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Speckle temporal stability in XAO coronagraphic images

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ABSTRACT

Context. The major source of noise limiting high-contrast imaging is caused by quasi-static speckles. Speckle noise originates from wavefront errors caused by various independent sources, and evolves on different timescales depending on their nature. An understanding of how quasi-static speckles originate from instrumental errors is paramount to the search for faint stellar companions. Instrumental speckles average to form a fixed pattern, which can be calibrated to a certain extent, but their temporal evolution ultimately limits this possibility.

Aims. This study focuses on the laboratory evidence and characterization of the quasi-static pinned speckle phenomenon. Specifically, we examine the coherent amplification of the static speckle contribution to the noise variance in the scientific image, through its interaction with quasi-static speckles.

Methods. The analysis of a time series of adaptively corrected, coronagraphic images recorded in the laboratory enables the characterization of the temporal stability of the residual speckle pattern in both direct and differential coronagraphic images.

Results. We estimate that spoiled and rapidly evolving quasi-static speckles present in the system at the angstrom/nanometer level affect the stability of the static speckle noise in the final image after the coronagraph. The temporal evolution of the quasi-static wavefront error exhibits a linear power law, which can be used to first order to model quasi-static speckle evolution in high-contrast imaging instruments.

Key words. instrumentation: high angular resolution – methods: laboratory – techniques: high angular resolution

1. Introduction

The direct detection of planets around nearby stars is challenging owing to the required flux contrast and angular separation of the companion from its bright parent star. From the ground, the first issue to overcome is the large, dynamical wavefront error that the atmosphere generates. Real-time adaptive optics systems measure and correct these down to fundamental limitations (fitting error, spatial aliasing, wavefront sensor noise, and servo-lag error). The next generation of high-contrast imaging instruments such as SPHERE (Beuzit et al. 2008), GPI (Macintosh et al. 2008), HiCIAO (Hodapp et al. 2008), and Project 1640 (Hinkley et al. 2011) will improve the actual level of correction by reducing these fundamentals. High-order deformable mirrors, combined with more sensitive wavefront sensors, i.e. extreme adaptive optics (XAO) systems, will enable a dramatic reduction in the fast-varying speckle noise floor left uncorrected upon the actual performance.

For an ideal coronagraphic system, the stellar residual noise would average out over time. Owing to the random nature of this speckle noise, this would leave a smooth halo for which the intensity variance would converge to provide a null contribution for an infinitely long exposure. In these conditions, the fundamental noise floor in the science image is set by the photon noise. However, ideal instruments do not exist, and wavefront aberrations introduced into the optical train contribute to the noise budget. In contrast to the random and uncorrelated noise suppressed by averaging, both static and quasi-static speckles affect the sensitivity of an observing sequence. For instance, optical quality (polishing) or misalignment errors generate static speckles that constitute a deterministic contribution to the noise

variance, and thereby long-timescale wavefront errors. Though it corresponds to an additional perturbation, a deterministic contribution can easily be calibrated. Nonetheless, observing acquisitions have shown that the major noise-source limitation in high-contrast imaging is another class of instrumental speckles, the *quasi-static* speckles (Beuzit et al. 1997; Oppenheimer et al. 2001; Marois et al. 2003; Boccaletti et al. 2003, 2004; Hinkley et al. 2007). Quasi-static speckles correspond to slowly varying instrumental wavefront aberrations (amplitude and phase errors) present in the system, which finally dominate the companion signal. These speckles have various causes, among others mechanical or thermal deformations, or Fresnel effect, highly chromatic speckles originating from phase-to-amplitude conversion due to out-of-pupil plane optics (Marois et al. 2006b), and evolve on a shorter timescale than long-lived aberrations.

The temporal evolution of these quasi-static speckles is needed to quantify the gain expected with angular differential imaging (ADI, Marois et al. 2006a), as well as determine the timescale on which speckle nulling techniques should be carried out. Several authors have investigated the decorrelation timescale of quasi-static residuals in the particular context of ADI but at moderate 20–40% Strehl levels (Marois et al. 2006a; Lafrenière et al. 2007), though to our knowledge, in the context of very high Strehl (XAO systems), no information is present in the literature. Understanding these time-variable quasi-static speckles, and especially their interaction with other aberrations, referred to as the *pinning effect*, is paramount to the search for faint stellar companions. The timescale of quasi-static speckles evolution is essential to understand and predict the performance of XAO instruments.

The propagation through a coronagraph in the presence of aberrations, and the pinned speckle phenomenon were intensively analyzed in Soummer et al. (2007) from a statistical and numerical point of view. By adopting the same formalism, we can write down the wavefront complex amplitude at the entrance pupil as the coherent sum of four terms,

$$\Psi(r) = [A + A_s(r) + a_1(r) + a_2(r)] \times P(r). \quad (1)$$

Here, the function $P(r)$ describes the normalized telescope transmission, A is a deterministic term corresponding to a perfect, i.e. plane wave, $A_s(r)$ is a deterministic, complex term corresponding to the static aberrations, $a_1(r)$ is the atmospheric part of the wave front (a random term with zero mean), $a_2(r)$ is the contribution of the quasi-static speckle part of the wavefront, and r is the coordinate vector. In addition, $|A^2|$ represents the Strehl ratio S of the system. It is assumed that the lifetimes, τ_1 of $a_1(r)$ and τ_2 of $a_2(r)$, are such that $\tau_2 > \tau_1$. In this context, N_1 and N_2 describe the number of speckle realizations associated with each process during an exposure of duration Δt , and finally, N , the ratio of N_1 to N_2 , is the number of fast speckle realizations during a slow-speckle lifetime τ_2/τ_1 .

Soummer et al. (2007) proposed an analytical expression for the variance in the intensity, including speckle and photon noise in the presence of static, quasi-static, and rapidly varying aberrations, of

$$\sigma_I^2 = N \left(I_{s1}^2 + N I_{s2}^2 + 2 I_c I_{s1} + 2 N I_c I_{s2} + 2 I_{s1} I_{s2} \right) + \sigma_p^2, \quad (2)$$

where I denotes the intensity, and σ_p^2 is the variance in the photon noise. The intensity produced by the deterministic part of the wavefront, including static aberrations, is denoted by I_c , while the I_s terms correspond to the halo produced by random intensity variations, i.e. atmospheric and quasi-static contributions.

Equation (2) is used to describe the effect of quasi-static speckles and their interactions with other aberrations present in a system. In this generalized expression of the variance, several contributions can be identified in order of appearance: (1/) the atmospheric halo; (2/) the quasi-static halo; (3/) the atmospheric pinning term, where the static aberrations are amplified by the rapidly evolving atmospheric speckles; (4/) the speckle pinning of the static by quasi-static speckles; and finally (5/) the speckle pinning of the atmospheric speckles by quasi-static speckles. The noise budget of Eq. (2) provides useful insights into high-contrast imaging, especially with a coronagraph. It also enables a general comprehension of the several types of pinning phenomenon. The interest in the combination of the adaptive optics system, coronagraphy, speckle calibration, active correction, speckle nulling, and post-processing methods to remove most of the terms contributing to the noise variance is enlightened here.

The present study is concerned with the laboratory evidence of contribution (4/) to this noise budget in XAO coronagraphic images. We examine and quantify the speckle pinning of the static by the quasi-static speckles in a real system delivering highly corrected, coronagraphic images when no atmospheric contribution is present, i.e., when the contribution of I_{s1} to Eq. (2) can be neglected. In this situation, Eq. (2) can be simplified to:

$$\sigma_I^2 \simeq \left(I_{s2}^2 + 2 I_c I_{s2} \right) + \sigma_p^2, \quad (3)$$

and the present study focuses on the effect of the cross-term $I_c I_{s2}$.

The paper reads as follows. In Sect. 2, we detail the test apparatus and data reduction aspects, while in Sect. 3 we present and discuss the results. In Sect. 4, we attempt to discuss our results in the broader context of actual XAO instruments. Finally, we draw conclusions in Sect. 5.

2. Laboratory conditions

2.1. Experimental setup

The High-Order Testbench (HOT, Aller-Carpentier et al. 2008) is a versatile high-contrast imaging, adaptive optics bench developed at the European Southern Observatory (ESO) to test and optimize different techniques and technologies, in particular wavefront sensors, coronagraphs, speckle calibration methods, and image post-processing. It offers a unique opportunity to operate several critical components in a close-to-real instrument environment, by reproducing the conditions encountered at a telescope, e.g. the ESO Very Large Telescope (VLT).

The HOT comprises a turbulence generator with phase screens to simulate real seeing conditions. The light sources are a broadband, superluminescent semiconductor-diode (SLED) module from EXALOS, centered in the near-infrared at $1.6 \mu\text{m}$, coupled with a halogen white light lamp for wavefront sensing in the visible. A mask reproducing the footprint of the VLT pupil is installed on a 60-element bimorph deformable mirror (DM), which is held by a tip-tilt mount and employed to correct for static aberrations. A 32×32 actuator micro-DM, an electrostatic MEMS device, can be used to correct dynamical aberrations. A beam splitter diverts 50% of the light towards a wavefront sensor, while the rest is transmitted towards the coronagraph and the infrared camera, a $1\text{k} \times 1\text{k}$ HAWAII detector. The infrared camera offers various possibilities of near-IR filters, while during the experiment a narrow-band H filter was used ($\Delta\lambda/\lambda = 1.4\%$). All optics are mounted on an air-suspended table fully covered with protection panels and forming a nearly closed box, set in a dark room. The HOT features both a pyramid wavefront sensor (PWS) and the Shack-Hartmann sensor (SHS) which was used for this study. The implemented coronagraph is an apodized pupil Lyot coronagraph (Soummer et al. 2003, APLC), with a focal plane mask diameter of $4.5 \lambda/D$. This corresponds to an inner working angle (IWA) of $2.3 \lambda/D$ (90 mas in H -band). The IWA offers a qualitative description of the minimum separation from the bright on-axis star, at which the coronagraphic design allows the detection of a faint companion. The APLC combines pupil apodization with a hard-edged focal plane occulter and an undersized pupil-plane stop with 90% throughput. It is installed at an F/48 beam. Further details of the prototype can be found in Martinez et al. (2009).

Since the goal of this study is to examine the interaction between quasi-static and static aberrations, the phase screens of the bench were replaced by mirrors. This setup avoids the presence of dynamical aberrations and justifies the approximation made in Eq. (3). Our experiment used the micro-DM in combination with the bimorph DM to correct static aberrations. The latter was operated in open-loop, i.e. by statically applying a corrective voltage pattern, in addition to the fix operating voltage that sets the mirror surface to its initial shape.

The SHS is used to drive the tip-tilt mount in closed-loop mode, countering the main contribution of bench turbulence. The static aberrations that are common-path wavefront errors, are thereby reduced from ~ 200 to ~ 50 nm rms using the bimorph DM in open loop, i.e. by applying a corrective voltage pattern to the initial voltage pattern that sets-up the mirror (Aller-Carpentier et al. 2008). The wavefront-sensor non-common-path wavefront errors were measured using a reference fibre at the entrance of the sensor, and slope offsets were applied to the DM not to take into account these aberrations in the correction. Additionally, some slope offsets have been applied to correct for non-common path errors from the near-IR optical path (the initial wavefront error level is estimated to 25 nm rms) based on the

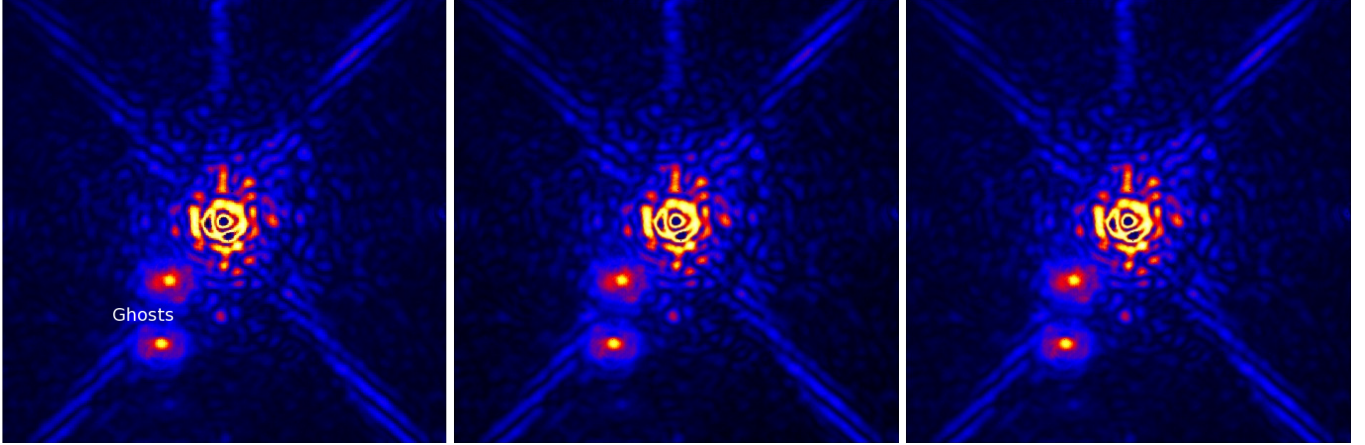


Fig. 1. Coronagraphic images recorded at t_0 , $t_0 + 3$ min, and $t_0 + 6$ min. The signal is intentionally saturated in the image core to emphasize the speckle signal in the halo. The Strehl ratio is $\sim 92\%$. The arbitrary color scale and dynamic range (identical for the three images) were chosen to enhance the contrast for the sake of clarity. The presence of two ghosts is highlighted in the left figure.

point spread function (PSF) image quality. Further details can be found in several papers (Aller-Carpentier et al. 2008; Martinez et al. 2010, 2011). Therefore, the static wavefront errors in the system can be estimated to be between 50 and 75 nm rms. In these conditions, the near-IR Strehl ratio is $\sim 92\%$. A qualitative temporal analysis of a time series of coronagraphic images over two days demonstrated the constance of the residual speckle pattern; images recorded on a timescale of several minutes are presented in Fig. 1.

2.2. Data acquisition and reduction

Raw coronagraphic images are dominated by static speckle noise. This means that the interaction between the quasi-static terms of Eq. (3), which are time-dependent, and static terms, assumed to be time-independent, can be studied by means of differential imaging from a time series of raw coronagraphic images. This simply refers to the difference in intensity between an image recorded at time $t_0 + \Delta t$ and the reference image registered at t_0 . The contribution from the quasi-static term is then evident from a time series of differential coronagraphic images. To guarantee a high speckle signal in the halo, the coronagraphic images are saturated in the image core, basically from the center to $3 \lambda/D$. The images are normalized to the direct, non-coronagraphic PSF flux, taking into account a non-saturated coronagraphic image to ensure an adequate calibration of the saturated images.

Depending on the nature of the image analyzed, we applied different metrics. The *contrast* (\mathcal{C}) refers to the ratio of intensity in the raw coronagraphic image, averaged azimuthally at a given angular separation, to the peak intensity of the direct flux. When studying a differential image, produced by subtracting a reference from the raw image, the average contrast is no longer adequate. The *detectability* (σ) is then used, which stands for the azimuthal standard deviation measured in a ring of width λ/D . It quantifies the ability to distinguish a companion at a given angular distance.

Each coronagraphic image of the time series corresponds to a series of 1.18 s short-exposure images, averaged out over 3 min. This was found to be the best compromise in terms of signal-to-noise level, considering the inherent camera noise. The data-reduction process corrects for bad pixels and background, and normalizes the images with respect to the exposure time and

flux. The radial profile and standard deviation are then calculated from suitable regions, in particular excluding the remnant spider-vane diffraction pattern. Before subtraction, a fine, sub-pixel correction of the residual tip-tilt component is performed on the raw images, using two ghosts present in the images as references (as seen in the left bottom corner of Fig. 1). These two ghosts originate from reflection in the optical train before the science arm, probably from the protecting window of the deformable mirror or the beam splitter. Examples of differential images are presented in Fig. 2. Figure 3 presents the contrast profiles of two raw, i.e. non-differential, coronagraphic images (taken at t_0 and $t_0 + 3$ min in dashed lines) and the resulting detectability obtained from the difference between the two (black line). The photon noise is estimated (pink line) and guarantees that σ_p^2 does not limit the noise variance expressed by Eq. (3).

In Fig. 3, the evaluation of the contrast and detectability levels are only provided for angular separation of $3 \lambda/D$ and more, which is due to the saturation of the inner part of each image. Figure 4 presents the evolution of the contrast and detectability profiles of the raw and differential coronagraphic images evolving for 165 min, as obtained from a time series of images. These data allow the study of the temporal characteristics of static and quasi-static speckles, and their interaction in a highly aberration-corrected, coronagraphic system.

3. Analysis and interpretation

The profiles presented in Fig. 4 clearly indicate that the detectability level degrades with time. These profiles demonstrate that raw coronagraphic images evolve temporally, being less and less correlated with the reference image over time, even though this evolution cannot be readily seen in raw images. This degradation of the detectability occurs for all angular separations, and in a homogeneous fashion.

As shown in Fig. 3, the data set is not photon-noise limited, so that the contribution σ_p^2 from the noise variance can be neglected. In these conditions, Eq. (3) can be further simplified to become:

$$\sigma_I^2 \simeq (I_{s2}^2 + 2I_c I_{s2}), \quad (4)$$

where the two contributing terms identify the static and quasi-static speckles. As observed in Fig. 1 and presented in Fig. 4, raw coronagraphic images are dominated by the static contribution,

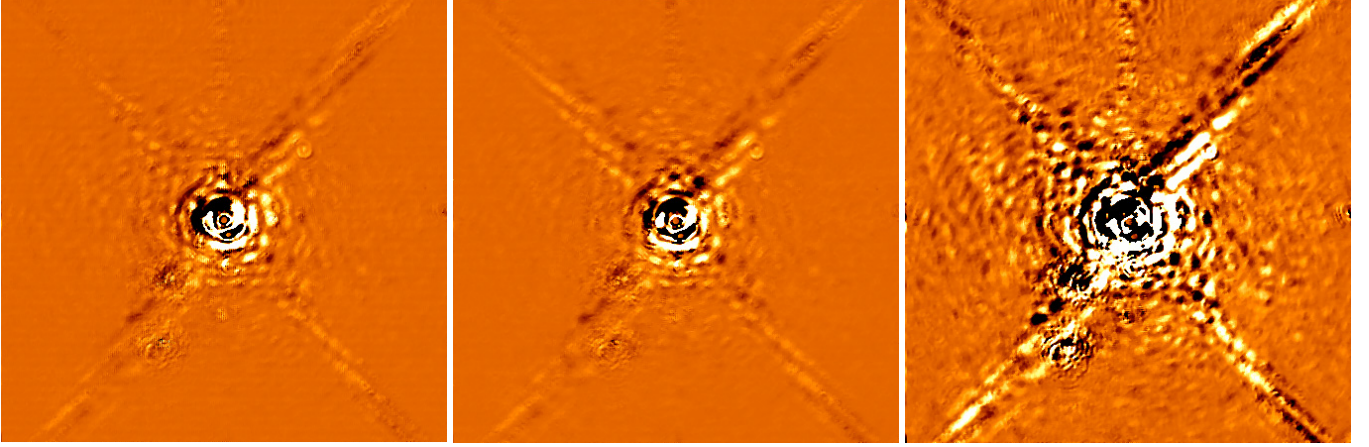


Fig. 2. Differential coronagraphic images. *Left:* difference of the $t_0 + 3$ min image to the reference t_0 (middle minus left image of Fig. 1). *Middle:* difference of the $t_0 + 6$ min image to the reference t_0 (right minus left image of Fig. 1). *Right:* difference of the $t_0 + 165$ min image to the reference t_0 . The arbitrary color scale and dynamic range were chosen to enhance the contrast for the sake of clarity. The increase in the strength of residuals can be qualitatively observed here, and quantitatively assessed in Fig. 4 as well as the scaling to the coronagraphic images.

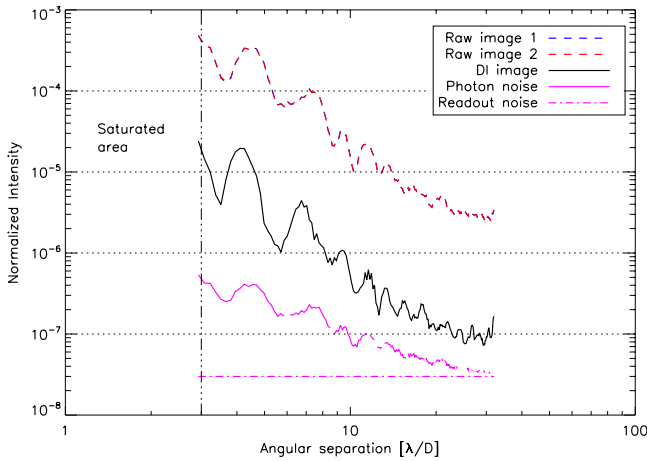


Fig. 3. Contrast profiles (\mathcal{C}) of a time series of coronagraphic images recorded at t_0 (dashed blue line) and $t_0 + 3$ min (dashed red line), both are which fairly identical; the detectability (σ) of the difference between both (differential image, full black line), and the associated photon-noise level (pink line) and readout noise (pink dashed line).

for which contrast profiles are roughly stable over time at any angular separation. Taking this into consideration, we can assume that $I_{s2} \ll I_c$. As a consequence, I_{s2} can be neglected except in the cross-term, and the noise variance in the raw coronagraphic image finally becomes:

$$\sigma_I^2 \simeq 2I_c I_{s2}. \quad (5)$$

This simple expression for the noise variance accurately describes what is observed in the data set: the degradation of the detectability level as a result of the pinning effect of the quasi-static onto the static speckles (i.e. an effect of interaction). This is qualitatively supported by the speckle pattern in the coronagraphic image being stable over time.

A breakdown of this pinning effect can be carried out at the level of the differential images. A similar expression of the noise variance for the differential images (σ_{DI}) can be derived as the difference of Eq. (5) evaluated at $t_0 + \Delta t$, from that of the reference, at t_0 . It reads:

$$\sigma_{DI}^2 \simeq 2I_c \Delta I_{s2}, \quad (6)$$

where ΔI_{s2} represents the quasi-static evolution between the two successive images. Therefore, the quasi-static contribution can be expressed as:

$$\Delta I_{s2} \simeq \frac{\sigma_{DI}^2}{2I_c}. \quad (7)$$

A general expression of the speckle intensity (Racine et al. 1999) is:

$$I_{\text{speckle}} \simeq \frac{(1-S)}{0.34}, \quad (8)$$

where S can be related to the wavefront error ϕ using Maréchal's approximation (Born & Wolf 1993): $S \approx 1 - \left(\frac{2\pi\phi}{\lambda}\right)^2$. With this, and using Eqs. (7) and (8), the contribution from quasi-static speckles to the wavefront error in the differential images has the approximate expression:

$$\Delta\phi_{s2} \simeq \frac{\lambda}{2\pi\sqrt{6}} \times \frac{\sigma_{DI}}{\sqrt{I_c}}. \quad (9)$$

Similarly, the wavefront error associated with the static contribution (assuming that $I_{s2} \ll I_c$) can be expressed as:

$$\phi_c \simeq \frac{\lambda}{\pi\sqrt{6}} \times \sqrt{I_c}. \quad (10)$$

Hence, using Eqs. (9) and (10), the analysis of both the direct and differential images becomes possible. The static wavefront error amplitude was evaluated for the raw coronagraphic images using Eq. (10), and for our data set converges to the value of 48 nm rms ($\lambda = 1.65 \mu\text{m}$). This is in fair agreement with our initial expectation (50 to 75 nm rms).

From our time series of differential images, using Eq. (9), we derive the quasi-static wavefront error contribution *per Fourier component*, of the pinning effect at several angular separations. Figure 5 shows the temporal evolution of ϕ_{s2} at 5, 10, and 25 λ/D , i.e. the quasi-static wavefront error (rms) as a function of time at several angular separations. It clearly indicates that ϕ_{s2} is time-dependent and increases with time, justifying the constant degradation of detectability observed in Fig. 4. This is true for all angular separations, and the shorter the separation the higher the amplitude.

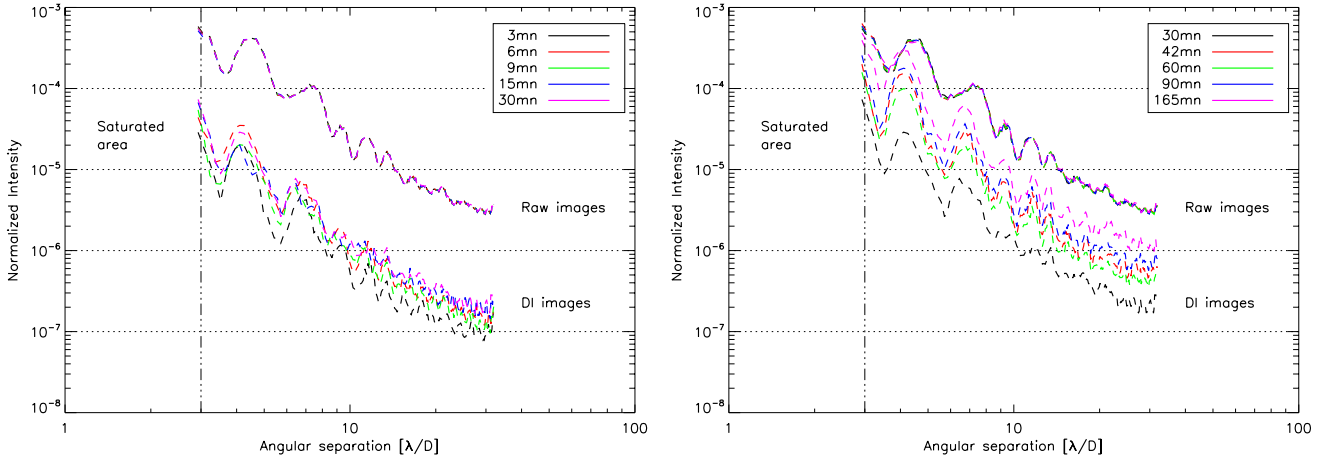


Fig. 4. Contrast profiles (\mathcal{C}) of a time series of coronagraphic images (top curves) and detectability (σ) of the differential images (subtraction of the time series of coronagraphic images to the reference one, bottom curves). *Left*: timescale evolves from 3 to 30 min, *right*: timescale evolves from 30 to 165 min.

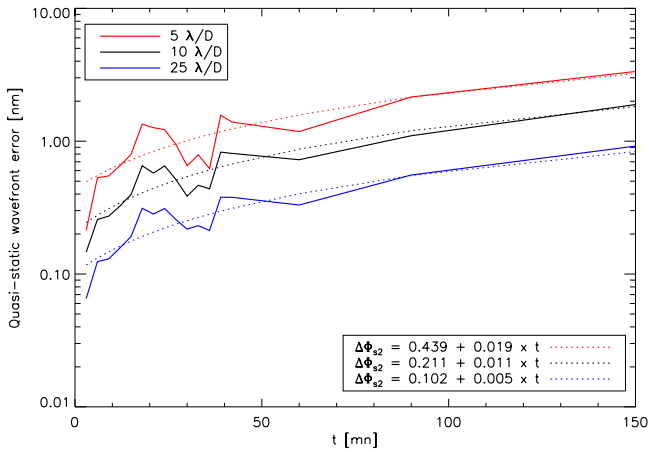


Fig. 5. Time variability of wavefront error due to quasi-static speckles, evaluated at various angular separations (observational data).

The power law of the temporal evolution of the quasi-static wavefront error at the three angular separations is derived and exhibits a similar tendency. It can be fitted by a linear function of time. The slope of the linear fit decreases with the angular separation, i.e. at $5 \lambda/D$ the increase in the quasi-static wavefront error with time occurs roughly two times more rapidly than at $10 \lambda/D$. The parameters for the linear fits are presented in the legend of Fig. 5, and can be used to extrapolate a model for quasi-static speckle evolution at least under laboratory conditions. From these linear fits derived for the data at 5, 10, and $25 \lambda/D$, and considering that the difference in amplitude is insignificant (smaller than 1 nm rms over an hour), we attempt to generalize the expression of the power law for any angular position in the field, which becomes the approximation:

$$\Delta\phi_{s2} \simeq 0.250 + 0.012 \times t, \quad (11)$$

where t is the time in minutes, and $\Delta\phi_{s2}$ is expressed in nm rms. Though nothing supports the universality of the parameters for the fit, the linear evaluation with time is clearly established in a laboratory environment. A linear temporal dependence was expected since the derivative of Eq. (11) must be a constant to ensure that the wavefront degradation over Δt is independent of the actual value of the reference image taken arbitrary here at t_0 .

Higher order terms would therefore make no physical sense. Only a linear relation with time is consistent with this condition.

Quantitatively, the level of quasi-static wavefront error responsible for the loss of contrast in the differential images (Fig. 4) is found to be in the regime of 1 \AA to 1 nm over an hour of time. In addition, for all curves (Fig. 5), a characteristic knee between 30 and 40 min is observed, during which the contrast degrades significantly (Fig. 4), though its origin is not well-understood. Nevertheless, the jump between 30 and 40 min does not deviate far from the mean trend given by the statistics of the data, and is likely a result of a disturbance during the measurement series. To assess whether there is an actual decorrelation over this specific timescale, we re-analyzed the data assuming the image acquired at $t_0 + 12$ min as the reference image. For this condition, the knee is still observable but on a timescale of 20 to 30 min in this case. This simple test clearly indicates that the observed knee in the data is due to a disturbance during the measurement rather than a statistical event.

Additionally, with simulations based on an IDL Fraunhofer propagation code that reflects our test setup and experimental conditions, we estimate the level of amplification of the static contribution (i.e. the total wavefront error) that can explain the detectability level obtained from our differential image data between t_0 and $t_0 + 3$ min (black curve, Fig. 3, as in the left figure of Fig. 4). The simulation assumes as-manufactured coronagraphic components and a typical power law of manufactured optics (PSDs with f^{-2} variation, e.g. Duparré et al. 2002, where f is the spatial frequency), to generate two coronagraphic images based on the same static aberration pattern but with slightly different amplitude levels. This simulates the effect of the interaction with pinned speckles, which we examine here. We found that an about 10 nm rms overall difference in static wavefront error between two images converges to similar contrast levels as the ones observed in our data (Fig. 6, left). The detectability according to simulated and observed data was matched at various angular separations to assess the error resulting from our estimation (± 2 nm in this case, see Fig. 6, left).

This result is supported by the rough estimate that can be derived from Eq. (7) using similar values, which for the contribution from quasi-static speckles converges to a nanometer level. In addition, the overall static wavefront error can be estimated similarly for all our data time gaps, and its temporal evolution can be deduced in a similar way as done previously

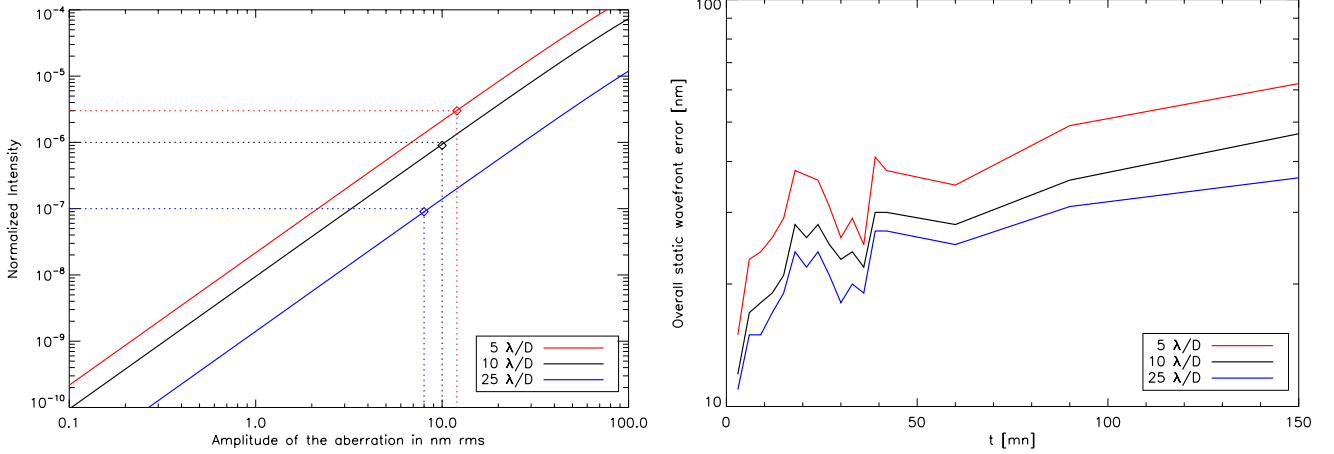


Fig. 6. *Left:* detectability (σ) of the differential image at various angular separations, with increasing difference in static aberration between the reference and the second image (simulated data). *Right:* time variability of wavefront error due to static speckles, estimated at various separations (simulated data, assuming f^{-2} for the power law).

for the quasi-static contribution. The total static wavefront error as a function of time is presented in Fig. 6 (right). To assess the error from the estimate, it was again derived at various angular separations. It is observed that the estimates derived from various angular separations are less and less compatible over time. A fair agreement is found on a short timescale, while the estimates differ significantly on an intermediate to longer timescale. However, the power law derived for the temporal evolution of the total wavefront error due to static aberrations is found to be similar on all angular separations and also to be linear, as observed for the quasi-static speckles.

In conclusion, the amplification of the 50 nm rms static aberrations present in the system by ≈ 10 nm rms can be explained by the effect of pinned, quasi-static speckles at the level of a few angstroms to nanometers. This effect is assumed to reflect the thermal and mechanical instabilities of the optical bench.

4. Discussion

The temporal evolution of quasi-static speckles is a key parameter for predicting the performance of upcoming XAO imagers. When the noise is dominated by quasi-static speckles, it can still be calibrated but to a limited extent. Using a reference image, quasi-static noise can be subtracted, but its temporal evolution ultimately limits this possibility; in particular, it is understood that some timescales have a larger impact than others. For instance, a typical hour-long ADI observing sequence provides a partial self-calibration of the residuals after a rotation of $\sim 1\lambda/D$ at a given angular separation, which generally takes less than a few minutes (e.g., 5 to 7 min at $1''$ on a 8-m class telescope for stars near the meridian in H -band), though it depends on wavelength. Residual speckles with decorrelation times shorter than the time needed to obtain the ADI reference image cannot then be removed, while quasi-static speckles that persist on longer timescales can largely be subtracted. In this context, the observed decorrelation time in our data ($\ll 3$ min integration time) which dependent slightly on field position, provides relevant information to help us understand and predict the limitations of existing and upcoming high-contrast instruments. In addition, it is remarkable to see that the decorrelation timescales observed in our data at very high Strehl ratios and the ones observed by Marois et al. (2006b) for a long sequence of ADI at low $\sim 20\%$ Strehl ratio (see Figs. 2 and 4 of that paper) are on the same order (few minutes).

Nonetheless, it should be pointed out that our results have been obtained in a laboratory environment and are thus valid in these conditions unless demonstrated otherwise, and scaling them to real instruments is highly non-trivial. Nothing supports the universality of the quasi-static speckle decorrelation time observed in our data, which depends significantly on the instrument environment (temperature or pressure changes, mechanical flexures, etc.). Furthermore, as initially discussed in Martinez et al. (2010), our contrast levels must be carefully considered as direct comparison with those actually provided by real high-Strehl instruments is not easy. Upcoming XAO imagers are much more complicated than our experimental demonstrator, and will adopt several calibration procedures such as the use of a reference star, either observed in the same image but obtained at different orientations (ADI), wavelengths (dual-beam imaging), or polarizations (differential polarimetry), or in a calibration image acquired by an integral field spectrograph.

5. Conclusion

We have presented our analysis of the static and quasi-static aberrations observed in a time series of extreme adaptive optics-corrected coronagraphic images. Our most significant result is that they exhibit a linear power law with time and interact by means of the pinning effect. We have examined and discussed this effect using the statistical model of the noise variance in high-contrast imaging proposed by Soummer et al. (2007). The pinning effect of quasi-static to static speckles described by the expression for the variance (Eq. (3)) is found to reflect our data set, which was obtained in a laboratory environment.

We found that quasi-static speckles, fast-evolving on the level of a few angstroms to nanometers, explain the evolution of our differential imaging contrast in the halo from 10^{-6} to 10^{-7} in terms of the amplification of the systematics. It has been proposed that this effect is a consequence of thermal and mechanical instabilities in the optical bench. The HOT bench is localized in a classical laboratory setting, where the enclosure of the bench is not thermally actively controlled, but the room temperature was monitored, and found to be stable at the level of a few tenths of degree. This result emphasizes the importance of this stability for the next generation of high-contrast instruments. In addition, for a further increase in the dynamic range of instruments, reducing the level of static speckles (I_c) through speckle reduction techniques, e.g. speckle nulling, is shown to be critically important.

The understanding of the temporal evolution of quasi-static speckles is required for an accurate quantification of the gain expected when using angular differential imaging, and to determine the interval over which speckle nulling techniques must be carried out. In our data, quasi-static speckles are observed to be temporally unstable over a timescale of a few seconds ($\ll 3$ min integration time) and follow a linear power law with time. Although nothing supports the universality of this estimate, in order to guarantee the high contrast level required to detect faint companions, non-common path wavefront errors must be sensed and corrected at a timescale that is shorter than the typical speckle decorrelation time.

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