is computed by measuring  
 the difference between the current estimated class  $C_i$  and the true training class  $C_{i,true}$ . For that,  
 we compute an objective function (i.e. a loss function), such as the categorical crossentropy

function is defined as follows:

$$J(\theta) = \sum_i^m y_{i,true} \log(f(X_i; \mathbf{W}))$$

Then, we need to update the free parameters of the neural network to model the prediction on the training outputs. For that, the loss function  $J$  is minimized by a gradient descent method (called optimizer) using the backpropagation technique (Rumelhart et al., 1986). This technique uses the fact that the derivative of  $J$  with respect to the synaptic weights can be expressed as the prediction error. Note that the derivative of  $J$  is only compared to a limited part of the synaptic weights, chosen randomly, which is the main idea of the Stochastic Gradient Descent (SGD). Therefore, we choose new free parameters that reduce the loss function:

$$\mathbf{W}_{new} = \mathbf{W}_{old} - \epsilon \nabla_{\mathbf{W}} J(X, \mathbf{W}_{old})$$

where  $\epsilon$  is the step of the descent which is commonly called the learning rate. Note that some optimizers add a more complex step or/and descent direction in order to speed up the convergence of the gradient descent (see ADAM method (Kingma & Ba, 2014), Adagrad method (Duchi et al., 2011) or RMSprop method (Tieleman & Hinton, 2012)). The update is performed iteratively for a fixed number of times called epochs.

Usually, the input and the output data are split into three different sub-datasets: (i) a training dataset, (ii) a validation dataset and, (iii) a test dataset. The training dataset is fed to the neural network which tunes the free parameters to make correct predictions on the dataset itself. Therefore, this dataset need to be representative of the global problem. The validation and the test dataset are used to know how well the neural network will generalize to new cases. If the model performs well on the training data, but it does not generalize, we say that the model overfits the training data, i.e. learning features are too specific to the training dataset. This overfitting can be reduced by using a regularization technique called dropout (Srivastava et al., 2014). Basically, this technique ensures that every neuron has a probability  $p$  of being temporarily ignored during one training step. The hyperparameter  $p$  is called the dropout rate.

To evaluate the performance on the different datasets, we compute an accuracy score such as, for a classification task, the ratio of correct predictions, which is defined as:

$$acc = \frac{1}{N} \sum_i^N \mathbb{1}_{C_i=C_{i,true}}$$

where  $C_{i,true}$  is the true class of the data  $X_i$ . We have used this accuracy score in the following to evaluate the performance of the tested self-learning methods.

Note that the accuracy score does not take into account the class distribution (some classes could appear much more frequently than others) and does not give information about the num-

319 ber of True Positive (TP), True Negative (TN), False Positive (FP), and False Negative (FN).  
320 Neural network performances can be described by the following metrics: (i) the accuracy of  
321 the positive precisions among all predicted positives, called precision and computed as  $TP/(TP+FP)$ ,  
322 and (ii) the ratio of positive instances, called recall and computed as  $TP/(TP+FN)$ , that are cor-  
323 rectly detected by the method. As FP and FN are quite similar in this study, the performance  
324 is simply illustrated by the accuracy score.

### 325 3.3 Implementation and resources

326 Nowadays, neural network methods are largely and actively used in space science, es-  
327 pecially in space weather applications for the data processing and the automatic detection of  
328 space weather events (Camporeale et al., 2018). Zhelavskaya et al. (2016) applied neural net-  
329 works to automatically determine the electron density from an electric field experiment on-  
330 board Van Allen Probes mission (Mauk et al., 2013). For that, they used the measured elec-  
331 tric field spectra and some geomagnetic conditions such as magnetic field line or the geomet-  
332 ric index. For this study, we chose to apply two separated neural networks to (i) determine the  
333 plasma region encountered by the spacecrafts (Sect. 4) and to (ii) extract the thermal electron  
334 density (Sect. 5), using only the WHISPER spectra, therefore ignoring external conditions.

335 Several other automatic methods have been tested to process the WHISPER dataset. It  
336 must be noted that a large number of sub-operational modes exist, leading to different frequency  
337 bandwidth (hence several frequency steps). Unsupervised methods (i.e. unlabeled algorithms)  
338 such as KMEANS (Arthur & Vassilvitskii, 2007) or DBSCAN (Ester et al., 1996) are sensi-  
339 tive to these modes, i.e. the results are driven by operational mode and not plasma regimes.  
340 Neural networks have been retained because they can overcome this issue. Moreover, they do  
341 not require feature extraction (i.e. data representation) to improve the accuracy of the predic-  
342 tion, in contrary to the majority of self-learning algorithms. Indeed, the hidden layers of the  
343 neural networks (see Sect. 3.2) allow the extraction of different features from the data (which  
344 are unknown and possibly difficult to interpret).

345 Neural networks have been implemented using Python libraries *Scikit-Learn* (Pedregosa  
346 et al., 2011) and *Keras* (Chollet et al., 2015). They have been run on a workstation featured  
347 with an AMD Threadripper 2990 WX (32 cores at 3.4 GHz) and a GPU card Nvidia Geforce  
348 1660 GTX (6 Go DDR5 with 1406 CUDA cores).

349 Hereafter, we detail the neural networks used to predict the plasma regions (resp. the  
350 thermal electron density) in Section 4 (resp. in Sect. 5).

## 4 Detection of the plasma regimes

In this section, we describe the implementation of several neural networks to predict the plasma region into three classes: solar wind, magnetosheath and other plasma regions (plasmasphere, tail, cusp, ...). First, we detail the input data and the output (i.e. labels) of the neural networks (Sect. 4.1). Secondly, we compare the performance of the neural networks (Sect. 4.2). Finally, we apply the best neural network to more WHISPER data (Sect. 4.3).

### 4.1 Data and labels

To predict the plasma region crossed by CLUSTER-II at a specific time, we have used the WHISPER data format defined for the Cluster Science Archive (Trotignon et al., 2010). Each active spectrum contains 480 frequency bins covering the 3.5-81.5 kHz band. Note that for the sub-operational modes measured at different frequency bandwidth (see Sect. 2.1), the missing values are replaced by 0. Each natural spectrum contains 470 frequency bins covering the 3.5-79.9 kHz band. Moreover, all spectra have been expressed in decibels ( $20\log_{10}$ ) and individually normalized between 0 (amplitude min.) and 1 (amplitude max.). Therefore, each input data can be expressed as:

$$X_i = (act_1, \dots, act_{480}, nat_1, \dots, nat_{470})$$

where  $act_i$  (resp.  $nat_i$ ) is the  $i^{th}$  value of the active spectrum (resp. natural spectrum).

The spectra  $X_i$  are classified as three different plasma regimes: (i) free solar wind, (ii) magnetosheath region and, (iii) a class containing various ionized medium (plasmasphere, tail, cusp, ...). Therefore the output  $y^*$  can be seen as a vector of three dimensions containing the estimated probability for each class. The plasma region  $C_i$  is chosen as  $argmax(y^*)$ .

In order to train the neural network and validate its outputs, the region labels have been identified manually for a substantial set of data randomly chosen during the mission lifetime. We ensured that the training and the test datasets were sufficiently representative of the entirety of WHISPER spectra by verifying that selected data distributions in terms of (i) value of thermal electron density and (ii) the maximum amplitude in dB were consistent/representative with the overall same distributions. Finally, the total number of spectra are the following: 113,829 spectra from the free solar wind, 118,632 spectra from the magnetosheath and 113,551 spectra from other plasma regions and from an additional specific dataset composed of 40,762 spectra measured in the plasmasphere. From this dataset, we randomly took 67% of the spectra from each plasma region to build the training (95%) and the validation dataset (5%). The

373 testing dataset is composed of the remaining 33%. In order to classify WHISPER spectra ac-  
374 cording to the plasma region encountered by the CLUSTER-II spacecraft, we have tested sev-  
375 eral neural networks and we have optimized the neural network characteristics (number of hid-  
376 den layers, number of neurons, learning rate, ...) using GridSearch method (Géron, 2019).  
377 A comparison between some architectures is presented in the following section.

## 378 4.2 Comparison of several architectures

379 We have compared two neural networks architectures: (i) a fully-connected (DENSE)  
380 neural network (see Sect. 3.2) and (ii) a recurrent (GRU) neural network (Cho et al., 2014).  
381 Each architecture has been tested with three different input datasets containing respectively: (i)  
382 only the active spectra (A), (ii) the active and natural spectra (A+N) and, (iii) only the nat-  
383 ural spectra (N).

384 To compare the performance of these models, we have first computed the variation of  
385 the accuracy on each input dataset during the training task. Results are shown in Figure 6. First,  
386 each model converged after four iterations (i.e. epochs). Secondly, we see that the neural net-  
387 works which only learnt with the natural spectra (green and yellow curves) have the poorest  
388 accuracy (from 0.84 to 0.91) whatever the architecture (dense or recurrent). This observation  
389 is consistent with the fact that the plasma resonances are not actively excited in passive mode  
390 (see Fig. 3). Therefore, the plasma signatures are generally less visible in the natural spectra.  
391 Finally, the best accuracy is obtained with the fully-connected (DENSE) architecture with the  
392 active and natural spectrum combination (purple curve). The accuracy goes up to 97.5% at the  
393 last epoch. We see that the recurrent (GRU) architecture gives a lower accuracy than the fully-  
394 connected network, whatever the input data.

395 Secondly, we have applied these neural networks to the test dataset composed by 24,324  
396 spectra measured in the free solar wind, 25,562 spectra measured in the magnetosheath region  
397 and 51,406 in other plasma regions (including the plasmasphere). We have computed the ac-  
398 curacy and the output probability given by these models. These parameters are presented in  
399 Table 1. On one hand, we can see that the dense neural network trained with only the active  
400 spectrum (DENSE A) gives the best accuracy for the solar wind and the magnetosheath (resp.  
401 97.9 and 96.4%). However, the recurrent neural network trained with only the active spectra  
402 (GRU A) gives the best accuracy for the other plasma regions (98.5%). On the other hand,  
403 we have computed (i) the mean probability associated to the predicted plasma region  $C_i$  given  
404 by the neural network (fourth column), (ii) the mean probability associated to the predicted

**Table 1.** Accuracy and mean probability of several neural networks implemented to predict the plasma region (Solar Wind, Magnetosheath and Other): GRU with active + natural spectrum in input (GRU A+N), GRU with only the active spectrum (GRU A), GRU with only natural spectrum, fully-connected NN with active + natural (DENSE A+N), fully-connected NN active (DENSE A) and fully-connected with only natural spectrum (DENSE N).

Model	Solar Wind	Magnetosheath	Other	Mean Proba.		
				Total	Correct Pred.	Wrong Pred.
GRU A+N	94.9	93.0	94.2	0.95	0.96	0.77
GRU A	95.6	92.8	98.5	0.97	0.98	0.75
GRU N	75.8	76.6	87.2	0.89	0.92	0.77
DENSE A+N	94.3	94.6	95.0	0.96	0.97	0.77
DENSE A	97.9	96.4	96.9	0.95	0.96	0.66
DENSE N	75.2	83.5	87.8	0.92	0.94	0.81

405 plasma region (i.e. maximum probability for each spectrum) when the model predicted the cor-  
 406 rect class and, (iii) the mean probability associated to the predicted plasma region (i.e. max-  
 407 imum probability for each spectrum) when the model predicted a wrong class.

408 We see that GRU A model has the highest mean probability for correct prediction (0.98)  
 409 and DENSE A model has the lowest mean probability for wrong predictions (0.66). There-  
 410 fore, if we choose to impose a threshold on the probability to delete the wrong predictions,  
 411 more correct predictions will be kept with both models. In the following, we chose to apply  
 412 the DENSE A model to predict the plasma regime.

413 Table 2 summarizes the characteristics of this neural network, which is used to predict  
 414 the plasma regime. The training part needs about 1 hours for 200,000 active spectra and the  
 415 prediction (i.e. testing) part takes around 5 seconds for 50,000 active spectra. We have applied  
 416 the model to more WHISPER spectra. We discuss the results in the following section.

**Table 2.** Characteristics of the best neural network model used to predict the plasma regime.

Model	<b>Plasma Regime</b>
Input	Active spectrum
# of spectra	305,480
Pre-processing	normalized dB
Architecture	Dense
# hidden layers	3
# neurons	1024+1024+1024
Activation function	ReLU/Sigmoid
Dropout	30%
Loss function	Categorical Crossentropy
Optimizer	Adam
Metrics	Accuracy
Number of parameters	3,076,099
Output	3 classes (SW,MS,Other)

### 4.3 Application of the best model

We have applied the model presented in Table 2 to WHISPER measurements presented in Sect 2.2 from 18 Feb 2007 at 09:43 UT to 19 Feb 2007 at 09:54 UT when the C3 spacecraft crossed several plasma boundaries. Figure 7 (middle panel) shows the corresponding classification obtained from the neural network: solar wind (yellow), magnetosheath region (red) and other (blue). We see that the plasma region boundaries are quite well defined. For instance, we note that the model predicted a solar wind region from the beginning to 17 Feb 2007 at ~17 h corresponding to the bow shock crossing (see Fig. 3). Then, the model predicted a magnetosheath region until 19 Feb 2007 at ~00:00 corresponding to the penetration of the satellite into the magnetopause. Finally, the model predicted, as expected, a magnetosphere regime. Resulting predictions are consistent with the shape of the spectra. First, only one strong resonance is observed on the active spectra (upper panel). Then, the magnetosheath region corresponds to a lower maximum amplitude leading to a low signal-to-noise ratio. Finally, the plasmasphere is well defined by the presence of several plasma resonances, especially the harmonics of the electron cyclotron frequency, which depend on the magnetic field amplitude.

Note that the magnetic field amplitude could provide a direct way to distinguish the plasma regimes. However, we only used the WHISPER dataset in order to set up an electron density pipeline independent from the other CLUSTER-II instruments, that is mainly motivated by operational considerations.

We observe that wrong predictions can be observed inside the boundaries. For instance, some spectra are labeled as magnetosheath whereas they seem to belong to the plasmasphere or the tail. In particular, in the free solar wind, the model sometimes predicted a magnetosheath regime. This can be due to (i) instrumental artefact such as a low signal-to-noise ratio or the presence of interferences potentially affecting the noise level or (ii) the fact that the prediction is only based on WHISPER observations. Indeed, WHISPER spectra acquired in the free solar wind and in the magnetosheath regions usually exhibit the same features, leading to an ambiguous prediction. Similar observations have been done with unsupervised and supervised methods (e.g. decision tree). In the other plasma regimes, including the plasmasphere, the wrong predictions are mainly due to (i) a high amplitude of the magnetic field (leading to an electron cyclotron frequency above the WHISPER frequency range) and, (ii) a poor signal-to-noise ratio.

Let us analyse the prediction of the plasma region compared to external parameters such as the magnetic field amplitude and the spacecraft position. Figure 8 shows the predicted plasma

450 region for one orbit (from 4 Jan 2013 at 00:00 UT to 6 Jan 2013 at 4:00 UT) with respect to  
451 the electron cyclotron frequency (expressed in kHz in logarithmic scale) and the  $X_{gse}$  coord-  
452 inate (Russell, 1971), normalized by the Earth radius. As expected, the solar wind region is  
453 associated with a large distance from Earth (higher than 10 Earth radii) on the Sun side and  
454 a low electron cyclotron frequency (i.e. low magnetic field). Moreover, the magnetosheath re-  
455 gion is associated with a large Earth distance range (from 2.5 to 10 Earth radii) and interme-  
456 diate electron cyclotron frequencies (from 0.1 to 1 kHz). The other plasma regions are pre-  
457 dicted close to Earth, especially the plasmasphere regime, where the plasma region is driven  
458 by a high magnetic field amplitude (i.e. high electron cyclotron frequency). Therefore, we can  
459 conclude that the predicted plasma regions are mainly driven by the spacecraft location and  
460 the magnetic field, despite the fact that the prediction is only implemented with WHISPER  
461 spectra.

462 In both case studies (Fig. 7 and 8), an interference or less likely other signatures (e.g.  
463 lower hybrid frequency) can be incorrectly interpreted as the unique plasma resonance lead-  
464 ing to a classification in the magnetosheath or solar wind regime. In order to correct these wrong  
465 predictions and avoid such isolated detections, plasma regions time/space continuity could be  
466 taken into account. To this end, we have implemented another step in the predicted plasma  
467 region process: the  $k$ -nearest neighbors algorithm (Cover & Hart, 1967; Géron, 2019). This  
468 method is generally applied for data classification tasks using pre-labeled data as input. For  
469 each unlabeled data (or test data), the method identifies the  $k$ -nearest neighbors taken from the  
470 labeled data and determines the most contributing class. If we consider a uniform contribu-  
471 tion between the  $k$ -nearest neighbors, the most contributing class is then equivalent to the most  
472 frequent class among the  $k$ -nearest neighbors. The resulting class is then assigned to the test  
473 data.

474 We have applied this method to the spatial domain around the Earth. In this context, the  
475 input data are the points along the spacecraft orbit (defined by their GSE coordinates) and pre-  
476 viously labeled by the neural network. For each grid point defining a volume around the Earth  
477 (corresponding to an unlabeled test data), the algorithm determines the  $k$ -nearest neighbors and  
478 the resulting class. Finally, we have decided to take advantage of this large-scale labelling pro-  
479 cess to correct the region associated with each point of the orbit by imposing the label (i.e.  
480 plasma region) of the closest volume point.

481 Figure 9 shows the results for one complete orbit of C1 spacecraft in the  $XY_{gse}$  frame,  
482 normalized by Earth radius, from 4 Jan 2013 at 00:00 UT to 6 Jan 2013 at 4:00 UT. The plasma

483 regions predicted by the neural network are given by the color points (yellow: solar wind, red:  
484 magnetosheath and blue: other) along the orbit. The background color represents the plasma  
485 regions predicted by the  $k$ -nearest neighbors algorithm from the neural network predictions  
486 as inputs. We see that wrong detections made by the neural network can be corrected by the  
487 large-scale classification given by the  $k$ -nearest neighbors algorithm, as the plasma region bound-  
488 aries are now well defined. Note that using this method with a high value for  $k$ , the plasma  
489 region is less sensitive to wrong predictions (not shown here) but cannot account for fast mul-  
490 tiple boundary crossings (e.g. when skimming the bow shock).

491 As explained in Sect. 2.2, the detection of the thermal electron density depends on the  
492 plasma regime. The automatic prediction of the plasma region is then used as an input of the  
493 extraction of the thermal electron density. We present the automatic model and the results of  
494 the prediction of the thermal electron density in the following section.

## 495 **5 Prediction of the thermal electron density**

496 In this study, we chose to define two separated neural networks which apply in differ-  
497 ent plasma regimes. First, in the solar wind/magnetosheath regime, a self-learning algorithm  
498 is implemented in order to fully automate the extraction of the thermal electron density. We  
499 describe the method and the results in Sect. 5.1. Secondly, we focused on the plasmasphere  
500 region from which the extraction of the thermal electron density is more intricate, and *ad hoc*  
501 methods require a manual intervention. We present the neural network and the given predic-  
502 tions in Sect. 5.2.

### 503 **5.1 In the solar wind/magnetosheath regime**

#### 504 **5.1.1 Data and labels**

505 As explained in Sect. 2.2, the two plasma regions considered now (solar wind and mag-  
506 netosheath, respectively) are characterized by the presence of a main resonance on spectra lo-  
507 cated at, or close to, the electron plasma frequency. Therefore, the thermal electron density  
508 can be directly derived from the predicted electron plasma frequency, and is obtained in the  
509  $0.15$  to  $82.37$   $\text{cm}^{-3}$  range (corresponding to the  $3.5$ - $82$  kHz frequency range). Note that *ad hoc*  
510 methods can provide an electron plasma frequency which could be not aligned on the emit-  
511 ted frequency bins of the active mode. In that case, the electron plasma frequency has been  
512 translated onto the nearest active frequency bin. Therefore, the frequencies have been rescaled

513 on the emitted frequency bins of the active mode. Thus, the output of the model can be seen  
514 as a vector of 480 classes corresponding to the emitted frequencies defined in the 3.5-82 kHz  
515 bandwidth with a 162.8 Hz resolution. For the input data, we have used the active spectra and  
516 the time-closest natural spectra measured by WHISPER where the thermal electron density  
517 has been extracted from *ad hoc* methods adapted to the solar wind and the magnetosheath regimes.

518 Note that we have chosen not to consider a class corresponding to the case where *ad*  
519 *hoc* methods were not able to extract the electron plasma frequency, that means that spectra  
520 without associated plasma frequency were discarded from the analysis. The prediction of such  
521 models are sensitive to the presence of this class (not shown here), in particular because the  
522 extraction of the electron plasma frequency from *ad hoc* methods is mainly based on natural  
523 spectra and then assigned to the closest active spectrum in time. Therefore, two similar ac-  
524 tive spectra will not necessarily lead to the same plasma frequency estimations. Actually, the  
525 training part can be strongly affected by such a case, when the model learning is based on ac-  
526 tive spectra.

527 The labels (i.e. the electron plasma frequencies) have been identified manually for a sub-  
528 stantial set of data selected during the entire mission lifetime. We ensured that the data is rep-  
529 resentative of the entire WHISPER dataset, in particular with respect to the distribution of the  
530 electron plasma frequency for each plasma regime. The total numbers of spectra are the fol-  
531 lowing: 73,709 spectra for the solar wind and 77,458 spectra for the magnetosheath regime.  
532 From this dataset, we randomly took 67% of the spectra from each plasma region to build the  
533 training and the validation dataset. The testing dataset is composed of the remaining 33%.

### 534 **5.1.2 Comparison of several architectures**

535 Like in Sect. 4, we have tested several neural network architectures to predict the ther-  
536 mal electron density in the solar wind and in the magnetosheath regime. We have implemented  
537 two architectures: (i) a fully-connected (DENSE) neural network and, (ii) a recurrent (GRU)  
538 neural network. Each architecture has been trained and tested with the same dataset composed  
539 of three sub-datasets with (i) only active spectra (A), (ii) with active and natural spectra (A+N)  
540 and, (iii) only natural spectra (N).

541 Figure 10 shows the evolution of the accuracy of the two neural network architectures  
542 separately trained with the three sub-datasets. First, we see that the two architectures tested  
543 with only the natural spectra give the worst accuracy (between 0.1 to 0.2), probably due to lower  
544 signal-to-noise ratio. As explained in Sect. 4, in passive mode, the signal-to-noise ratio is lower

545 than the sounding (active) mode. Therefore, the determination of the plasma frequency is more  
546 tricky for this operational mode. Secondly, the best accuracy is obtained by the recurrent neu-  
547 ral network (GRU) tested with only the active spectra. The accuracy reaches up to 0.7 at the  
548 last epoch whereas the accuracy of the other neural networks do not exceed 0.6. Thus, we chose  
549 to apply the GRU architecture with only the active spectrum to predict the electron plasma fre-  
550 quency in the free solar wind and in the magnetosheath regime. Table 3 summarizes the main  
551 parameters of the retained neural network. The training part needs about 2 hours for 200,000  
552 active spectra and the prediction (i.e. testing) part takes around 40 seconds for 50,000 active  
553 spectra. We have applied the model to more WHISPER spectra. We discuss the results of this  
554 model on the WHISPER dataset in the following section.

### 555 **5.1.3 Results**

556 In this section, we comment on the results of the thermal electron density automated de-  
557 tection in the solar wind/magnetosheath region using the best neural network chosen in the  
558 previous section.

559 First, we have tested the recurrent neural network presented in section 5.1 on 24,323 (resp.  
560 25,561) active spectra acquired in the free solar wind (resp. in the magnetosheath regime). We  
561 have computed the difference between the predicted electron plasma frequency ( $f_{pe,pred}$ ) and  
562 the electron plasma frequency given by *ad hoc* methods ( $f_{pe,ad hoc}$ ), considered as ground truth.  
563 Figure 11 shows the percentage of correct predictions within a tolerance interval (expressed  
564 in kHz) for different neural network architectures. We can see that the recurrent (GRU) neu-  
565 ral network with active spectra as input (represented by the red line) gives the best absolute  
566 accuracy (70%). By increasing the tolerance interval by one frequency bin ( $\pm 0.182$  Hz) for  
567 each predicted electron plasma frequency, we see that recurrent and dense models are give quite  
568 similar accuracy (95%). This large increase of the precision is mainly due to the fact that the  
569 electron plasma frequency, extracted by *ad hoc* methods, is given as a real value and the pre-  
570 dicted electron plasma frequency is expressed into the 480 frequency bins of the active mode.  
571 Moreover, the detection of the electron plasma frequency by *ad hoc* methods, sometimes, can  
572 be done with only the natural spectrum. Therefore, in the active spectrum, the predicted plasma  
573 frequency can be different by one or several bins compared to the plasma frequency given by  
574 *ad hoc* methods.

575 Secondly, we have run the neural network on active spectra measured by WHISPER on  
576 C1 on 13 Feb 2012 between 00:02 and 13:21 UT. At this time, the spacecraft were in the free

**Table 3.** Summary of the neural network used to determine the thermal electron density in the Solar Wind and Magnetosheath region

Model	SW/MS
Input	Active spectrum
# of spectra	151,167
Pre-processing	normalized dB
Architecture	Recurrent (GRU)
# hidden layers	3
# neurons	1024+1024+1024
Activation function	ReLU/Sigmoid
Dropout	30%
Loss function	Categorical Crossentropy
Optimizer	Adam
Metrics	Accuracy
Number of parameters	17,215,491
Output	$f_{pe}$ on 480 freq. bins (3.5 to 81.5 kHz)

577 solar wind region characterized by a single plasma signature observed on active spectra. Fig-  
 578 ure 12 shows the prediction of the electron plasma frequency  $f_{pe}$ , expressed in frequency bins  
 579 (red points) and the electron plasma frequency given by *ad hoc* methods (black points).

580 For this case study, we have computed the relative error made by the self-learning al-  
 581 gorithm compared to the thermal electron density  $n_e$  derived from the electron plasma frequency  
 582  $f_{pe}$ , extracted using *ad hoc* methods. The distribution of the electron density relative error is  
 583 shown in Figure 13 (upper panel). We see that the relative error is low. Notably, the mean of  
 584 the relative error is around 0.01. The bottom panel shows the scatter plot of the predicted ther-  
 585 mal electron density  $n_e$  versus the density extracted by *ad hoc* methods. We see that the pre-  
 586 dictions follow the electron density given by *ad hoc* methods. However, there exist wrong pre-  
 587 dictions for which the model gave  $n_e \sim 2\text{-}5\text{cm}^{-3}$  and *ad hoc* methods,  $n_e \sim 12\text{ cm}^{-3}$ . Taking  
 588 into account the probability  $y_i$  corresponding to the predicted class given by the model (col-  
 589 orbar), we see that the probability is low (from 0.2 to 0.4). Therefore, it could be possible to  
 590 delete these wrong predictions by imposing a reasonable threshold on the probability  $y_i$ .

591 We also predicted the thermal electron density in the solar wind and the magnetosphere  
 592 regions for a larger amount of data. We have applied the self-learning method to 29,735 WHIS-  
 593 PER data measured onboard C1 in 2012. Figure 14 shows three scatter plots of the thermal  
 594 electron density showing the predicted electron density versus the density detected by *ad hoc*  
 595 methods. The first panel shows all the data. The middle panel shows the data where the prob-  
 596 ability is higher than 0.2. The amount of data has decreased to 28,094. The right panel shows  
 597 the data where the probability is higher than 0.5. The amount of data has decreased to 21,386.  
 598 We see that the number of wrong predictions also decreases. Therefore, if we want to auto-  
 599 matically extract the thermal electron density, it is possible to impose a probability threshold  
 600 in order to minimize the wrong predictions.

## 601 **5.2 In the plasmasphere regime**

### 602 **5.2.1 Data and labels**

603 The prediction of the thermal electron density in the plasmasphere is more tricky than  
 604 in the solar wind and the magnetosheath regions. In active spectra, the resonance correspond-  
 605 ing to the electron plasma frequency is less visible, when it is, than the resonance located at  
 606 the upper hybrid frequency (see Figure 3). Therefore, we have chosen to identify the upper  
 607 hybrid frequency in a first step, and then, knowing the electron cyclotron frequency from the

608 measurement of the magnetic field amplitude of FGM, to derive the electron plasma frequency.  
609 This automatic pipeline is shown in figure 15.

610 We have used active spectra and the closest natural spectrum measured by WHISPER  
611 for which the thermal electron density has been extracted using *ad hoc* methods. We only kept  
612 spectra (i) that are not labeled in the solar wind and magnetosheath region and (ii) spectra where  
613 the electron cyclotron frequency (derived from the magnetometer) is higher than 1.5 kHz. Then,  
614 we deleted 16% of the dataset ( $\sim 58,000$  spectra) by applying thresholds on several charac-  
615 teristics of active spectra. In particular, for each active spectrum, we have computed the num-  
616 ber of resonances that are not located close to the electron cyclotron frequency or to its har-  
617 monics. A high value of this number (i.e. higher than 5) means that the key plasma resonances,  
618 especially the resonance associated with the upper hybrid frequency, if measured, are not well-  
619 described in the spectrum. Moreover, we have modified the threshold to be less restrictive us-  
620 ing the mean amplitude at low and high frequencies in order to limit the impact of the noise  
621 at such frequencies. A combination of the two descriptors allows to delete different kinds of  
622 active spectra which are considered as not suitable for detection of the electron plasma fre-  
623 quency or the upper hybrid frequency.

624 On the selected active spectra, a top-hat filter (Serra, 1983) has been applied in order  
625 to amplify the plasma resonances. Moreover, the spectra have been normalized in dB between  
626 0 and 1. The output of the model can be seen as a vector of 480 classes corresponding to the  
627 emitted frequencies defined on the 3.5-81.5 kHz bandwidth with a precision of 162.8 Hz. Note  
628 that the electron plasma frequency can be lower than 3.5 kHz. 360,607 spectra measured in  
629 the plasmasphere have been used. A careful study of this dataset has been performed in or-  
630 der to adopt a well representative dataset of the WHISPER instrument in the plasmasphere.  
631 In particular, we ensured that in both datasets, the distribution of the upper hybrid frequency,  
632 compared to the electron cyclotron frequency and its harmonics or Bernstein waves, was sim-  
633 ilar to the entire measurements of the WHISPER experiment. From the entire dataset, we ran-  
634 domly took 66.7% of the spectra to build the training and the validation datasets. The testing  
635 dataset is composed of the remaining 33.3%.

636 Table 4 summarizes the characteristics of the best neural network used in the plasma-  
637 sphere to predict the upper hybrid frequency. Note that the model uses a hybrid activation func-  
638 tion composed of an Exponential Linear Unit (ELU) and a hyperbolic tangent function (Clevert  
639 et al., 2016; Manessi & Rozza, 2018). We apply the Nesterov Accelerated Gradient method  
640 (Nesterov, 1983). This method measures the gradient of the cost function not at the local po-

sition but slightly ahead in the direction of the momentum vector that points generally in the right direction. Note that the low dropout rate (5%), considered as a hyperparameter of the model, has been obtained using a grid search method (Bergstra & Bengio, 2012). We applied this neural network to the WHISPER dataset. The results are shown in the following section.

### 5.2.2 Results

Figure 16 shows an almost perfect case of active spectrogram in the plasmasphere measured on C1 (RUMBA) on 5 August 2002 between 17:00 and 20:40 UT. It shows several plasma resonances corresponding to the electron cyclotron frequency  $f_{ce}$  and its harmonics, the upper hybrid frequency  $f_{uh}$ , and Bernstein frequencies. The corresponding frequency bins of the electron plasma frequency  $f_{pe}$ , when obtained with *ad hoc* methods, are shown in the bottom panel as black points, while those predicted by the automatic pipeline are shown in red.

We have computed the relative error of the predicted thermal electron density derived from the predicted  $f_{pe}$  for this case study. The distribution of the relative error is shown in Figure 17 (upper panel). The mean relative error is around 0.09, thus larger than in the solar wind/magnetosheath regime. We have also computed the scatter plot of the predicted thermal electron density versus the density given by *ad hoc* methods (Fig. 17, lower panel). We can observe that the model seems sometimes perturbed by other resonances, as illustrated by vertical lines formed by the points on the scatter plot for this case study. The probability  $y_i$  of each prediction is represented by the colorbar. In contrast with the solar wind or the magnetosheath region results, the model gives a lower probability of correct predictions (around 0.2). This low probability is mainly due to the fact that the active spectra shown in this case study are of exceptional quality, with all of the key plasma resonances well-described. This kind of spectra is rare and thus poorly represented in the training dataset, then leading to a low probability value for the prediction. For most of spectra measured in the plasmasphere, the probability of correct predictions is quite similar to the probability given in the solar wind/magnetosheath regime.

## 6 Future data processing

In this section, we first describe the applicability of self-learning methods for the data processing of WHISPER spectra (section 6.1). Secondly, we discuss the applicability of such automatic data processing for the future active electric field experiments onboard spacecraft such as BepiColombo/Mio or JUICE (section 6.2).

**Table 4.** Characteristics of the best neural network used to determine the upper hybrid frequency in the plasmasphere regime. The hybrid activation function is a combination of an Exponential Linear Unit (ELU) and a hyperbolic tangent function.

Model	<b>Plasmasphere</b>
Input	Active + Natural spectrum
# of spectra	360,607
Pre-processing	normalized dB + additionnal processing (top hat)
Architecture	Dense
# hidden layers	2
# neurons	512+480
Activation function	Hybrid function*
Dropout	5%
Loss function	Categorical Crossentropy
Optimizer	Nesterov
Metrics	Accuracy
Number of parameters	964,032
Output	$f_{uh}$ on 480 freq. bins (3.5 to 81.5 kHz)

## 6.1 WHISPER data processing

In this study, we have applied self-learning algorithms to predict the thermal electron density on specific data or events. We could apply these methods to the complete WHISPER dataset, present and future, and replace *ad hoc* methods (see Sect. 2.3), currently in use, by the self-learning methods shown in this study. However, the high cadence of WHISPER spectra measurements requires an optimization of the manual intervention, especially for deleting wrong detections. In order to minimize this intervention, we have implemented a new pipeline that evaluates the self-learning algorithms in the solar wind and the magnetosheath regime. This tool, named FP JEDAI (Judging Electron Density by Artificial Intelligence), allows to plot, visualize and validate the predictions made by the neural networks. It is developed with the main objective of reducing the tedious and time-consuming electron density manual determination or *ad hoc* methods selection. FP JEDAI combines two models described in this study: the region classification model and the  $f_{pe}$  determination model only applied in the solar wind and the magnetosheath regimes.

First, the model used in the tool predicts the plasma region for each spectrum. Using the time stamp and the probabilities provided by the model, large intervals are automatically selected. This step allows to automatically delete the spurious predictions, in particular the predictions of dynamic plasma regions that varies a lot in a short time period. Secondly, the electron plasma frequency is extracted from the selected spectra. Combined with a probability threshold, a contrast formula, that gives information about the resonance-to-noise ratio, is computed in order to select only the best predictions. The interface allows manual selection of the electron plasma frequency in order to delete the bad predictions. Finally, the thermal electron density is computed and saved in a file.

FP JEDAI could allow to deliver density files with human intervention reduced up to 10 times for WHISPER active spectra (compared to the *ad hoc* methods) and only limited to a validation step (as opposed as a preprocessing step and a validation step for the currently used *ad hoc* methods). For instance, the processing of one month of data for the four spacecraft requires approximatively 4h of manual intervention whereas the *ad hoc* methods required around 40h. In order to limit ambiguous predictions, we imposed a severe threshold (around 0.4) on the probability associated to each density estimate. This can lead to a 20%-loss in the number of electron densities given by neural networks as compared to *ad hoc* methods.

## 6.2 Future electric field experiments

Self-learning algorithms could be used for future space missions such as BepiColombo (Benkhoff et al., 2010) or JUICE (Grasset et al., 2013) which include electric field experiments such as mutual impedance experiments (Trotignon et al., 2006) or quasi-thermal noise spectroscopy (Moncuquet et al., 2006).

For instance, the Active Measurement of Mercury's Plasma (AM<sup>2</sup>P, (Trotignon et al., 2006)) experiment is one element of the Plasma Wave Investigation (PWI, Kasaba et al. (2020)) consortium onboard the Mercury Magnetospheric Orbiter (Mio/MMO) of the BepiColombo mission, successfully launched in October 2018. From March 2026, the mutual impedance experiment aims to determine the thermal electron density in the Hermean magnetosphere for plasma frequencies in the 0.7-120 kHz band. The Mio/MMO spacecraft will fly along an elliptic polar orbit of 400×11,824 km with a 9.3 h period (Benkhoff et al., 2010), so that the spacecraft will cross several plasma regions (Yagi et al., 2017; Kasaba et al., 2020) such as the free solar wind, where the electron cyclotron frequency is expected to be much smaller than the electron plasma frequency, and the Hermean plasmasphere, where the electron cyclotron frequency and its harmonics will be much larger than the electron plasma frequency. Therefore, the electric field spectrogram should present similarities, in terms of frequency position of plasma signatures, with the Earth magnetospheric observations made by the WHISPER instrument. Prediction of the plasma region will also be highly desirable to automatically extract the plasma bulk properties from the AM<sup>2</sup>P measurements. In contrast with the WHISPER experiment which has been operating for more than twenty years, the mutual impedance experiment should monitor the Hermean plasma environment for two and a half terrestrial years at most (including a planned one terrestrial year extension). Moreover, the AM<sup>2</sup>P measurement cadence will be lower than the one of WHISPER instrument, with active measurements planned to be performed every 160–200 s in the Hermean magnetosphere and every 320–400 s in the free solar wind. Therefore, the amount of AM<sup>2</sup>P active spectra will be substantially lower than those of the WHISPER dataset. In order to characterize the capability to implement a neural network to predict the plasma regime, we have studied the influence of the amount of spectra needed for an efficient prediction of the plasma regime.

Figure 18 shows the accuracy of the neural network on a test dataset with respect to the number of active spectra in the training dataset from 10 to 10,000 spectra. The corresponding time period to measure such number of spectra with the AM<sup>2</sup>P instrument is given by the colored verticals bars from 1 day (blue) to 4 months (red). The training dataset is built with

735 spectra randomly chosen. In order to be independent of this random part, we have run the model  
736 several times with different training datasets. The overall accuracy score is then given with an  
737 error bar (shown in vertical black lines) for each case. We see that the accuracy goes up from  
738 0.5 to 0.95, meaning that an automatic pipeline to predict the plasma region will be efficient  
739 after 4 months of operations. Note that this estimation is based on the assumption that all spec-  
740 tra are exploitable, especially in the solar wind and the magnetosheath regions where a clear  
741 single signature is expected to be observed. Therefore, the number of spectra actually needed  
742 in the training dataset could be higher in real operational conditions.

743 However, in order to increase the size of the training dataset, it could be possible to model  
744 the electric field experiments. Indeed, modeling of the experimental response has been per-  
745 formed in several plasma conditions such as in interplanetary plasma or planetary plasma (Béghin,  
746 1995; Gilet et al., 2017; Wattieaux et al., 2019; Gilet et al., 2019). Recent studies show that  
747 modeling of the experiment taking into account the effect of a vacuum sheath around the ex-  
748 periment and the spacecraft, are close to *in situ* observations (Wattieaux et al., 2019). More-  
749 over, thanks to a comparison between the observations and the dataset of modeled spectra, it  
750 is possible to characterize the surrounding plasma. Wattieaux et al. (2020) provided a char-  
751 acterization of two-electron-temperature-plasma in the ionosphere of 67P/Churyumov-Gerasimenko  
752 using a combination of the observations made by the mutual impedance probe (RPC-MIP, Trotignon  
753 et al. (2007)) and the modeling of the instrument response. Therefore, it is possible to gen-  
754 erate a dataset of modeled electric field spectra in order to train a model to predict the plasma  
755 region and, eventually, the thermal electron density. A complementary alternative could be to  
756 make use of modelling of the plasma regions in the context of the JUICE mission using iono-  
757 spheric modeling of Ganymede (Leclercq et al., 2016; Leblanc et al., 2017; Carnielli et al.,  
758 2019) from which the plasma bulk properties can be extracted to model the instrumental re-  
759 sponses of mutual impedance experiments (Gilet et al., 2017; Wattieaux et al., 2019).

## 760 **7 Conclusion**

761 In this study, we have implemented several automated pipelines based on neural network  
762 methods to extract the thermal electron density from the electric field spectra measured by WHIS-  
763 PER instrument onboard the four CLUSTER-II spacecraft. We have seen that the determina-  
764 tion of the thermal electron density mainly depends on the plasma regime, which is driven by  
765 the magnetic field amplitude and the solar activity. In the electric field spectrogram, the ef-

766 effect of the magnetic field leads to the presence of multiple plasma resonances, thus compli-  
767 cating the determination of the electron plasma frequency.

768 Therefore, we first predicted the plasma region encountered by the WHISPER instru-  
769 ment from the active and natural spectra. We have used a fully-connected (dense) neural net-  
770 work composed of three hidden layers with additional dropout. We have shown that the model  
771 reaches an accuracy score close to 97% for the three plasma regimes. Then, we have imple-  
772 mented two neural networks in the solar wind/magnetosheath region (i.e. low magnetic field)  
773 and in the plasmasphere (i.e. high magnetic field).

774 In the low magnetic field regime, the main resonance is close to the electron plasma fre-  
775 quency, that is directly related to the thermal electron density. Therefore, we chose to predict  
776 the electron plasma frequency, defined in the frequency range of the WHISPER instrument.  
777 We have used a recurrent neural network based on Gated Recurrent Unit (GRU) built with three  
778 hidden layers of 1024 neurons with additional dropout (30%). In the free solar wind and in  
779 the magnetosheath regimes, the prediction accuracy score reaches up to 95%. A fully-automatic  
780 pipeline is currently under development (FP JEDAI) in order to produce datasets of thermal  
781 electron density using outputs of the neural networks (prediction and probability).

782 For the plasmaspheric region (in practice, for electron cyclotron frequencies higher than  
783 1.5 kHz), the spectral signature at the upper hybrid frequency, related to the electron cyclotron  
784 frequency and the electron plasma frequency, is much more simple to detect than the signa-  
785 ture at the electron plasma frequency. Therefore, we first chose to predict the upper hybrid fre-  
786 quency. Then, with the cyclotron frequency computed from the magnetic field amplitude mea-  
787 sured by the magnetometer, it is possible to automatically determine the thermal electron den-  
788 sity. We have shown that active spectra need to be pre-processed in order to increase the ac-  
789 curacy of the upper hybrid frequency prediction. In the plasmasphere regime, the prediction  
790 accuracy score reaches up to 75%. For the other plasma regions such as the cusp or the tail  
791 where the signal-to-noise ratio is low, the extraction of the thermal electron density is more  
792 tricky. A specific automatic method is currently under development.

793 Finally, we have shown that automatic methods could be applied for future data process-  
794 ing of electric field experiments such as mutual impedance experiments onboard BepiColombo  
795 (Hermean environment) and JUICE (jovian environment) missions with constraints related to  
796 the size of the dataset. The efficiency of the automatic process strongly depends on the qual-  
797 ity and the representativeness of the training dataset. We have shown that in the context of Bepi-  
798 Colombo, a self-learning predictive model of PWI/AM<sup>2</sup>P instrumental response in the Her-

799 mean environment should only be effective after 4 months of operations around Mercury. How-  
 800 ever, modeling of the instrumental responses (Gilet et al., 2017; Wattiaux et al., 2019) could  
 801 be used to feed the training dataset and shorten this period.

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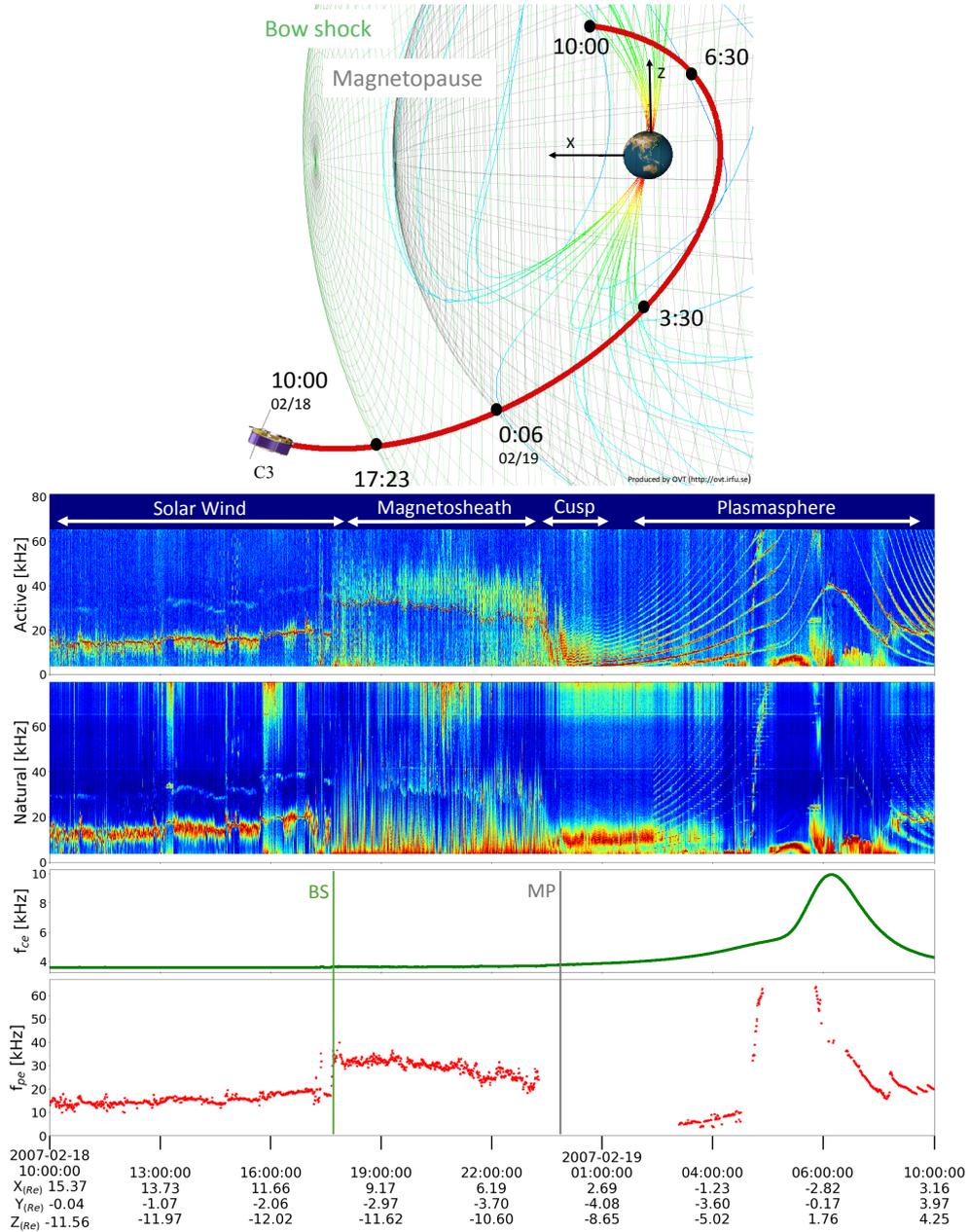
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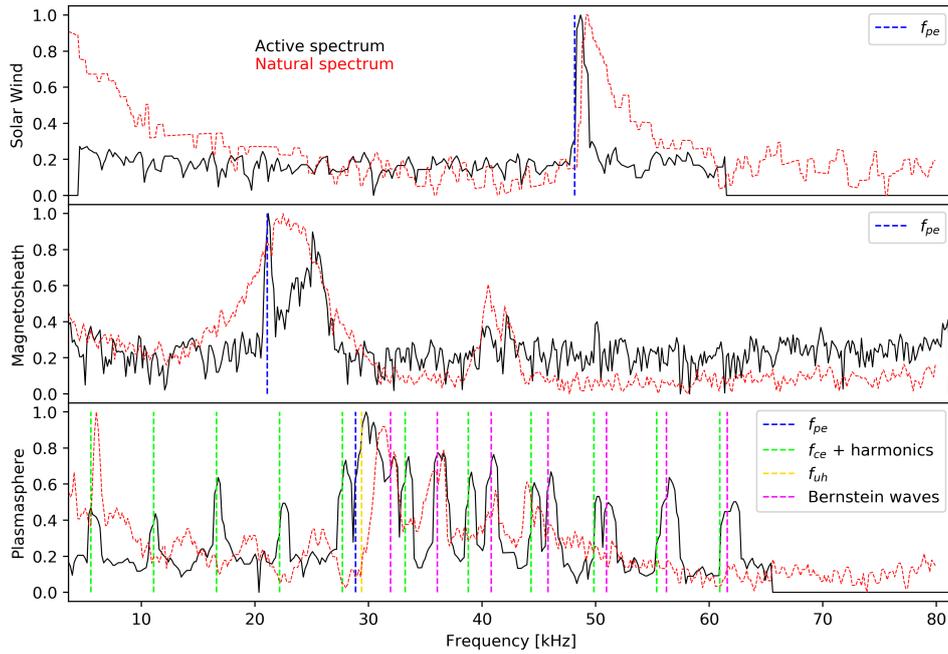
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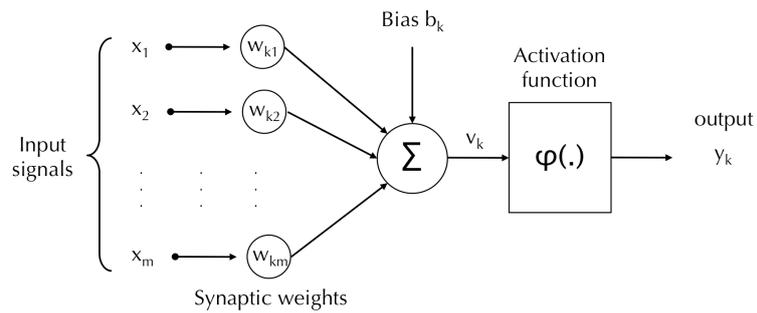
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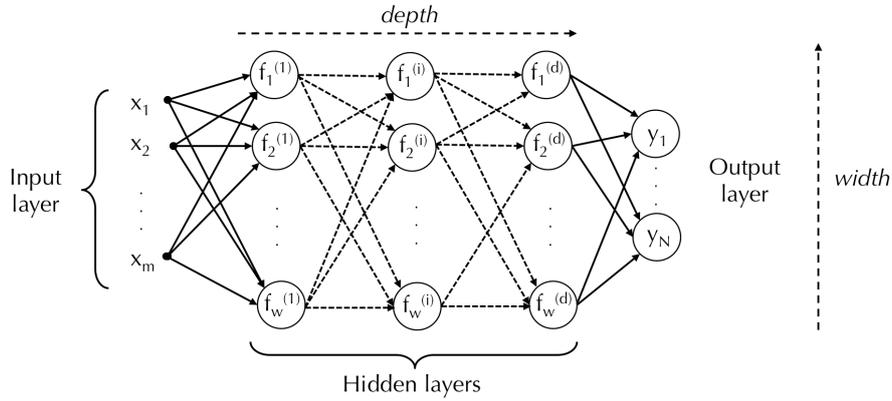
**Figure 2.** Overview of the WHISPER dataset with parameters of interest measured from 18 Feb 2007 at 09:43 UT to 19 Feb 2007 at 09:54 UT on the C3 (SAMBA) spacecraft. *Upper panel:* orbit of the C3 spacecraft (red line) and field lines in the X-Y GSE coordinate system, normalized to the Earth radius  $R_e$ , produced by the Orbit Visualization Tool (OVT) (available at <http://ovt.irfu.se/>). C3 crossed the bow shock and the magnetopause successively at 17:23 and 00:06 UT. *Second and third panel:* Frequency/time active and natural electric field spectrograms measured by WHISPER, expressed in dB normalized between 0 and 1 (red: maximum amplitude, blue: minimum amplitude). *Fourth panel:* Variation of the electron cyclotron frequency  $f_{ce}$ , expressed in kHz, derived by the measurement of the magnetic field amplitude by FGM. *Fifth panel:* Variation of the electron plasma frequency  $f_{pe}$ , expressed in kHz, extracted from the WHISPER spectra by *ad hoc* methods (see Sect. 2.3).



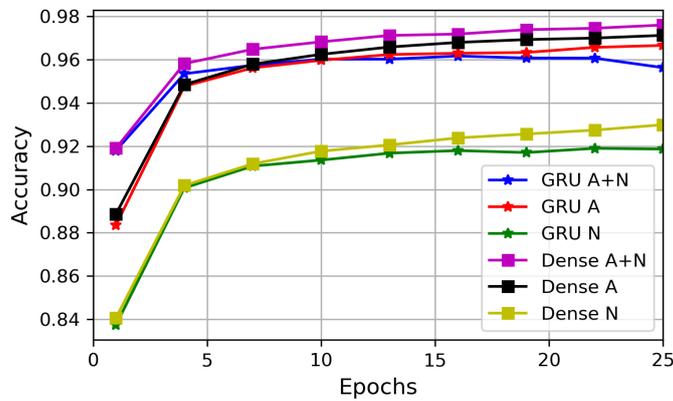
**Figure 3.** Typical WHISPER individual active (black curve) and natural (red dotted curve) electric field spectra measured in several plasma regimes: in solar wind (first panel), in magnetosheath (second panel) and in the plasmasphere (third panel). The frequency position of the plasma resonances are given by vertical dotted line: the electron plasma frequency  $f_{pe}$  (blue), the electron cyclotron frequency  $f_{ce}$  and its harmonics (green), the upper hybrid frequency  $f_{uh}$  (yellow) and Bernstein frequencies  $f_{qn}$  (magenta). All spectra have been expressed in dB and each of them normalized in amplitude between 0 and 1.



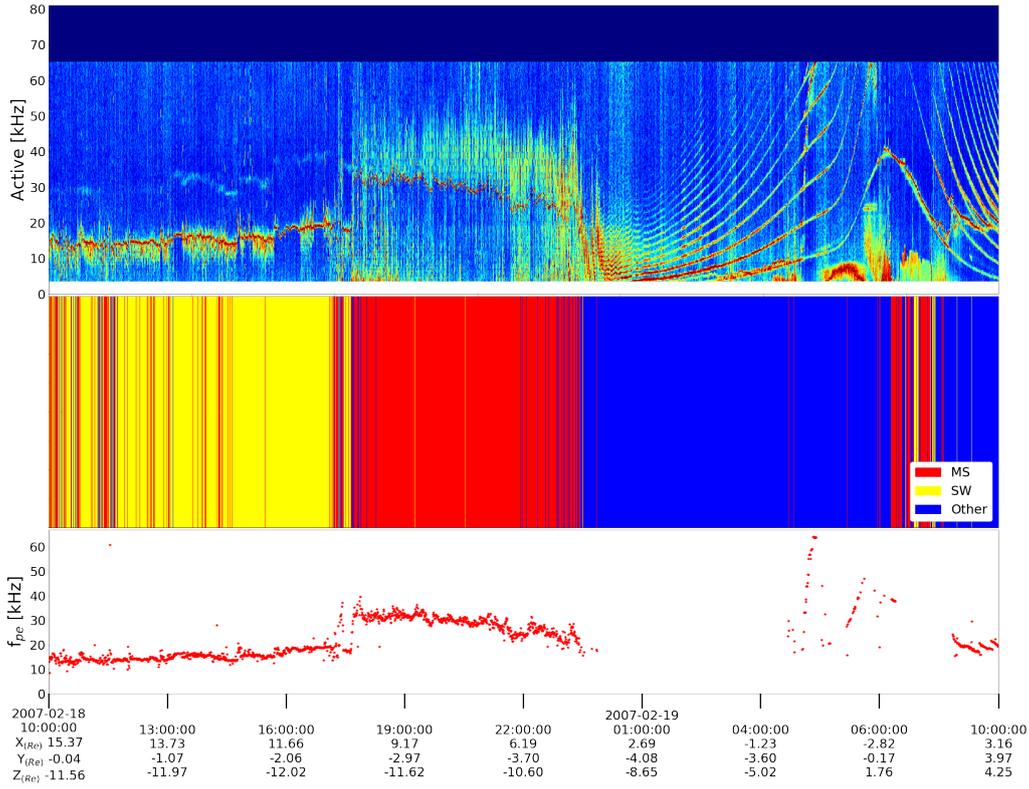
**Figure 4.** Architecture of an artificial neuron. The neuron takes  $m$  input values  $x_i$ , multiplies each input by a synaptic weight,  $w_{k,i}$ , and sums them along with a bias,  $b_k$ . An activation function  $\phi$  is then applied to the output which gives the final output  $y_k$  of the neuron.



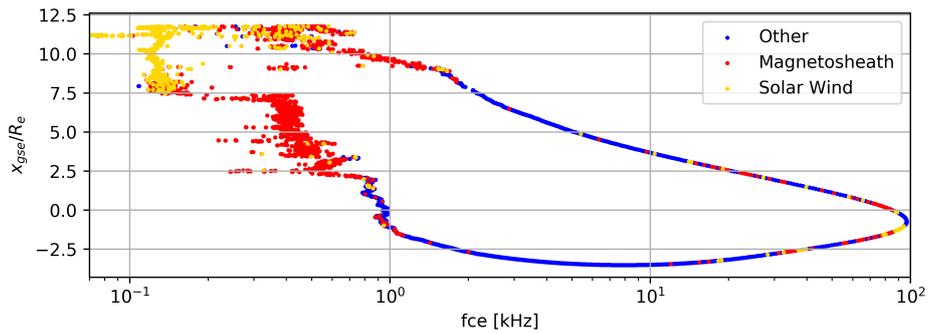
**Figure 5.** Illustration of the architecture of a multilayer feedforward (dense) neural network composed by several layers: an input layer  $X$ ,  $d$  hidden layers and an output layer  $y$ . The neural network is also defined by a combination of activation function  $f_i^{(j)}$ . The depth of the neural network is defined by the number of hidden layers. The width is defined by the number of neurons on each hidden layer.



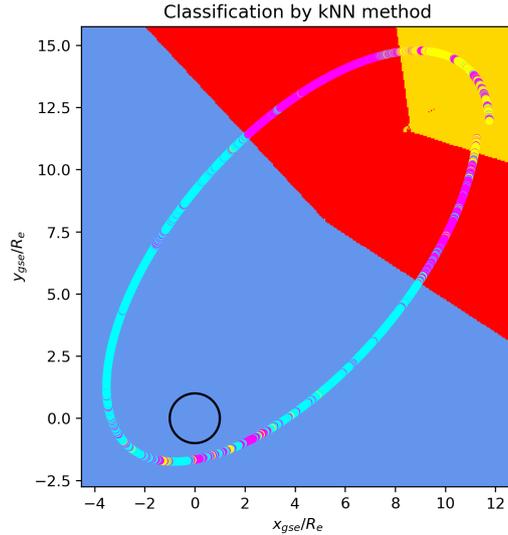
**Figure 6.** Accuracy of several neural network architectures used to predict the plasma region on the training dataset: (i) fully-connected (DENSE) neural network (squared color line) and, (ii) recurrent (GRU) neural network (asterisk color line), in the training dataset composed of (i) only active spectra (A), (ii) active and natural spectra (A+N) and, (iii) only the natural spectra (N).



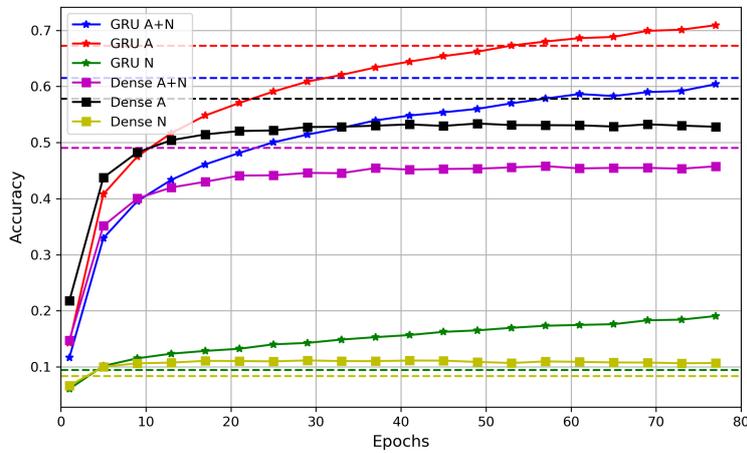
**Figure 7.** Prediction of the plasma region and electron plasma frequency  $f_{pe}$  for the case shown in Fig 2 for the WHISPER measurement on C3 (SAMBA) spacecraft from 18 Feb 2007 at 9:43 UT to 19 Feb 2007 at 09:54 UT. *First panel:* active WHISPER spectrogram expressed in dB. *Second panel:* Predicted plasma regime: Solar wind (SW, yellow), Magnetosheath (MS, red) and Other (blue). *Third panel:* Predicted electron plasma frequency  $f_{pe}$  expressed in kHz.



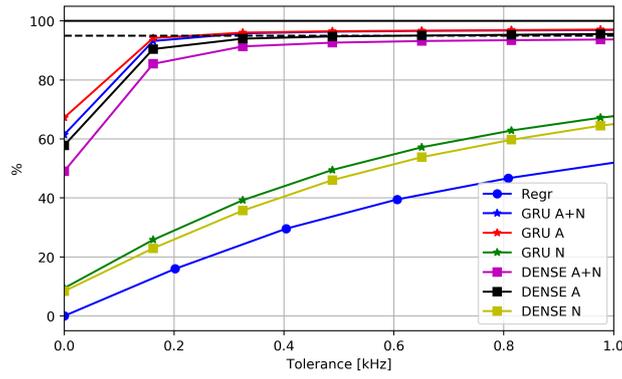
**Figure 8.** Prediction of the plasma region from 4 Jan 2013 at 00:00 UT to 6 Jan 2013 at 4:00 UT compared to the  $X_{gse}$ , normalized by Earth radius and the electron cyclotron frequency  $f_{ce}$ , expressed in kHz in logarithmic scale. The solar wind region is indicated by yellow points, the magnetosheath region by red points and the other regions by blue points.



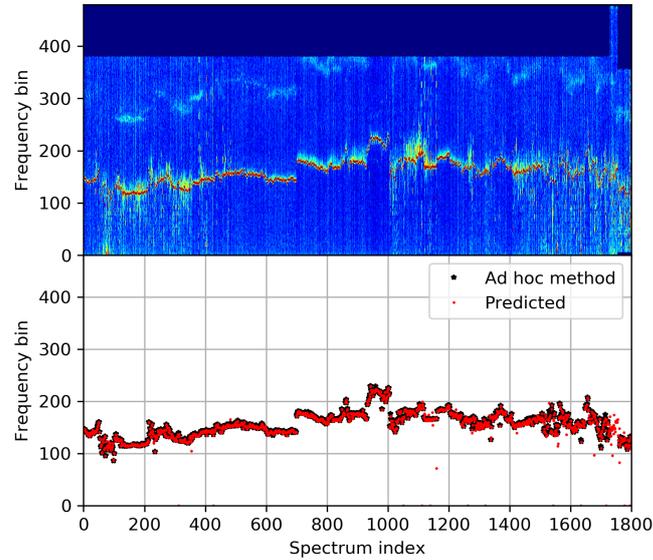
**Figure 9.** Classification of the plasma region on one complete orbit described by C1 (RUMBA) from 4 Jan 2013 at 00:00 UT to 6 Jan 2013 at 4:00 UT by  $k$ -nearest neighbors algorithm using the plasma regions predicted by the neural network model, in the  $XY_{gse}$  coordinates (normalized by Earth radius). The color background shows the predicted plasma regimes: free solar wind (yellow), magnetosheath (red) and other (blue).



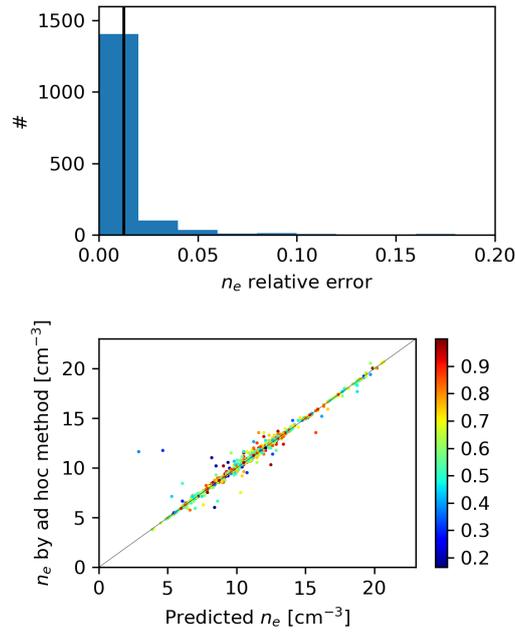
**Figure 10.** Accuracy of several neural network architectures to predict the thermal electron density on the training dataset: (i) fully-connected (DENSE) neural network (squared color line) and, (ii) recurrent (GRU) neural network (asterisk color line), in the training dataset composed of (i) only active spectra (A), (ii) active and natural spectra (A+N) and, (iii) only natural spectra (N) measured in the solar wind or the magnetosheath regime. Accuracies on the test dataset, at 80 epochs, are given by the horizontal dotted line with the same color code.



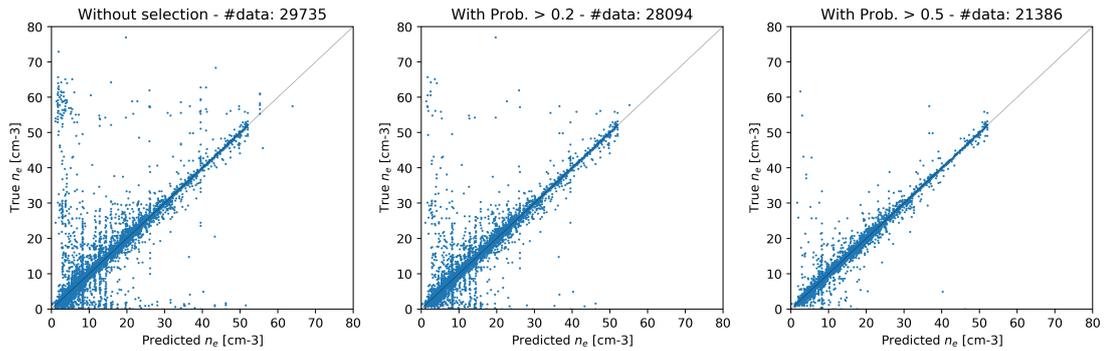
**Figure 11.** Percentage of well predicted electron plasma frequencies compared to a tolerance threshold, expressed in kHz, for several neural network architectures: recurrent network (GRU), dense (DENSE), or by a regression method. The black vertical dotted line shown the 95% accuracy threshold.



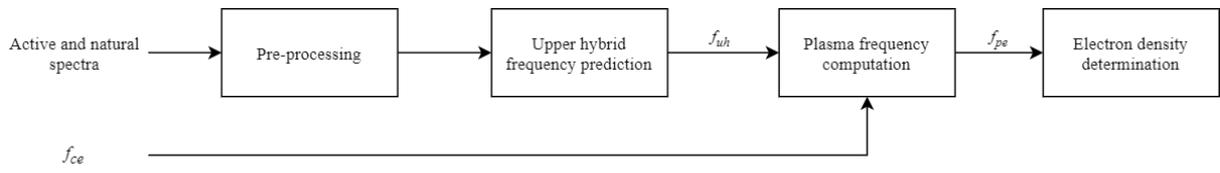
**Figure 12.** *Upper panel:* Active WHISPER spectrogram measured on C1 (RUMBA) on 13 Feb 2012 between 00:02 UT and 13:21 UT. *Lower panel:* Electron plasma frequency  $f_{pe}$ , expressed in frequency bins, given by *ad hoc* methods (black points) and predicted by neural network (red points). Note that the size of red points has been decreased for the sake of clarity.



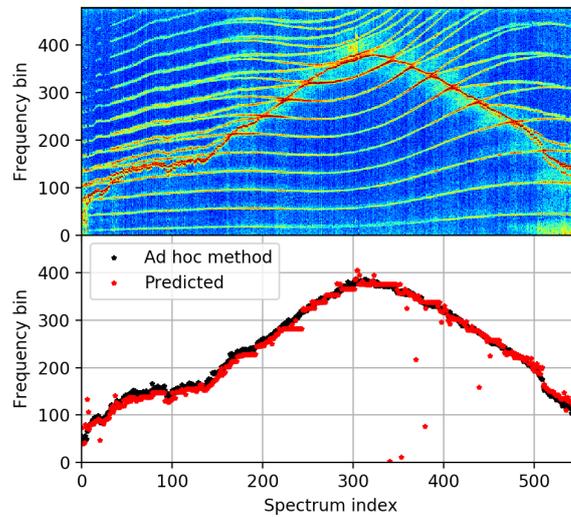
**Figure 13.** *Upper panel:* Relative error distribution of the predicted thermal electron density on the data shown in Figure 12. The mean relative error is given by the black vertical line. *Lower panel:* Scatter plot of the predicted thermal electron density versus the density given by *ad hoc* methods, expressed in  $\text{cm}^{-3}$ . The class probability is given by the colorbar (blue: min, red: max).



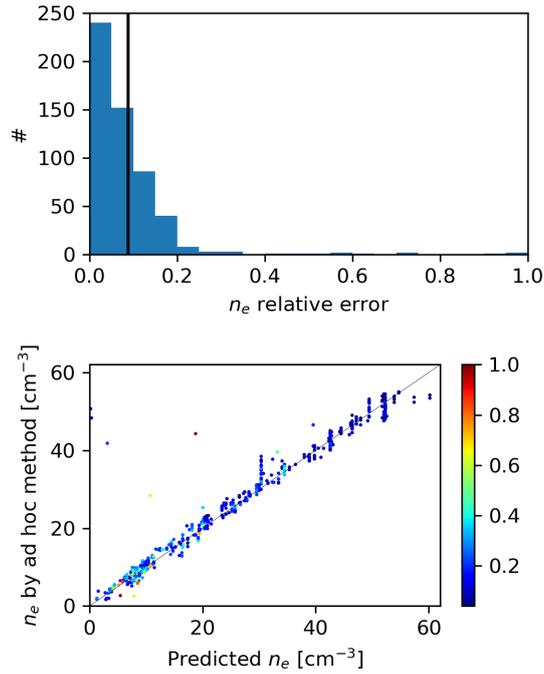
**Figure 14.** Scatter plots of the thermal electron density showing the predicted density versus the density detected by *ad hoc* methods. Both density are expressed in  $\text{cm}^{-3}$ . The data corresponds to the WHISPER measurements made onboard C1 spacecraft in 2012 (i) without threshold on the probability (*left panel*), (ii) with a threshold of 0.2 (*middle panel*) and, (iii) with a threshold of 0.5 (*right panel*).



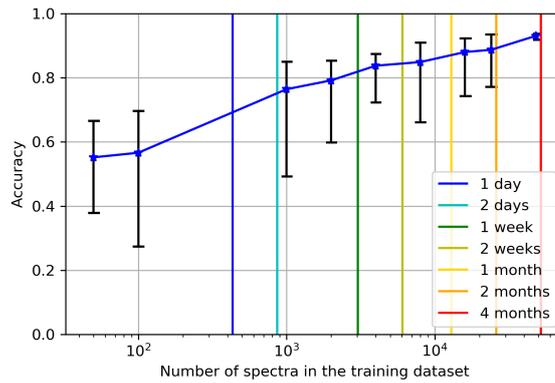
**Figure 15.** Illustration of the automatic pipeline used to predict the thermal electron density in the plasmasphere regime.



**Figure 16.** *Upper panel:* Active WHISPER spectrogram measured on C1 on 5 Aug 2002 between 17:00 and 20:40 UT. *Lower panel:* Electron plasma frequency  $f_{pe}$ , expressed in frequency bins, given by *ad hoc* methods (black points) and predicted by the neural network (red points).



**Figure 17.** *Upper panel:* Relative error distribution of the predicted thermal electron density on the data shown in Figure 16. The mean relative error is given by the black vertical line. *Lower panel:* Scatter plot of the predicted thermal electron density versus the density given by *ad hoc* methods, expressed in  $\text{cm}^{-3}$ . The class probability is given by the colorbar (blue: 0, red: 1).



**Figure 18.** Accuracy score of an automatic plasma region model compared to the amount of spectra in the training dataset in the AM<sup>2</sup>P experiment context. The error bar is given in black vertical bar. The time period corresponding to the AM<sup>2</sup>P measurement rate is given by vertical bars from 1 day (blue vertical bar) to 4 months (red vertical bar).