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Core-flow constraints on extreme archeomagnetic intensity changes



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ABSTRACT

Recent studies (Ben-Yosef et al., 2009; Shaar et al., 2011) propose extreme archeomagnetic intensity changes (termed spikes) in the range $\sim 4\text{--}5\text{ }\mu\text{T}/\text{year}$ c.a. 1000 BC in the Near East, around 40 to 50 times larger than values typical of the present-day. In order to investigate whether such extreme changes are consistent with a model of the source region of the magnetic field, namely the fluid flow at the surface of Earth's core, we construct upper bounds for instantaneous magnetic intensity change at an arbitrary site on the Earth's surface. These bounds are constrained by the amount of kinetic energy available to sustain the change, taken here to be a prescribed value for the root-mean-squared surface velocity of 13 km/yr as inferred from the current state of the core. Further, we focus attention on two end-members of optimised core surface flow structure: unrestricted and purely-toroidal. As the derivation of the bounds demands complete knowledge of the geomagnetic field at the core surface, we model the unknown field by means of a Monte Carlo approach, extending to high degree the CHAOS-4 (epoch 2010 AD) and CALS10k1.b (epoch 1000 BC) geomagnetic field models.

Using 2000 realisations for each family of stochastic field models, we find that optimised core flows are always large-scale and that they tend to generate a non-dipole, quadrupole-dominated secular variation at the Earth's surface. The dependence of the upper bounds as a function of site location reflects the large-scale structure of the intensity itself: stronger field permits more rapid change. For the site in the Near East, purely-toroidal flows have upper bounds of approximately $0.62 \pm 0.02\text{ }\mu\text{T}/\text{year}$, whereas unrestricted flows increase this bound to $1.20 \pm 0.02\text{ }\mu\text{T}/\text{year}$. We favour the former as more geophysically sound, on the account of a large body of previous results from core surface flow inversions and consistency with the existence of a stratified layer at the top of the core. Even if we allow for a generous threefold increase in the prescribed rms velocity (and a concomitant threefold increase in the bound), we conclude that the reported occurrences of extreme intensity changes as suggested in the Near East are not compatible with the commonly accepted structure of core-surface flow. However, it may be that an explanation for spikes lies beyond our current perception of core-dynamics and future work would be further motivated by seeking corroborative evidence of rapid intensity change from sites elsewhere on Earth's surface; we therefore also discuss the form that the secular variation would take in the case of simultaneous archeomagnetic spikes.

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1. Introduction

Over the last few years there has been considerable effort focused on studies of geomagnetic field intensity (F) variations over the past several millennia, mainly analysing the thermoremanent magnetization carried by archeological artifacts heated at the time of their manufacture or use. These studies led to the emergence of increasingly detailed composite intensity variation curves for European regions (e.g. De Marco et al., 2008; Kovacheva et al., 2009; Gómez-Paccard et al., 2012; Genevey et al., 2013; Hervé et al.,

2013), as well as for the Middle East, where many opportunities of sampling recently allowed the recovery of the geomagnetic intensity fluctuations over the past millennia BC (e.g., Thébault and Gallet, 2010; Gallet et al., in press). The results highlighted a series of regional centennial-scale intensity maxima. In particular, Genevey et al. (2009, 2013) showed the existence in Western Europe of three intensity peaks during the last millennium (during the 12th century, the second half of the fourteenth century and around 1600 AD) that the reconstructed time-varying global archeomagnetic field models are unable to capture, because of their still limited temporal resolution (Korte et al., 2011; Licht et al., 2013). The peaks observed in Western Europe are associated with intensity variation rates of $dF/dt \sim 5\text{--}10\text{ }\mu\text{T}$ per century (or 50–100 nT/yr), comparable to variation rates presently

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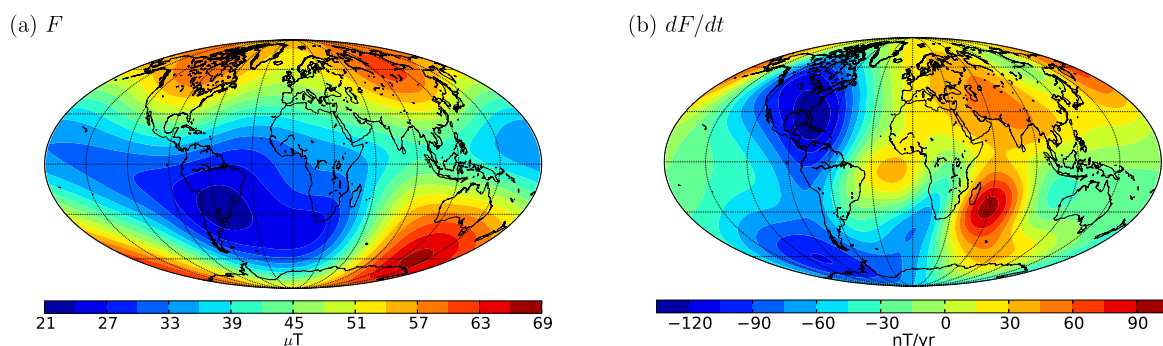


Fig. 1. Contours of (a) F and (b) dF/dt from CHAOS-4 at epoch 2010 to degree 13 on the Earth's surface. The maximum rate of change of intensity is currently ~ 100 nT/yr.

prevailing in many regions (as shown in Fig. 1). This rate from Genevey et al. (2009, 2013) is determined from an averaged curve and the existence of episodes with larger intensity variation rates cannot be excluded. Such a possibility was proposed by Gómez-Paccard et al. (2012) for Western Europe from rough comparisons between pairs of intensity data, although the derived rates did not take into account uncertainties in the intensity or age. These authors suggested variation rates larger than ~ 10 μT per century (100 nT/yr) during the Medieval era with values up to 50–80 μT per century (500–800 nT/yr) – such high rates obviously not persisting for the entire period.¹ While variations close to ~ 100 nT/yr presently exist only in the Indian ocean and the Americas, values larger than ~ 150 nT/yr appear very unusual.

The best evidence for very rapid intensity variations at a rate much larger than ~ 100 nT/yr was most probably provided by archeointensity data obtained from the Near East. Recent archeomagnetic studies conducted in Anatolian, Syrian and Levantine regions made it possible to assemble the main intensity variation patterns over the last three millennia BC: see Fig. 2(a); (Genevey et al., 2003; Gallet and Le Goff, 2006; Gallet et al., 2006, 2008, in press; Gallet and Al-Maqdissi, 2010; Ben-Yosef et al., 2008, 2009; Shaar et al., 2011; Ertepinar et al., 2012). These changes are marked by several relative intensity maxima, among which three occurred during the Bronze Age (~ 3000 – 1200 BC), with variation rates again of ~ 50 – 100 nT/yr (e.g. Thébault and Gallet, 2010; Gallet et al., in press). But the latter appear very minor compared to the rates reported for the very beginning of the first millennium BC (beginning of the Iron Age; Fig. 2(b)). These data were principally obtained from paleomagnetic analyses of metallurgical residues (slag) in the Levant (Ben-Yosef et al., 2008, 2009; Shaar et al., 2011), and more recently from baked-clay fragments collected from a kiln discovered at Arslantepe (Turkey; Ertepinar et al., 2012). Furthermore, a selection of the available data over a wider geographic area (see Fig. 1 in Shaar et al., 2011, with data selected between 20° N and 50° N in latitude and between 10° E and 50° E in longitude) does not change the main message conveyed by Fig. 2: the beginning of the first millennium BC was characterised in the Near East (and elsewhere) by the highest geomagnetic field intensities ever observed during the Holocene and beyond. There was a suggestion of this phenomenon in the analysis of global and regional compilations of geomagnetic field intensity data (e.g. Yang et al., 2000; Genevey et al., 2008; Knudsen et al., 2008), but not with such a high intensity level. The key information obtained by Ben-Yosef et al. (2009) and Shaar et al. (2011) is that these extreme geomagnetic intensities, larger than 100 μT , were reached in a very short time in-

terval (~ 10 – 20 years), which led to the concept of a “geomagnetic intensity spike” (Ben-Yosef et al., 2009). Two such events have been proposed so far, at ~ 980 BC and ~ 890 BC (Fig. 2(b); from Fig. 7 by Shaar et al., 2011). Fig. 2(b) shows that regional intensity variations as extreme as ~ 30 μT (Shaar et al., 2011, considering solely the data from archeological site Timna-30), even possibly ~ 50 μT (Ben-Yosef et al., 2009, further considering the data from site Khirbat en-Nahas, abbreviated in what follows to “KEN”), beyond the previously assumed intensity level (~ 75 μT) would have occurred in approximately a decade. Figs. 2(c) and 2(d) show smooth fits² through the data (orange curve: Timna-30 and KEN datasets, red: Timna-30 only); we present separate analyses as only the intensity recorded at Timna-30 is independently verified by a measurement of comparable magnitude nearby (Ertepinar et al., 2012). In both cases Fig. 2(d) shows similar rates of change of intensity of up to 4–5 μT /yr during the two proposed spike-events.

These archeomagnetic spikes, which have not been found elsewhere, in particular in eastern Europe (for instance neither in the Bulgarian nor Greek data sets; De Marco et al., 2008; Kovacheva et al., 2009; Tema and Kondopoulou, 2011), pose a number of questions, in particular on the precise geographical extension and time-scale of the spike events, on the relative contribution of the dipolar and non-dipolar field components to these features, as well as on the reliability of the extreme intensity data, although the latter have met strict quality criteria, or on the dating precision of these data. The kiln studied by Ertepinar et al. (2012) at Arslantepe yielded a spike-like intensity value (~ 100 μT), thereby confirming the extremely high intensity level during the early Iron Age. However, Ertepinar et al. (2012) emphasized the fact that the dating uncertainties for this kiln are 300 yr. It may be that the date at which the oven was fired happened to coincide with the proposed 20–30 yr spike, although this may be regarded as too much of a coincidence. Should the dates not coincide, this would favour not a spike but a centennial-scale intensity peak, albeit extreme, like other maxima so far observed in the Near East and in Europe.

Considering the importance of intensity spikes, and more generally of episodes characterised by rapid intensity changes for deciphering the geomagnetic field behaviour during the Holocene, we decided in the present study to approach the topic from a different perspective: that of asking what intensity variation rates in the

² We generated 100 realisations (thin blue lines) of data bootstrapped from Shaar et al. (2011) and Ben-Yosef et al. (2009), based on a uniform distribution of ages (within the bounds given) and normally distributed intensity (with the mean and standard deviation as given). We fitted uniformly-weighted cubic splines through the data using the Matlab routine *SPAPS*, where the tradeoff between the fit to the data and the smoothness was chosen so that the maximum $|dF/dt|$ was at most 10 $\mu\text{T}/\text{yr}$, a factor of 100 higher than typical archeomagnetic intensity change. The solid orange line shows the average spline, the red shows the equivalent average restricted to the Timna-30 dataset.

¹ Although we have reported intensity variation rates expressed per century to be consistent with the cited literature, in view of the short time-scales under consideration in this study, hereafter we will only refer to rates expressed per year.

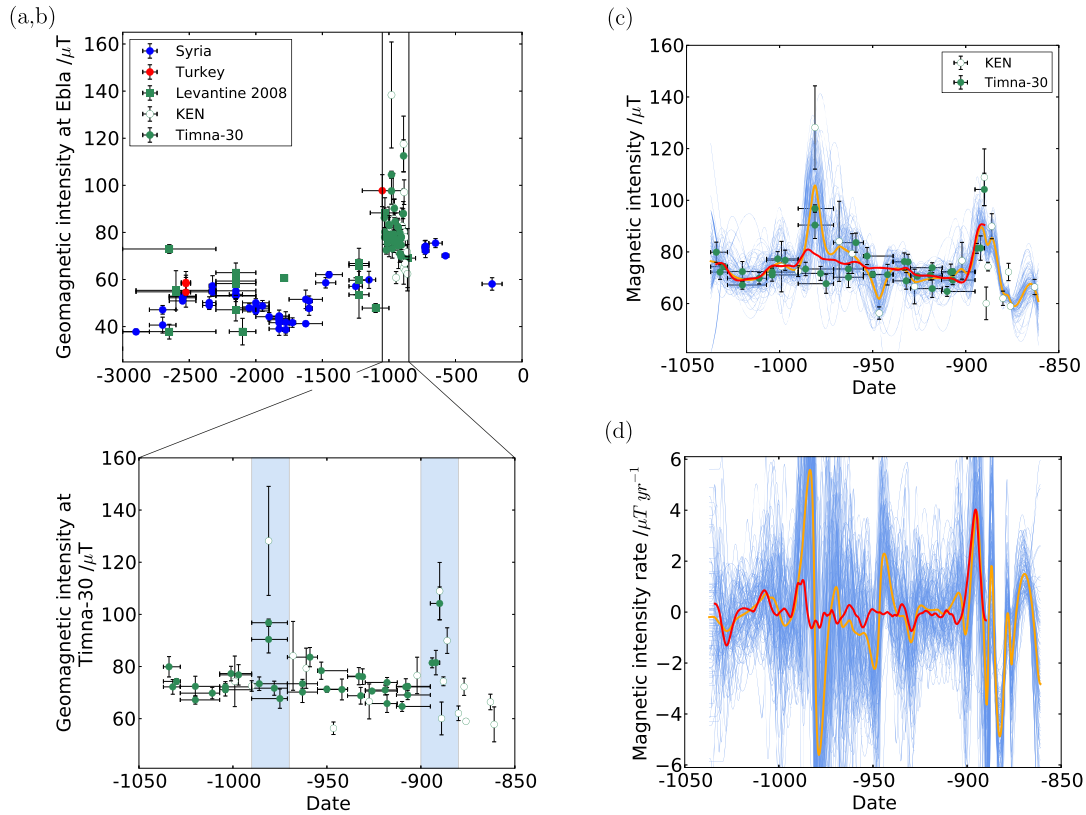


Fig. 2. Centennial to millennial-scale geomagnetic field intensity variations in the Near East as recovered from recent archeointensity data sets. (a) Temporal distribution of archeointensity data covering the last three millennia BC obtained from Turkey (red circles, [Ertepinar et al., 2012](#)), Syria (blue circles, [Genevey et al., 2003](#); [Gallet and Le Goff, 2006](#); [Gallet et al., 2006, 2008, in press](#); [Gallet and Al-Maqdissi, 2010](#)) and from the Levantine region (green squares, [Ben-Yosef et al., 2008](#); green open circles, [Ben-Yosef et al., 2009](#) with age calibration according to [Shaar et al., 2011](#); green solid circles, [Shaar et al., 2011](#)). All data were reduced to the latitude of Ebla/Tell Mardikh ($\sim 35.8^\circ$ N). (b) Composite high resolution geomagnetic field intensity record between 1050 and 850 BC reconstructed by [Shaar et al. \(2011\)](#) from archeointensity results obtained from two early Iron Age archeological sites, Khirbat en-Nahas (KEN) (open circles, [Ben-Yosef et al., 2009](#)) and Timna-30 (closed circles, [Shaar et al., 2011](#)). All data were reduced to the latitude of site Timna-30 ($\sim 29.8^\circ$ N). The age calibration is provided by ^{14}C dates and stratigraphic constraints. Two spikes in geomagnetic intensity were proposed by [Shaar et al. \(2011\)](#) around 980 BC and 890 BC (blue shaded zones). (c) as (b) but over-plotted with cubic-spline fits to 100 realisations of this dataset (thin blue lines), each constrained by a maximum intensity change of $10 \mu\text{T}/\text{yr}$; orange shows the average curve, the red is the equivalent average restricted to the Timna-30 dataset. (d) The values of dF/dt for each curve in (c) as a function of time. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

Near East (specifically at the site Timna-30 used in [Shaar et al., 2011](#)) are consistent with the process of magnetic field generation in Earth's core.

We adopt an optimisation approach, and ask, “what is the largest rate of change of intensity, dF/dt , at a site on the Earth's surface consistent with a reasonable description of the physics of magnetic field generation?”. The physics to which we refer is that of magnetic induction on the core–mantle–boundary (CMB), the principle ingredient of which on short time-scales is the action of the core-flow, advecting and shearing magnetic field-lines. We constrain the flow amplitude to be broadly consistent with our current understanding of the geodynamo, which we take to be the condition that the root-mean-squared flow speed on the CMB is $13 \text{ km}/\text{yr}$ ([Holme, 2007](#)). Such a constraint is vital since, as faster flows generate more rapid secular variation, the maximum value of dF/dt would be formally unbounded if the flow was unconstrained (i.e. allowed to become infinitely large). Subject to this rms constraint we optimise over all possible configurations of flow on the CMB, encompassing every possible state of the geodynamo consistent with this assumption. Within this well-defined framework, the upper bounds on dF/dt will allow us to critically assess the likelihood of the suggested extreme intensity changes.

We remark briefly that an alternative method is to run geodynamo models, recording the intensity changes with time and noting the largest and fastest variations. These models (see e.g. [Christensen and Wicht, 2007](#), for a review) are now arguably able

to reproduce the main features of the observed geomagnetic field, provided the time-scales of rotation, advection by fluid flow, and magnetic diffusion, are in approximate geophysical proportions ([Christensen et al., 2010](#)). However, although the models are expected to provide a reasonably good approximation of the secular variation on time-scales of the order of a century and longer, they cannot resolve the interannual to decadal time-scales, the very features of interest in this study (consult [Finlay et al., 2010](#), for further reading on this topic).

A full description of our method is laid out in Section 2, following which we provide a pedagogical example in Section 3. In Section 4 we describe our Monte Carlo models of magnetic field, and in Section 5 we present our main results with concluding remarks in Section 6. We end with a discussion in Section 7.

2. Methodology

We consider an observation site S on the Earth's surface (radius $a = 6371 \text{ km}$), at colatitude and longitude (θ_s, ϕ_s) . Changes in this magnetic field structure everywhere outside the core (assuming an electrically insulating mantle), including at S , are slaved to changes in the magnetic field on the CMB ([Jackson and Finlay, 2007](#)). Thus, for the purposes of constructing upper bounds we do not require a complete model of magnetic field generation inside the core, but only a description of its changes on the edge of the region where the geodynamo operates.

The optimisation methodology that we describe below requires complete knowledge of the magnetic field, \mathbf{B} , on the CMB: this point is discussed further within the framework of Monte Carlo methods in Section 4. Further, we neglect radial diffusion of the magnetic field on the CMB as it would also require knowledge of gradients of \mathbf{B} which are observationally unconstrained; we discuss this limitation in Section 7. We begin by describing the method in the limit of frozen-flux (Roberts and Scott, 1965; Jackson and Finlay, 2007), in which magnetic diffusion is neglected on the CMB; adding in horizontal diffusion is then a simple extension.

At S , the intensity is given by

$$F = |\mathbf{B}| = \sqrt{B_r^2 + B_\theta^2 + B_\phi^2}, \quad (1)$$

so that

$$\frac{dF}{dt} = \frac{1}{F} \left(B_r \frac{dB_r}{dt} + B_\theta \frac{dB_\theta}{dt} + B_\phi \frac{dB_\phi}{dt} \right) = \frac{1}{F} \left(\mathbf{B} \cdot \frac{d\mathbf{B}}{dt} \right). \quad (2)$$

Ignoring diffusion, the radial-component of the instantaneous rate of change of magnetic field on the CMB ($r = c$, $c = 3485$ km) is

$$\frac{\partial B_r}{\partial t} = -\nabla_H \cdot (\mathbf{u}_H B_r), \quad (3)$$

where \mathbf{u}_H denotes the horizontal flow and $\nabla_H = \nabla - \hat{\mathbf{r}} \frac{\partial}{\partial r}$ is the horizontal part of the gradient operator. Modelling \mathbf{B} and hence $\partial \mathbf{B} / \partial t$ as a potential field in the mantle $r \geq c$, we adopt the usual representation

$$\frac{\partial \mathbf{B}}{\partial t} = -a \nabla \sum_{l,m} \left(\frac{a}{r} \right)^{l+1} Y_l^m(\theta, \phi) \dot{\beta}_l^m \quad (4)$$

where $\dot{\beta}_l^m = (\dot{g}_l^m, \dot{h}_l^m)$ is the vector of Gauss coefficients of the secular variation, and Y_l^m are Schmidt quasi-normalised spherical harmonics. This equation is simply the description of the upwards-continuation of the magnetic field (or rather its rate of change) from $r = c$ to $r = a$. By (4) and (3), each $\dot{\beta}_l^m$ depends linearly on \mathbf{u} , from which it follows that all three components of $\partial \mathbf{B} / \partial t$ at $r = a$, and indeed $\frac{dF}{dt}$, depend linearly on \mathbf{u} at $r = c$. The relation is trivially also homogeneous as if $\mathbf{u} = \mathbf{0}$ there can be no secular variation.

We can exploit this elementary relation to express dF/dt as a linear homogeneous function of the flow,

$$\frac{dF}{dt} = \mathbf{G}^T \mathbf{q}, \quad (5)$$

for some column vector \mathbf{G} (which needs to be computed), and where the flow is written as an expansion over a set of modes, \mathbf{u}_k , whose coefficients are stored in the vector \mathbf{q} :

$$\mathbf{u} = \sum_k q_k \mathbf{u}_k. \quad (6)$$

In simple terms, element \mathbf{G}_k gives the contribution to the rate of change of intensity at S from flow mode \mathbf{u}_k , and encapsulates information about the background field, the coordinates of S and also the structure of the flow mode. All flows we will consider are divergence-free, and within this class we will consider the most general set which we term *unrestricted*, comprised of both toroidal and poloidal modes, respectively

$$\nabla \times t_l^m Y_l^m(\theta, \phi) \mathbf{r}, \quad \nabla_H [r s_l^m Y_l^m(\theta, \phi)], \quad (7)$$

up to a fixed spherical harmonic degree L_U , where \mathbf{u}_k is defined by the vector of coefficients (t_l^m, s_l^m) of zeros except for a one in the

k th position. We will also consider flows which are also purely-toroidal, describing flows that are everywhere horizontal.

For a given site location and prescribed magnetic field (to degree L_B), the vector \mathbf{G} is then straightforward to assemble, one element at a time. Each mode of flow was taken in sequence and we calculated (i) the spherical harmonic spectrum to degree $L_B + L_U$ of $\partial B_r / \partial t$ at $r = c$ using a standard transform methodology based on Gauss–Legendre quadrature and the fast-Fourier transform, and then (ii) using (4) the contribution to dF/dt at S . All elements of \mathbf{G} are exact to machine precision.

The statement of the problem we need to solve then is rather succinct: maximise $\mathbf{G}^T \mathbf{q}$ subject to constraints on the flow. One feature of core-flows on which inverse studies broadly agree is the root-mean-squared (rms) velocity:

$$T_0 = \sqrt{\frac{1}{4\pi} \int_{r=c} |\mathbf{u}|^2 d\Omega} \quad (8)$$

where $d\Omega$ is the element of solid angle, for which we take $T_0 = 13$ km/yr (Holme, 2007) as a (typical) target value. In our representation of flow, this constraint may be written

$$\mathbf{q}^T E \mathbf{q} = \frac{1}{4\pi} \sum l(l+1) ([t_l^m]^2 + [s_l^m]^2) \frac{4\pi}{2l+1} = T_0^2 \quad (9)$$

where E is a diagonal matrix with elements $l(l+1)(2l+1)^{-1}$. Expressing the rms constraint using a Lagrange multiplier λ , we therefore seek the constrained maximum

$$\left. \frac{dF}{dt} \right|_{\max} = \max_{\mathbf{q}} [\mathbf{G}^T \mathbf{q} - \lambda (\mathbf{q}^T E \mathbf{q} - T_0^2)]. \quad (10)$$

At a local maximum, the gradient with respect to each component of the vector \mathbf{q} is zero, giving

$$\mathbf{G} - 2\lambda E \mathbf{q} = \mathbf{0}, \quad (11)$$

and so

$$\mathbf{q} = \frac{1}{2\lambda} E^{-1} \mathbf{G}, \quad (12)$$

where $\lambda > 0$ is found by scaling the flow to the target rms. Note that changing the sign of λ corresponds to the flow $-\mathbf{u}$ which minimises (rather than maximises) dF/dt . Finally, it is worth remarking that although the intensity depends nonlinearly on \mathbf{B} , here we only need optimise a linear quantity subject to a quadratic constraint, whose (unique) solution is given above. More complex constraints on the flow may not lead to such a straightforward solution.

The inclusion of magnetic diffusion is a simple extension of the above methodology. Eq. (3) now becomes

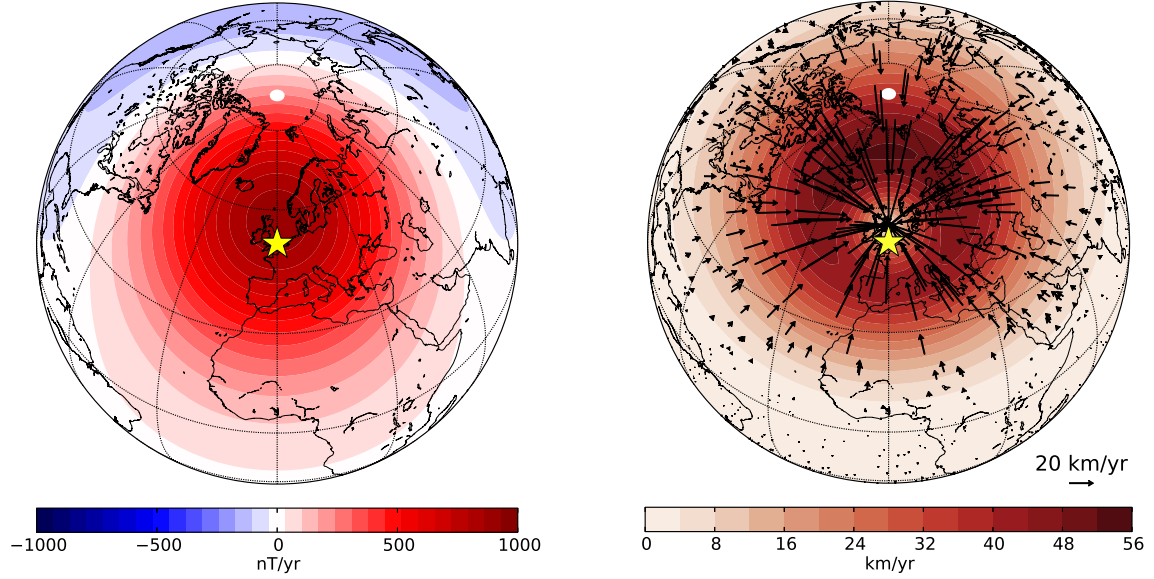
$$\frac{\partial B_r}{\partial t} = -\nabla_H \cdot (\mathbf{u}_H B_r) + \eta \hat{\mathbf{r}} \cdot \nabla^2 \mathbf{B}, \quad (13)$$

in which η denotes the magnetic diffusivity and $\hat{\mathbf{r}}$ the unit position vector. The last term is independent of the flow and can be split into two parts, stemming from either horizontal or radial diffusion of the magnetic field. We consider only horizontal diffusion, which, at $r = c$, may be written

$$\nabla_H^2 B_r = - \sum_{l,m} \frac{l(l+1)}{c^2} [B_r]_{(l,m)} Y_l^m \quad (14)$$

where $[B_r]_{(l,m)}$ denotes the Y_l^m component of B_r . Since \mathbf{B} is assumed known, (14) provides an additional term, independent of \mathbf{u} , to (10) and has no bearing on the optimising flow. We take $\eta = 0.7$ m²/s, based on a core electrical conductivity of

(a) Unrestricted flows



(b) Purely-toroidal flows

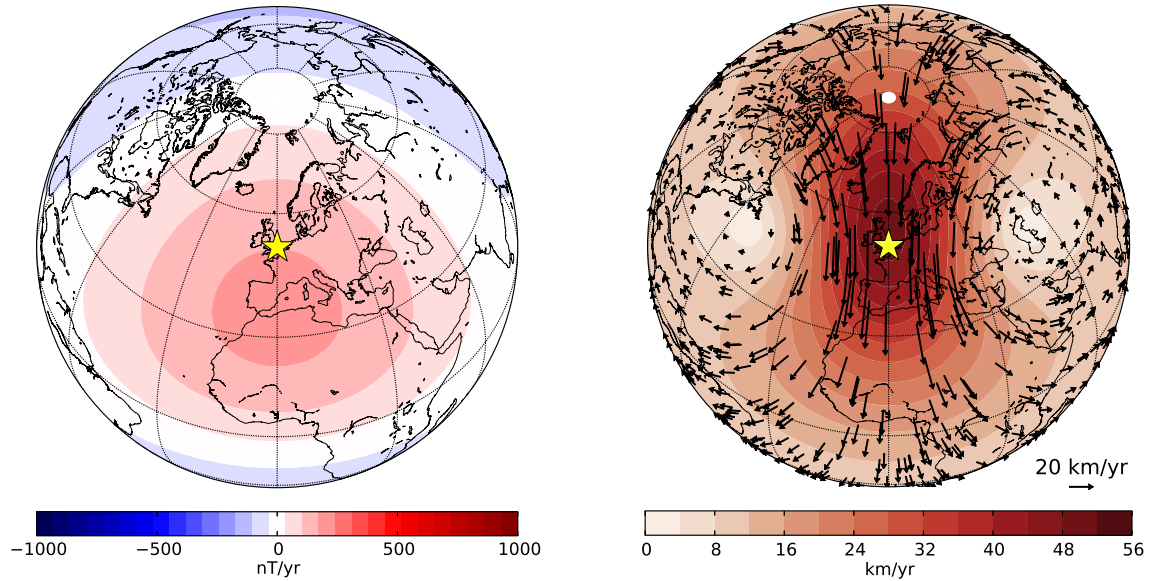


Fig. 3. Assuming a geomagnetic field of an axial dipole with $g_1^0 = -30000$ nT, contours of dF/dt maximised for an observation site at 52° N, 0° E (labelled by the star) with the optimal flow pattern for (a) unrestricted flows (b) and purely-toroidal flows. Each flow is normalised to have a rms value of 13 km/yr; the local flow speed is shown both by the coloured contours and the arrow size relative to the scale shown.

$\sigma = 1.1 \times 10^6 \Omega^{-1} \text{ m}^{-1}$ (Pozzo et al., 2013). This value, the smallest such compatible with current theory, provides us with a highest estimate of the upper bounds and is discussed further in Section 4.2.

Finally, it is worth remarking that the geometric attenuation of the magnetic field through the mantle, far from being an obstacle in our analysis, actually makes the optimisation procedure as described above. A theoretical observation site on $r = c$ would have an optimising flow, and associated secular variation, non-zero only at this point and consequently infinite in size. In contrast, sites on the Earth's surface are sensitive primarily to large-scale secular variation (since the smallest scales are strongly attenuated in the mantle), which we find generated by large-scale flows. Thus we anticipate (and find) that the optimisation procedure is well-posed, the optima of dF/dt are finite and the resulting flows large-scale.

3. A pedagogical example: optimal change in an axial dipole field

We now illustrate the analysis as described above by considering the idealised example of a purely axial dipolar geomagnetic field that is described by the Gauss coefficient $g_1^0 = -30000$ nT. The flow is expanded to degree $L_U = 25$, which ensures convergence.

Consider an observation point in London (latitude 52° N, longitude 0°), at which we optimise dF/dt . Fig. 3 shows a contour map of dF/dt on the Earth's surface along with the optimising flow at the core surface $r = c$, for both (a) unrestricted and (b) purely-toroidal flow cases.

A striking feature of the plots is the localisation of dF/dt , focused into quasi-circular contours, taking maximum values of (a) 887 nT/yr and (b) 171 nT/yr at the observation site. Away from the observation site, much of the Earth's surface has small and

negative values of dF/dt showing that the rapid increase in intensity at S comes at the expense of slower decreases elsewhere. Another point of note is that the maximum value of dF/dt does not coincide with the site location. This is not an error, but simply reflects the fact that with the flow optimised for site S , the (different) structure of the magnetic field elsewhere is such that it produces a greater value of dF/dt than at S . In (a), the background field is stronger at higher latitudes, which explains why the maximum of dF/dt is shifted to the north of London. However, in (b) it is the horizontal gradient of B_r that is important: $dF/dt = -\mathbf{u}_H \cdot \nabla_H B_r$ (from Eq. (3)); since the largest horizontal gradients of B_r are at the equator, the high is to the south of London. The values of the upper bounds themselves evaluated at London are really only of pedagogical value, as it turns out that the upper bounds change as we introduce more complex field structures. However, one persistent feature is the relative disparity of the optimum bounds from the two types of flow. Since purely-toroidal flows are a subset of the unrestricted flows, it follows that their associated maxima must be smaller. Yet, this simple statement tells us nothing about the actual difference: here, they vary by a factor of 5; as we will see later, in the more general case a factor of 2 is more typical.

The structure of the flows is very instructive, and illustrative of the more general case. Both flows, and their associated secular variation, are large-scale (see also supplementary Figs. 11(a–b)). The unrestricted flow is dominated by its high horizontal-convergence very close to, but not coincident with, the radial-projection of the observation site. Horizontally-convergent flow (with an associated down-welling) is a very efficient method of concentrating and amplifying magnetic flux, and thus results in a rapid change of intensity. By contrast, because it is everywhere horizontal the purely-toroidal case has to rely on a much less optimal method of creating intensity changes, that of advection of the poloidal field (in this case, due south beneath S , by means of a pair of counter-rotating vortices). Lastly, it is interesting that although both flows have rms values of 13 km/yr, they have maximum speeds of approximately 50 km/yr. Although in line with estimates of the maximum speed in the core (Finlay and Amit, 2011), for more complex magnetic fields the associated optimising flows are also more spatially complex and have greater maximum speeds than we see here. The results presented here contain horizontal diffusion, although its contribution to dF/dt turns out to be very small: -0.18 nT/yr, around 0.1% of the total.

4. Stochastic magnetic fields

4.1. Magnetic models

To address the question of intensity variability at the beginning of the first millennium BC, our framework formally requires complete knowledge of the main geomagnetic field at that epoch. This information is unfortunately not available, mainly because of the crustal concealing of the small-scale core field (approximately from harmonic degree 14 and beyond). In addition, our ability to describe accurately the theoretically visible large-scale core field at that epoch is further hampered by the poor geographical and temporal distribution of the existing data sets for this period (e.g., Donadini et al., 2009; Korte et al., 2011; Licht et al., 2013). We therefore study two types of model that attempt to characterise the structure of the field. Model ST_CALS (STochastic CALS10k1.b) is based upon the CALS10k1.b model (Korte et al., 2011), which provides a set of spherical harmonic coefficients to degree 10 (with standard deviations) over the entire Holocene. We use only the more robustly determined coefficients up to degree 4 and extend to higher degree using a stochastic extrapolation technique as described below. The second model, ST_CHAOS, is based upon the

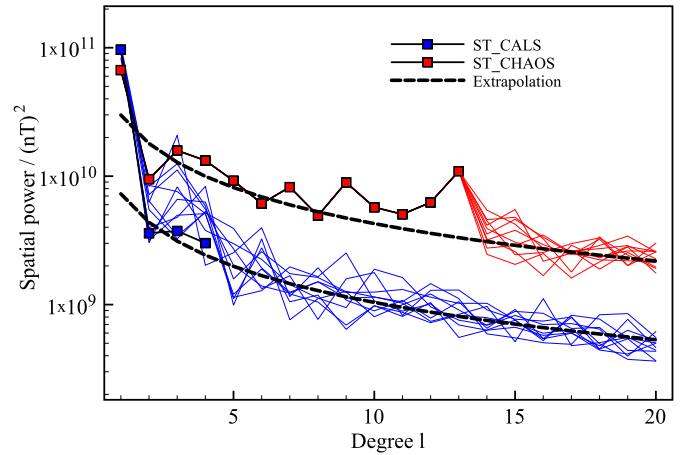


Fig. 4. A comparison of 10 realisations of the Mauersberger–Lowes energy spectrum on the CMB as a function of degree l , for the two models ST_CHAOS and ST_CALS. The extrapolation is based on the expected spectra of the form $A(2l+1)^{-1}$.

geomagnetic model CHAOS-4 (Olsen et al., 2010), providing the magnetic field at epoch 2010 (see Fig. 1). While the magnetic field has undoubtedly changed in the intervening 3010 years, the basic structure is much the same: a dominant dipole and high-latitude flux lobes (Korte et al., 2011). We exploit the fact that CHAOS-4 is known to a much greater accuracy since it is constructed from high-quality satellite data of almost uniform coverage, and use it as a tightly constrained proxy for the magnetic field in 1000 BC. In this model, we assume that the magnetic field is given exactly to degree 13, above which crustal contamination forces us to adopt a stochastic extrapolation.

We assume that the unknown Gauss coefficients of degrees 5 to L_B in ST_CALS and degrees 14 to L_B in ST_CHAOS are distributed normally with mean zero and degree-dependent standard deviation σ_l . Our treatment of the low degrees is model-dependent: in ST_CHAOS, we assume that degrees 1–13 are known exactly, whereas in ST_CALS degrees 1–4 are treated as random variables, with mean and standard deviation taken from CALS10k1.b. Choosing σ_l appropriately, and by generating pseudo-random values from this distribution, we then are able to construct multiple Monte Carlo realisations of the magnetic field. We statistically analyse all the optimised solutions, each calculated using a single realisation. We determine σ_l by using the fact that the Mauersberger–Lowes energy spectrum (Backus et al., 1996) of the magnetic field, where R_l denotes the contribution from degree l to $\int \mathbf{B}^2 d\Omega$ over the CMB, has the expected value

$$E(R_l) = E \left[\left(\frac{a}{c} \right)^{2l+4} (l+1) \sum_m [(g_l^m)^2 + (h_l^m)^2] \right] \\ = \left(\frac{a}{c} \right)^{2l+4} (l+1)(2l+1)\sigma_l^2. \quad (15)$$

We then assume that this follows the profile $A(2l+1)^{-1}$ (McLeod, 1996), where A is calculated by a least-squares fit to the non-dipolar spectra of the base models (i.e. to the spectrum of degrees 2–13 for ST_CHAOS and the expected spectrum for degrees 2–4 for ST_CALS). Fig. 4 illustrates the magnetic-energy spectra of ten realisations from each family of stochastic models. A significant point of note is that although the dipole component is stronger in CALS10k1.b than in CHAOS-4, degrees 2–4 are weaker, a possible consequence of the regularization imposed on the archeomagnetic field models, owing to the limited spatial coverage of the data sets. The lower energy available in the non-dipole spectrum has an important influence on the maximum dF/dt , as we shall see below.

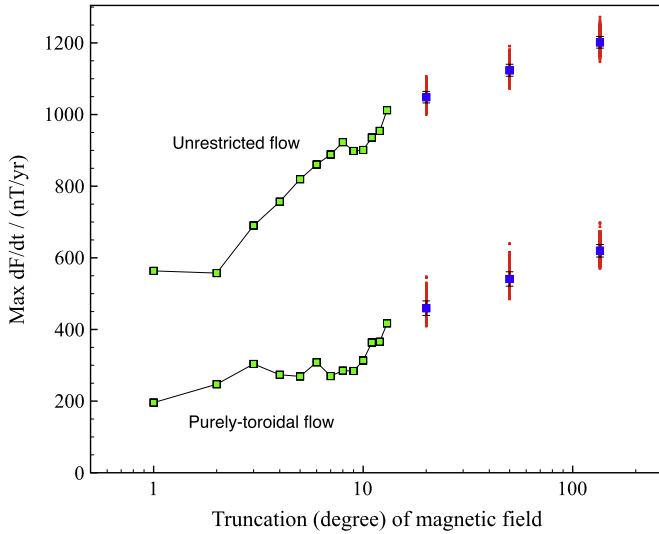


Fig. 5. Dependence of upper bounds (at Timna-30) on the truncation of the magnetic field extrapolated from ST_CHAOS. In green are shown the first 13 (unique) bounds derived from the (assumed exact) CHAOS-4 geomagnetic field model to degree 13; 2000 Monte Carlo realisations (red dots) are shown for magnetic fields stochastically extrapolated to degrees 20, 50 and 135. In each case, the mean and unbiased standard deviation are marked by the blue square with black error bars. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

4.2. Truncation

In both stochastic models for the magnetic field, we built up a suite of computations using ever larger truncations L_B on the maximum spherical harmonic degree. From this set of upper bounds, how do we choose which is most relevant for the Earth? There are two issues here. Firstly, the spectral form $A(2l+1)^{-1}$ cannot describe the geodynamo for arbitrarily high degree as the associated total (expected) magnetic energy is divergent (i.e. $\sum_l R_l$ is infinite), so there must be a threshold beyond which the spectra decreases more rapidly. Secondly, as L_B increases, the upper bounds of dF/dt at the site increase because ever smaller scales (and ever larger gradients) in the magnetic field make it easier for a flow to create secular variation. This behaviour is shown in Fig. 5, for a variety of truncations L_B (20, 50, and 135). As we populate the concealed part of the geomagnetic spectrum, we observe a monotonic (albeit slow, quasi-logarithmic) increase in the maximum attainable dF/dt .

We exploit the fact that the upper bounds increase with L_B by choosing the maximum truncation that is consistent with the duration of the archeomagnetic spikes of ~ 30 yr (Shaar et al., 2011) – that is, we assume that the magnetic field structure does not diffuse within the lifetime of the spike. This maximum L_B then gives us a highest estimate of the upper bounds. If the small-scale magnetic field changes only through horizontal diffusion, we constrain the e-folding time for magnetic field harmonics of degree l , by $c^2(l(l+1)\eta)^{-1} \leq 30$ yr. Taking $\eta = 0.7$ m²/s, this condition is satisfied for every $l \leq L_B = 135$. Note that larger values of η (consistent with historical, rather than very recently published, values of electrical conductivity of the core) give smaller values of L_B and so $L_B = 135$ provides a “greatest” upper bound over all past, present, and hopefully future, estimates of core conductivity. In addition, the slow, logarithmic increase displayed in Fig. 5 is such that multiplying this truncation by a factor of (say) 2 is likely to induce only a minor change in the estimated upper bounds.

Having noted above that the magnetic field diverges as L_B increases, we check that $L_B = 135$ still gives geophysically reasonable values for the expected field. Associated with this truncation is the

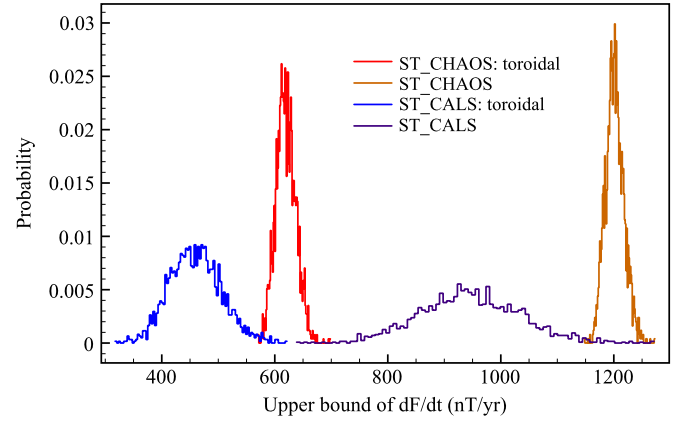


Fig. 6. Normalised histograms giving the discrete probability density function of the upper bound of dF/dt at Timna-30 with models ST_CHAOS and ST_CALS, for both unrestricted and purely-toroidal flows. In all cases 2000 realisations of the magnetic field extrapolated to degree 135 are used. The purely-toroidal assumption leads to a considerably lower mean upper bound compared to unrestricted flows: 620 nT/yr compared with 1200 nT/yr for ST_CHAOS; 460 nT/yr compared with 950 nT/yr for ST_CALS. The bounds derived from ST_CALS have significantly more variability than those derived from ST_CHAOS, with unbiased standard deviation of 46 nT/yr compared to 17 nT/yr for unrestricted flows, and 88 nT/yr compared to 16 nT/yr for purely-toroidal flows.

(expected) rms value of $B_r = 0.39$ mT and an (expected) minimum Ohmic dissipation of 1.5 GW (see Jackson and Livermore, 2009), all within geophysical bounds. Lastly, we adopt a truncation for the flow of $L_U = L_B + 10$ which provides well-converged solutions, as the optimising flows we find are always predominantly large-scale (see below).

5. Results

Fig. 6 shows normalised histograms of upper bounds derived at the site Timna-30 using 2000 realisations of the magnetic field, for both families of field models (ST_CALS and ST_CHAOS) and for unrestricted and purely-toroidal flows. The bounds derived from ST_CHAOS are displaced to the right of those from ST_CALS by 150–300 nT/yr, owing to the stronger non-dipolar magnetic field. Thus the bounds from ST_CHAOS provide a “greatest” bound of dF/dt over both models. For both ST_CHAOS and ST_CALS, the mean purely-toroidal flow bounds are about half those using unrestricted flows (620 nT/yr compared with 1200 nT/yr for ST_CHAOS; 460 nT/yr compared with 950 nT/yr for ST_CALS). These bounds are greater than (and therefore consistent with) the largest values of intensity change typical of the present-day (~ 0.1 μ T/yr), although they are well below those suggested for the archeomagnetic spikes of 4–5 μ T/yr.

Another feature of Fig. 6 is the relatively broad peaks of the bounds from ST_CALS: this stems from the fact that all the model coefficients are randomised, whereas those in ST_CHAOS are random only for degrees 14 and above. The narrow distribution of bounds for ST_CHAOS shows that, as already illustrated by Fig. 5, degrees 1 to 13 are the main contributors to an optimised dF/dt . In all cases, the contribution from diffusion is small, supplying approximately -0.3 nT/yr to the optima. Note that from additional analysis (supplementary Fig. 12) we concluded that 2000 realisations sufficed to produce converged statistics.

Figs. 7(a–b) show velocity power spectra of the flow for both classes of magnetic models. In each plot, 10 random representative realisations associated with purely-toroidal and unrestricted flows are shown. Figs. 7(c–d) show the energy spectrum of the associated secular variation; the inset in (c) shows a zoomed version of the figure at very low degree. In all cases, the optimal flows are

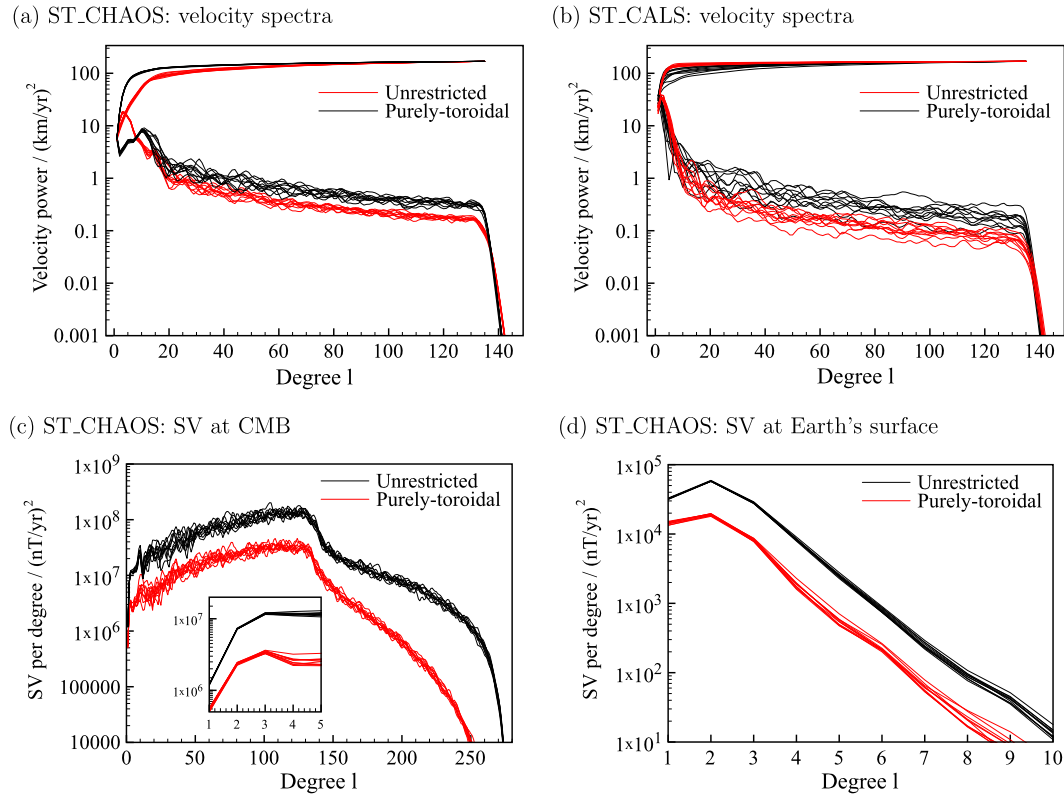


Fig. 7. Velocity power spectra of both unrestricted and purely-toroidal flows for 10 realisations of (a) ST_CHAOS and (b) ST_CALS magnetic models, for which dF/dt is optimised for Timna-30; both the energy per degree l and cumulative energy (up to degree l) are shown. Parts (c–d) show the energy spectrum for ST_CHAOS of the secular variation at the CMB and Earth's surface; the inset in (c) shows the data of the main plot at very low degree.

large-scale (converging by approximately degree 10). This observation justifies *a posteriori* the choice of 13 km/yr as a consistent constraint for the rms flow speed, a value which is based on core-flow inversions which themselves assume a large-scale flow. The optimal secular variation at the core surface increases with degree l until around degree 100 where it reaches a plateau, before an exponential decrease around degree $L_B = 135$. Due to attenuation in the mantle, only the large-scales dominate the spectrum at the Earth's surface which is around 4 times higher in the unrestricted flow case than the purely-toroidal flows case, giving the factor of two in the secular variation, or rather, dF/dt , itself. Interestingly the secular variation is quadrupole-dominated ($l = 2$), as is the current geomagnetic field (Hulot et al., 2007).

For the observation site of Timna-30, Fig. 8 shows contours of dF/dt (in both global and regional views), along with the structure of the optimising flow, for the median realisation of the ST_CHAOS model for both unrestricted and purely-toroidal flows. As seen previously in Section 3, the location of the maximum value of dF/dt is close to S but does not coincide exactly. Although the optimising flows were normalised to have a rms value of 13 km/yr, both are strong only in the vicinity of S and have maximum speeds of approximately 130 km/yr. It is also clear just how specialised the optimal flow is to the specific structure of the magnetic field, and that although still large-scale (according to Fig. 7), it differs from the typical core-flows obtained from inversion (e.g. Holme, 2007) by the notable lack of global-scale features. On a related point, Shaar et al. (2011) remarked that it was unclear whether dipolar (by which they mean “global”) or non-dipole field (i.e. “localised”) change is responsible for the archeomagnetic intensity spikes. In all our optimised cases, the intensity change is strongly localised (and therefore “non-dipolar”), although formally since magnetic intensity is a nonlinear quantity, such a separation into dipolar and non-dipolar components is not possible.

It is also of interest to compute comparable upper bounds on dF/dt for other sites. Fig. 9 shows the mean of the upper bounds for the model ST_CHAOS, for both purely-toroidal and unconstrained flows, as a function of site location on the Earth's surface. For graphical clarity, the plots use different scales. For both flow types, the main features are not only themselves similar, but also strikingly share many features of the magnetic intensity F itself (Fig. 1): pairs of high-latitude intensity patches, a strong low in the Pacific and moderately low equatorial values. This link is simply explained by the fact that high rates of change occur preferentially in regions where the field intensity is high, since the secular variation is linear and homogeneous in the magnetic field itself.

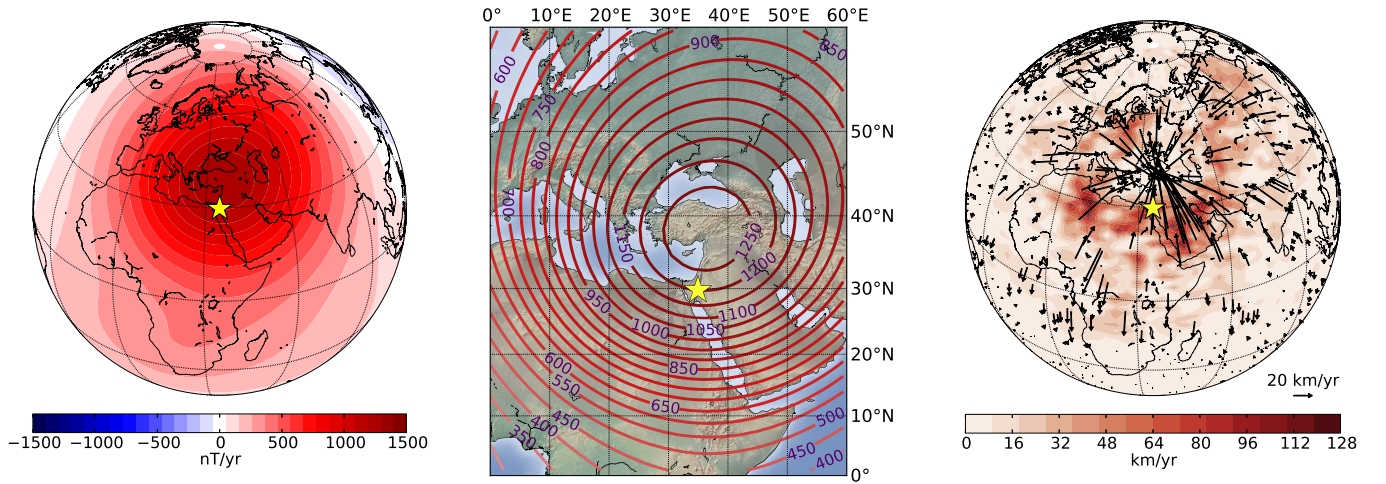
Lastly, future archeomagnetic studies may seek to find archeomagnetic spikes contemporaneous with that at Timna-30. We now ask what form the secular variation would take on the Earth's surface in the case of a dual-spike, by considering two possible (illustrative) dual-sites in (i) Xian, China and (ii) San Lorenzo, Mexico (i.e. in Mesoamerica), where archeology is particularly rich. Mathematically, we seek the maximum value of dF/dt that occurs (equally) at two sites, S and S_2 , subject to the same rms constraint on the flow as before, which becomes

$$\max_{\mathbf{q}} [\mathbf{G}^T \mathbf{q} - \mu [\mathbf{G}^T \mathbf{q} - \mathbf{G}_2^T \mathbf{q}] - \lambda (\mathbf{q}^T \mathbf{E} \mathbf{q} - T_0^2)], \quad (16)$$

where \mathbf{G}_2 is the analogue of \mathbf{G} at site S_2 , and λ and μ are Lagrange multipliers enforcing the constraints. As before, the (unnormalised) optimum flow is

$$\mathbf{q} = \frac{1}{2\lambda} \mathbf{E}^{-1} [(1 - \mu) \mathbf{G} + \mu \mathbf{G}_2] \quad (17)$$

(a) Unrestricted flows



(b) Purely-toroidal flows

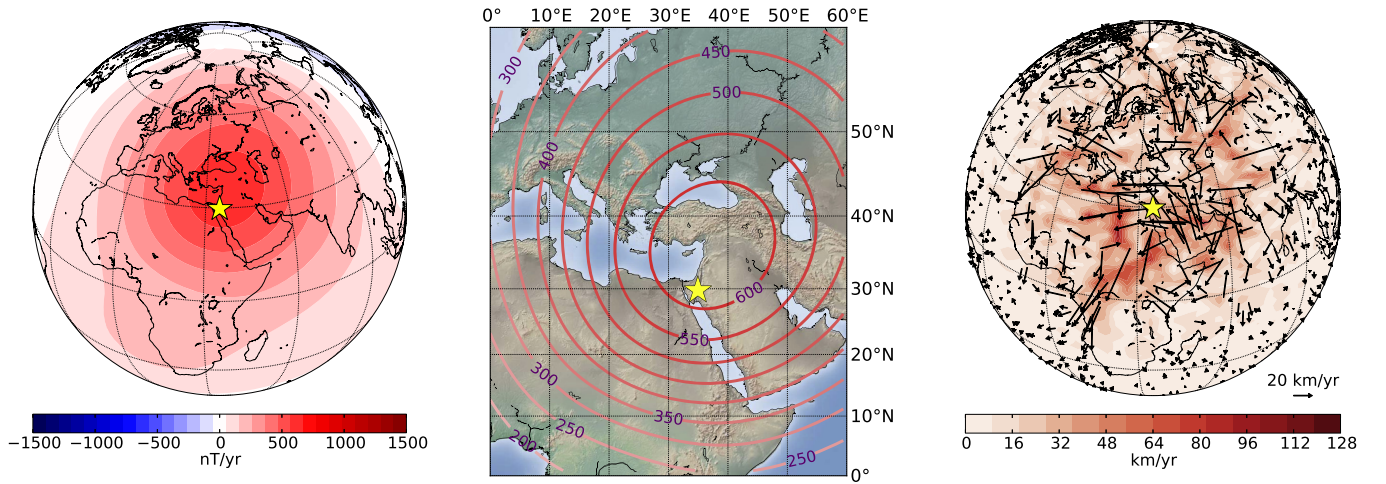
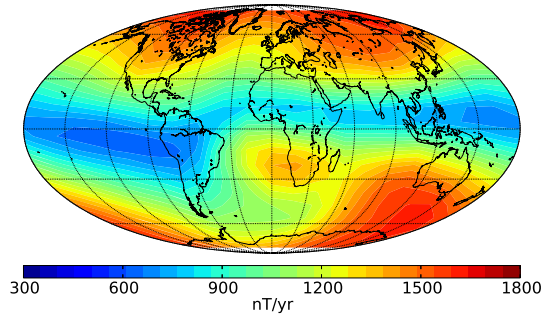


Fig. 8. Contours of dF/dt (in nT/yr) on the Earth's surface (left), a regional view (middle) and contours of $|\mathbf{u}|$ with indicative arrows showing the structure of the optimal flow (right) for the realisation of ST_CHAOS giving the median value of upper bounds for (a) unrestricted (top row) and (b) purely-toroidal (bottom row) flows, optimised for a site at Timna-30 (shown by the stars).

(a) Unrestricted flow



(b) Purely-toroidal flow

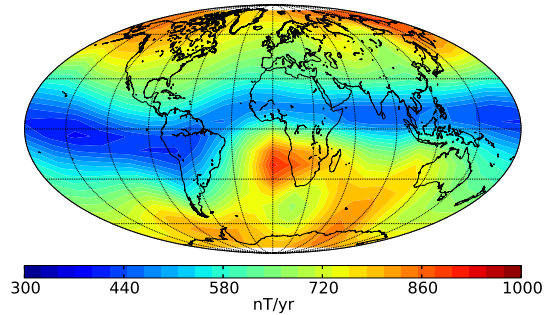
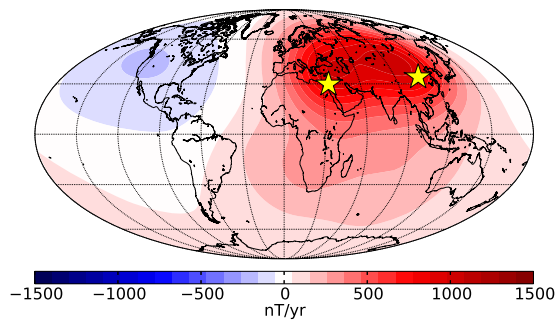
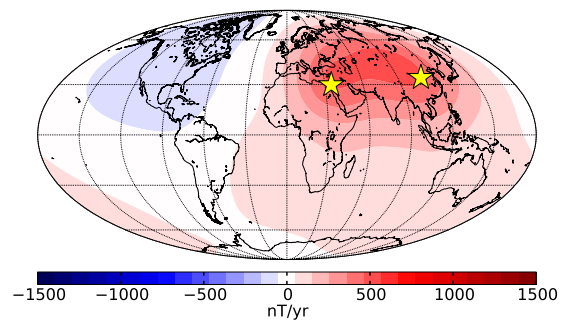


Fig. 9. Contour plot of the mean (over 2000 realisations) of the upper bound of dF/dt as a function of position of the observation site on the Earth's surface, for the magnetic field model ST_CHAOS for (a) unrestricted and (b) purely-toroidal flows. Note that the plots have different scales.

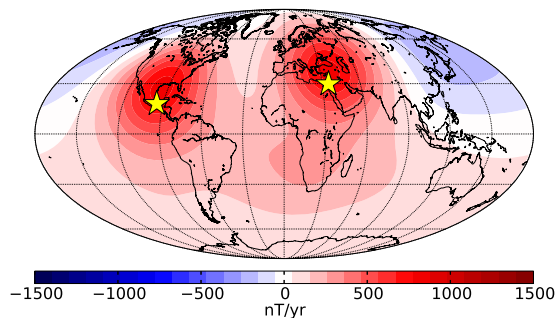
(i)(a) Timna-30 and Xian;
Unrestricted flow



(i)(b) Timna-30 and Xian;
Purely-toroidal flow



(ii)(a) Timna-30 and San Lorenzo;
Unrestricted flow



(ii)(b) Timna-30 and San Lorenzo;
Purely-toroidal flow

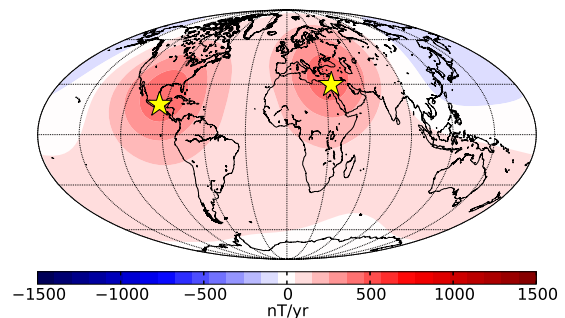


Fig. 10. Contour plot of dF/dt over the Earth's surface, for the dual-site calculations: (i) Timna-30 and Xian, China; (ii) Timna-30 and San Lorenzo, Mexico. The magnetic field is a single realisation of model ST_CHAOS. The flows (unrestricted and purely-toroidal) are chosen to give a maximal and equal value of dF/dt at both sites.

where the required value of the weighting, μ , ensuring equal values of dF/dt at both sites, is found using a simple bisection algorithm.

Fig. 10 shows contours of dF/dt for both dual-site problems with unrestricted and purely-toroidal flows, for a single (arbitrarily chosen) realisation of the magnetic field model ST_CHAOS. In case (i), where the two sites are relatively close, there is a single peak of dF/dt which is in between the sites. By contrast, in case (ii) where the two sites are of sufficient distance apart, the flows and corresponding intensity changes are quite separate. Thus, in the event of case (i), the same archeointensity spike would necessarily be realised over much of Asia but in (ii) the spikes may not be realised except in the vicinity of the two sites. Note that this analysis does not preclude potential localised spikes in (i) for flow structures different to the optimal cases derived here. In each case, the maximum values of dF/dt are about 70% of those for the single-site case.

Lastly, we commented earlier that, just as the present-day magnetic field, the one-site case had a secular variation dominated by $l = 2$. Here, of the four cases presented, only case (i)(a) has a secular variation on the Earth's surface dominated by degree 2, all other cases have a dipole-dominated spectrum.

6. Concluding remarks on the results

In this study we have described a methodology for computing the maximum value of intensity change, dF/dt , at any site on the Earth's surface subject to knowledge of the magnetic field (which we handled using statistical methods) and a rms constraint on the core-surface flow of 13 km/yr, a consensual figure from the core-flow inversion literature. For the site of Timna-30,

of the two magnetic field models used, that based on CHAOS-4 had a higher mean upper bound ($\sim 1.2 \mu\text{T/yr}$) than that based on CALS10k.1b ($0.95 \mu\text{T/yr}$). Restricting attention to purely-toroidal flows, the mean upper bounds are lowered by about a factor of 2 to $0.62 \mu\text{T/yr}$ and $0.46 \mu\text{T/yr}$. None of these bounds are consistent with (i.e. greater than) the values of dF/dt required by the archeomagnetic spikes of $\sim 4\text{--}5 \mu\text{T/yr}$ suggested for the Near East (recall Fig. 2). A further point of note is that the largest, but poorly constrained, variation rates of up to $0.8 \mu\text{T/yr}$ in European regions during the Medieval period suggested by Gómez-Paccard et al. (2012) are either barely consistent (in the unrestricted case) or inconsistent (in the toroidal case) with our upper bounds.

The extent of the discrepancy between the upper bounds and the severity of the archeomagnetic spikes depends on which flow assumption we take to be the most physically meaningful. The two choices of flow structure we studied were deliberately chosen as end-members of a spectrum of permissible poloidal flow structures in the core: at one end they are unrestricted, at the other constrained to be zero. It is well-known that a purely-toroidal flow can adequately explain the observed secular variation within the observational uncertainties. But due to the inherent nonuniqueness of the core-flow problem, many flows with a non-zero poloidal component provide as good a fit (see e.g. Holme, 2007). However, a large body of work in the core-flow literature points to a predominantly toroidal large-scale flow structure, even when the toroidal constraint is relaxed during the inversion. Indeed, in many such studies the ratio of the toroidal to poloidal flow energy is reported to be at least ten (Eymin and Hulot, 2005; Holme and Olsen, 2006; Pais and Jault, 2008; Gillet et al., 2009; Lesur et al., 2010). Furthermore, very recent work on the physical properties of the core itself suggests that the outermost part

of the liquid core is stratified (see Hirose et al., 2013, for a recent review), thereby admitting only toroidal flows. This motivates us to adopt the upper bounds derived from purely-toroidal flows, as the most physically compelling. The archeomagnetic spikes then require a rate of change of intensity of around 6 to 8 times larger than what our most favourable toroidal flows can account for.

A generous threefold increase (up to a flow rms of 40 km/yr) allows the toroidal bound to reach 1.5 $\mu\text{T/yr}$, but this still falls short of 4–5 $\mu\text{T/yr}$. Furthermore, and from a geometrical standpoint, this issue is compounded by the fact the optimising flows are very much more spatially focused than the global-flows inferred for the present-era. It would be rather fortuitous indeed if the only strong flow were to occur locally beneath Timna-30 at 1000 BC. Indeed, it is likely that such localised flows would never arise in the core, since due to the important role of the Coriolis force (and associated quasi-geostrophic flow), any rapid dynamics would be expected to be equatorially symmetric (Jault, 2008; Gillet et al., 2011), a property that our specialised optimal flows do not have.

Regarding the possibility of contemporaneous spikes of the same severity at Timna-30 and at another site (e.g. Xian or San Lorenzo), the upper bound is about 70% of that only for Timna-30. This reduction in the bound is simply a reflection of the fact that the kinetic energy available is spread more thinly over the CMB, and less is then available to drive rapid change at any one site. Thus simultaneous dual spikes of $\sim 5 \mu\text{T/yr}$ are even more unlikely than a spatially localised spike in the Near East. Furthermore, confirmation of the Near-East spikes could likely only be attempted in the immediate vicinity (see Fig. 8). It is however interesting to note that a spike in Xian, China, around 1000 BC would require either an even more intense contemporaneous spike in an intermediate region between the Near East and China, or for the two events to be completely independent and asynchronous in time (for which the more generous single-site bounds, rather than the lower dual-site bounds, would apply). The site in San Lorenzo is sufficiently far away from Timna-30 that two simultaneous spikes could occur without any signal in intermediate regions.

7. Discussion

We finish by briefly discussing how the discrepancy in our computations and the archeomagnetic intensity spikes might be rectified.

A simple resolution is to reduce the rate of change of archeomagnetic intensity found in the data, either by reassessing (and then reducing) the intensity itself or by making the duration of the intensity spike longer. Using our preferred upper bound of 0.62 $\mu\text{T/yr}$, this would necessitate a spike lasting several centuries rather than a few decades. The gap in the archeointensity data obtained from Syria admits such a possibility of an extreme intensity peak between 1100 BC and 800 BC. Moreover a longer duration would be more consistent with the fact that a spike-like feature is also observed at Arslantepe from a kiln with age uncertainties of 300 yr. However, increasing the duration of the spike (which would then become a “simple” archeointensity maximum) would severely contradict the stratigraphy and age models proposed by Ben-Yosef et al. (2009) and Shaar et al. (2011) in their archeological sites. It is further surprising that spike-like events have not been recorded in the Greek and Bulgarian data sets, although dF/dt there should be $\sim 0.55 \mu\text{T/yr}$ according to the results from ST_CHAOS (Fig. 8(b)). However, it is possible that this is due solely to the poor documentation of such an era, rather than the non-occurrence of a spike: this time interval in Eastern Europe and Near East corresponds to the ancient Dark Age (~ 1100 –800 BC) after the sudden demise of the flourishing Late Bronze societies, and thus a scarcity of archeological artifacts.

Alternatively, since a faster flow leads to more rapid intensity change, our preferred purely-toroidal bounds could become consistent with the archeomagnetic intensity changes if we increased our rms flow by a factor of 8 to $\sim 100 \text{ km/yr}$. However, such a flow is far away from what we consider to be the current dynamics of the core, requiring significant changes in the core-flow since 1000 BC. Furthermore, such a strong flow is not consistent with the understanding gained over the past few years from scaling laws: the rms flow speed inside the core is controlled by the available convective power (e.g. Christensen, 2010), which itself varies on the time-scales of the secular cooling of the Earth, and can be considered constant throughout the Holocene. Although fluctuations to this constant time-averaged flow are possible, deviations of up to 8 times the mean would be required here, which we deem not possible.

As a further alternative, it is conceivable that the magnetic field in 1000 BC was similar to none of our Monte Carlo realisations, and that our computed upper bounds significantly underestimate dF/dt for this epoch. One possibility is that the geomagnetic field models based on CALS10k1.b and CHAOS-4 are simply too weak: the values of dF/dt (linear and homogeneous in the magnitude of \mathbf{B}) therefore being too small. However, a magnetic field stronger by a factor of 8 (as required in the purely-toroidal case) is not consistent with records of the axial dipole moment over the Holocene (Knudsen et al., 2008). Another possibility is a strong small-scale magnetic field, but this surely would have been realised, at the very least, in the ST_CALS stochastic model. Although it is true that ST_CALS showed a higher variance than ST_CHAOS, 5 $\mu\text{T/yr}$ is around 100 standard deviations above the most optimistic bound of $0.95 \pm 0.046 \mu\text{T/yr}$ (with unrestricted flows). The most likely shortcoming of our CHAOS-4 models is the fact that the axial dipole field moment was stronger at the beginning of the first millennium BC than in more recent times (e.g. Knudsen et al., 2008). For this reason, we performed extra calculations assuming that the axial dipole coefficient in CHAOS-4 was twice that of its nominal value. This change led to an increase of the upper bounds by approximately 35% and 10% for the unrestricted and toroidal core-flow patterns, respectively. These rather moderate variations, in particular in the case of our preferred toroidal flows, are clearly not sufficient to reconcile the spike data with our computations.

Lastly, we concede that an explanation for the spikes may lie outside the scope of this study. With this in mind, we briefly examine the only physics of magnetic induction that our treatment neglects: that of radial diffusion of field. Although it is tempting to argue that diffusion in the radial and horizontal directions should have a comparable effect, this may be too simplistic. Magnetic features with short radial length scale would diffuse rapidly through the CMB and therefore, plausibly, could be important. The dynamic origin of these localised features is far from obvious however. One possibility are upwellings that carry strong, deep field to the surface, the concentrated flux then being expelled through the CMB by diffusion. Such a mechanism was for instance considered by Chulliat et al. (2010) to explain the recent acceleration of the north magnetic pole drift during the 1990s. However, a flux-expulsion event (Bloxham, 1986) not only requires a non-stratified outer core, but it remains to be seen whether it can deliver the required change in intensity over \sim one decade, very short compared to a core-overturn time-scale of \sim one century. Modelling of these dynamics and whether or not such a mechanism can explain the spikes is a future extension of our analysis. Looking more broadly, further data from the Near East would of course be highly beneficial in order to add to (and perhaps to refute or corroborate) the existing studies of Shaar et al. (2011) and Ben-Yosef et al. (2009). Moreover, it would be very useful to extend the analysis to directional data: the datasets that motivated this study contain only records of archeomagnetic intensity and not directional data, since

the slag materials are, in most cases, displaced from their cooling position. Should the observation of extreme rapid intensity change stand up to scrutiny, its implications would be far reaching, and may require consideration of yet poorly known core processes.

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Appendix A. Supplementary material

Supplementary material related to this article can be found online at <http://dx.doi.org/10.1016/j.epsl.2013.11.020>.

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