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Behind the mask: can HARMONI@ELT detect biosignatures in the reflected light of Proxima b?

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ABSTRACT

Proxima b is a rocky exoplanet in the habitable zone of the nearest star system and a key test case in the search for extraterrestrial life. Here, we investigate the characterization of a potential Earth-like atmosphere around Proxima b in reflected light via molecule mapping, combining high-resolution spectroscopy (HRS) and high contrast imaging, using the first-generation integral field spectrograph, High Angular Resolution Monolithic Optical and Near-infrared Integral field spectrograph (HARMONI), on the 39-m Extremely Large Telescope (ELT). We simulate comprehensive observations of Proxima b at an assumed 45° inclination using HARMONI's High Contrast Adaptive Optics mode, with spatial resolution ~ 8 mas (3.88 mas spaxel $^{-1}$) and spectral resolving power $R \simeq 17\,000$ between 1.538 – 1.678 μm , containing the spectral features of water, carbon dioxide, and methane. Tellurics, stellar features, and additional noise sources are included, and removed using established molecule mapping techniques. We find that HARMONI's current focal plane mask (FPM) is too large and obscures the orbit of Proxima b and thus explore smaller and offset FPMs to yield a detection. An $S/N = 5$ detection of Proxima b's reflected light, suitable for atmospheric characterization, is possible with such modifications, requiring a minimum of 20 h, but ideally at least 30 h of integration time. We highlight that such detections do not scale with the photon noise, hence suitably detailed simulations of future instruments for the ELTs are needed to fully understand their ability to perform HRS observations of exoplanet atmospheres. Alterations to the HARMONI FPM design are feasible at this stage, but must be considered in context of other science cases.

Key words: techniques: high angular resolution – techniques: imaging spectroscopy – planets and satellites: atmospheres – planets and satellites: terrestrial planets.

1 INTRODUCTION

One of the key goals of exoplanet science is the atmospheric characterization of Earth-sized planets in the habitable zones of Sun-like stars. An important focus of these studies will be the search for biosignatures; indicators of life, such as the combination of oxygen (O_2), carbon dioxide (CO_2), water (H_2O), and methane (CH_4) (Meadows et al. 2018). However, current and near-future planned observatories will find it very challenging to characterize a temperate rocky exoplanet in the habitable zone of a Sun-like star, due to unfavourable ratios between the planet–star radii and contrast, as well as very close spatial separations and low transit probabilities. Studies have thus turned to smaller stars, that is, M-dwarfs, where a reduced

stellar radius and luminosity leads to closer-in conventional habitable zones and therefore more favourable ratios and transit probabilities giving greater observability (Charbonneau & Deming 2007). In addition, M-dwarfs are the most common type of star in the galaxy with approximately 250 within 10 pc of the Sun (Reylé et al. 2021, 2022). These stars also have a higher occurrence rate of rocky planets than FGK stars (Mulders, Pascucci & Apai 2015), meaning that the prevalence of habitable worlds may be significantly influenced by the environment of M-dwarf host stars (Shields, Ballard & Johnson 2016). The habitability of an M-dwarf Earth is currently an open question due to its dependence on a wide array of factors such as atmospheric loss (e.g. Khodachenko et al. 2007), tidal locking (e.g. Showman et al. 2013), and photosynthetic viability (e.g. Kiang et al. 2007; Claudi et al. 2021). Of key importance is determining if these worlds have atmospheres. M-dwarfs can be very active stars (Yang et al. 2017; Vida et al. 2019) and it is possible that the stellar

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activity has eroded the planetary atmosphere which may impact abiogenesis (Khodachenko et al. 2007; Kreidberg et al. 2019) but observations with *JWST* of a handful of transiting M-dwarf systems should give a first indication of whether atmospheres are retained in the conventional habitable zone (e.g. LHS 475 b, TRAPPIST-1 b, and TRAPPIST-1 c, Greene et al. 2023; Lustig-Yaeger et al. 2023; Zieba et al. 2023). If these planets have atmospheres, it is likely that they contain CO₂ due to the balance between volcanic and tectonic outgassing of CO₂ and weathering sinks (e.g. Foley & Smye 2018). Therefore, CO₂ is a good tracer of the presence of a rocky planet atmosphere, as well as being a potential biosignature in combination with other species.

Proxima b, the nearest exoplanet (1.3 pc), offers the opportunity for a detailed close-up study of the environment of a rocky exoplanet in the habitable zone of a bright M-dwarf (Anglada-Escudé et al. 2016; Jenkins et al. 2019; Damasso et al. 2020; Faria et al. 2022). An exoplanet's atmosphere can be characterized through its transmission, thermal emission, or reflection spectra. The Extremely Large Telescopes (ELTs) could detect CO₂ and CH₄ on transiting planets, but O₂ and H₂O may require an unfeasible number of transits to detect (Currie, Meadows & Rasmussen 2023; Hardegree-Ullman et al. 2023). However, like many nearby M-dwarfs planets, Proxima b does not transit (Gilbert et al. 2021, and references therein). Therefore, this world must be characterized through its reflection or thermal emission spectra. While a full thermal phase curve with *JWST* may potentially distinguish between bare rock and an atmospheric presence, significant observing times of months are needed for molecular detection (Kreidberg & Loeb 2016). Furthermore, the future planned Habitable Worlds Observatory does not have Proxima b in its current target list¹ which will directly image the Habitable Zones of other nearby stars. A promising alternative is to leverage the better spatial resolution of the ground-based ELTs, in combination with high spectral resolution and high contrast imaging, to resolve the planet from its host star and obtain its thermal and reflection spectrum directly using the technique of molecule mapping (e.g. Snellen et al. 2015; Hoeijmakers et al. 2018; Petit dit de la Roche, Hoeijmakers & Snellen 2018; Wang et al. 2018; Cugno et al. 2021; Petrus et al. 2021; Ruffio et al. 2021, 2023; Wang et al. 2021).

Molecule mapping works by leveraging the spatial resolution obtainable with a large mirror using adaptive optics (AO) to suppress contamination by diffracted star light at the planet's location. An integral field or long-slit spectrograph then takes a spectrum of each 'spaxel' (spatial pixel) in an image including at the planet's location. Since most spaxels will not contain the planet's spectrum, it is possible to create a data-driven model of the stellar contamination on the exoplanet's spectrum. This technique is aided by high spectral resolution which separates the planet's spectral lines from those of the contamination. However, this does not remove the photon noise caused by the stellar spectrum so in most cases the planet's spectrum will be very low signal-to-noise ratio (S/N). None the less, information can be obtained by cross-correlating each spaxel in the image with a model of the exoplanet's spectrum. This combines the signal of the planet's spectrum across wavelength resulting in a higher cross-correlation value than the background noise. This technique can be used to obtain the low-resolution albedo function of the

planet using a method similar to, for example, Martins et al. (2018) and high-resolution information through retrieval methods which test many planet models to put constraints on planetary properties (e.g. Ruffio et al. 2019, 2021; Hoch et al. 2020; Zhang et al. 2021; Patapis et al. 2022; Wang et al. 2022; Xuan et al. 2022, 2023; Landman et al. 2023).

There are many AO-enabled integral field spectrographs (IFSs) among the next generation of instruments for the ELTs. These include HARMONI, METIS (Mid-infrared ELT Imager and Spectrograph), ANDES (Armazones high Dispersion Echelle Spectrograph), and PCS (Planetary Camera and Spectrograph) on the ELT, GMTIFS (Giant Magellan Telescope Integral-Field Spectrograph), and GMagAO-X + IFS on the Giant Magellan Telescope (GMT) and IRIS (InfraRed Imaging Spectrograph) and MICHI (Mid-Infrared Camera, High-disperser, and Integral field spectrograph) on the Thirty Meter Telescope (TMT) to name a few (Sharp et al. 2016; Wright et al. 2016; Packham et al. 2018; Kasper et al. 2021; Marconi et al. 2021; Brandl et al. 2021; Thatte et al. 2021; Males et al. 2022). As molecule mapping is a photon-limited technique, it typically makes use of these ground-based instruments at wavelengths shorter than $\approx 5 \mu\text{m}$ due to the thermal contamination from room temperature telescope optics and the Earth's atmosphere (Snellen et al. 2015). HARMONI and METIS on the ELT form a powerful first light pair for molecule mapping. This is because HARMONI operates at wavelengths less than $2.5 \mu\text{m}$ where reflected light dominates the spectrum of a temperate rocky exoplanet (see fig. 7 in Turnbull et al. 2006), while the high-resolution part of METIS will target mostly thermal emission between $3\text{--}5 \mu\text{m}$. In addition, RISTRETTO@VLT will operate between $0.62\text{--}0.84 \mu\text{m}$, aiming at detecting the oxygen A-band, $0.759\text{--}0.771 \mu\text{m}$, on Proxima b (Chazelas et al. 2020; Blind et al. 2022). Combined they have the potential to give a holistic view of a planet's atmospheric properties, including its energy budget, and robust measurements of its atmospheric constituents including the four key biomarkers O₂, CO₂, H₂O, and CH₄. Snellen et al. (2015) studied the potential of METIS to characterize the thermal properties of the atmosphere of a planet similar to Proxima b. In this work, we focus on the complementary reflection spectrum, by simulating observations for HARMONI. Previous work (Houllé et al. 2021; Bidot, Mouillet & Carlotti 2023), has demonstrated HARMONI's ability to detect the thermal emission of young, widely separated gas giants using the molecule mapping technique. Following the work of, for example, Wang et al. (2017), Houllé et al. (2021), and Patapis et al. (2022), we robustly estimate HARMONI's potential to characterize Proxima b including the effects of Earth's atmosphere, the optics of the ELT and HARMONI's, detector performance and several noise sources as in Houllé et al. (2021, described fully in Section 2). Additionally, due to the small on sky separation and short orbital period (≈ 11.2 d) of Proxima b, its on sky position and velocity can change appreciably during an observation. This motion is an effect currently unique to this system and is accounted for in the simulations.

This paper is laid out as follows. Section 2 describes the simulation of HARMONI observations for spatially resolved exoplanet systems made with the High Contrast Adaptive Optics (HCAO) mode. Section 3 demonstrates how the molecule mapping technique can be used to recover the signal of a fiducial exoplanet's reflected light, while Section 4 demonstrates how HARMONI can be used to study Proxima b specifically. We discuss here also the possibility of relatively minor modifications to the HARMONI instrument design to best enable this. Section 5 discusses the arguments regarding the change to the instrument design. We conclude in Section 6.

¹See NASA Exoplanet Exploration Program's Mission Star List for the Habitable Worlds Observatory. Available online: https://exoplanets.nasa.gov/internal_resources/2645_NASA_ExEP_Target_List_HWO_Documentation_2023.pdf

2 SIMULATING HARMONI

HARMONI is an IFS that will be one of the first instruments mounted on the ELT (Tecza et al. 2009; Thatte 2010; Thatte et al. 2014, 2016, 2020, 2021, 2022). It is a versatile instrument with: a non-simultaneous wavelength coverage between 0.47–2.45 μm ; a choice of three spectral resolutions; four spatial resolutions and several AO modes including a high contrast mode. For spatially resolved observations of exoplanets, the HCAO mode (Carlotti et al. 2018; Houllé et al. 2021) facilitates the required high-contrast observations with coverage of the H and K bands between 1.45–2.45 μm at a range of resolutions. This work simulates observations with this mode using the H-high grating (1.538–1.678 μm , $R = 17\,385$) with a spatial sampling of 3.88 mas which oversamples the spatial resolving power.

The HCAO mode can be configured with one of two available apodizers (named SP1 and SP2) and one of three partially transmissive focal plane masks (FPMs). The apodizers reside in the pupil plane and modify the point spread function (PSF) of the instrument to create a dark annulus where diffraction is suppressed around the central peak. The FPMs reside in the FPM wheel and reduces the flux of the PSF core by a factor of 10^4 which allows longer integration times to be used for bright stars. HARMONI uses an atmospheric dispersion corrector (ADC) optimized for a single airmass meaning there will be residual dispersion. Therefore, each of the FPM is elongated in one direction to better match the shape of PSF core. In this work we use only the SP1 apodizer with the H band (smallest) FPM.

We simulate observations for HARMONI's HCAO mode using a similar method to that in HSIM v310² (Zieleniewski et al. 2015) but with modifications for multi-exposure simulations to reduce computation time and output file size. Our simulations also allow for the instrumental parameters to be modified to simulate changes to HARMONI's design and different IFSs.

2.1 Modelling the orbits

Due to Proxima b's short orbital period and HARMONI's small spatial sampling, the planet may not remain on the same spaxel throughout a night of observations. In HCAO mode, the instrument rotator will track the parallactic angle, otherwise known as pupil tracking, to keep atmospheric dispersion at a fixed angle. This means the position angle of the image will appear to rotate during an observing run. Over a night (~ 10 h), this rotation corresponds to $\sim 150^\circ$ and is accounted for in our simulations. A smaller but important effect is the change in Proxima b's position due to its relatively short orbital period and proximity to the Solar system. For a face-on orbit, the position of the planet will rotate by $\sim 13^\circ$ (~ 2 spaxels at the separation of Proxima b) over 10 h.

As we aim to be as realistic as possible with the orientation of the Proxima system, we include the orbits of both the star and planet in the simulation although the stars motion is insignificant. Due to the spatial and spectral resolution of the simulation, it is sufficiently accurate to model the orbits as ellipses. For Proxima b's orbit, we use measured parameters from radial velocity studies (see Table 1) and Proxima Centauri we assume reflex motion due to Proxima b only. The orientation of the orbits are specified by three parameters:

(i) Inclination, i : the angle between the plane of the sky and the plane of the orbit.

Table 1. Parameters of the Proxima Centauri system used to simulate Proxima b's orbit and information on the spectra used in this work.

Spectral parameters	Value	Ref
Stellar type	M5.5 V	1
Right ascension	14: 29: 42.94613	2
Declination	−62: 40: 46.16468	2
Distance	1.302 pc	2
PHOENIX model	$T = 3000$ K	3
	$\log(g) = 5$	3
	$[\text{Fe}/\text{H}] = 0$	3
	$[\alpha/\text{M}] = 0$	3
Stellar rotation period, $P_{\text{rot},*}$	~ 90 d	4,5
Magnitude (H)	4.8 mag	6
Proxima b spectral model	1 bar oxyc atmosphere	7
Proxima b geometric albedo (average)	0.23	7
Proxima b minimum mass, $M_p \sin i$	$1.27 M_\oplus$	5
Proxima b radius (estimate), R_p	$1.07 R_\oplus$	8
Orbital parameters	Value	Ref
Systemic velocity, V_{sys}	$-22.204 \text{ km s}^{-1}$	9
Radial velocity amplitude, K_*	1.24 m s^{-1}	4
Semi-major axis, a	0.0485 au	4,5
Orbital period, P	11.186 d	4,5,10,11
Orbital velocity, K_p	47.2 km s^{-1}	*
Eccentricity, e	0	*
Inclination, i	45°	*
Longitude of the ascending node, Ω	90°	*
Mean longitude, λ	110°	5
Reference time for λ (JD), T_λ	2451634.73146	5

Notes. 1: Bessell (1991); 2 Gaia Collaboration (2020); 3: Husser et al. (2013); 4: Faria et al. (2022); 5: Anglada-Escudé et al. (2016); 6: Skrutskie et al. (2006); 7: Lin & Kaltenegger (2020); 8: Bixel & Apai (2017); 9: Kervella, Thévenin & Lovis (2017); 10: Jenkins et al. (2019); and 11: Damasso et al. (2020). * assumed.

(ii) The longitude of the ascending node, Ω : a rotation in the plane of the sky.

(iii) The argument of periastron, ω : a rotation in the plane of the orbit.

Unfortunately, the longitude of the ascending node is currently unknown and the inclination is only weakly constrained by the non-detection of transits (Gilbert et al. 2021, and references therein). We choose to set the eccentricity to 0, close to the value measured by Faria et al. (2022), which means the argument of periastron no longer affects the shape of the orbit. An intermediate inclination of 45° and a longitude of the ascending node of 90° are chosen for Proxima b's orbit in this work. This choice does not affect the maximum elongation of Proxima b but does affect the duration of and Doppler shift at maximum elongation. Section 5.1 discusses the difficulty of determining Proxima b's full 3D orbit prior to these observations and how this analysis might proceed if the orbit is unknown. The orbit chosen represents a good compromise between having large radial velocity shifts and spending longer at maximum elongation. The mean longitude and accompanying reference time are used to define the phase of the orbit at a given time.

Our treatment of Proxima b's orbit differs from that of Snellen et al. (2015) in their simulations of METIS as their planet stays at quadrature with a Doppler shift of 30 km s^{-1} throughout each observation. Additionally, their planet is also slightly larger ($R_p = 1.5 R_\oplus$) and closer to Proxima Centauri ($a = 0.032$ au) than Proxima b.

2.2 Spectrum of Proxima b

HARMONI will be sensitive to the reflected light of Proxima b meaning the planet's spectrum, F_p , is a Doppler shifted and rotationally broadened copy of the stellar spectrum, F_s , (Spring et al.

²<https://github.com/HARMONI-ELT/HSIM>

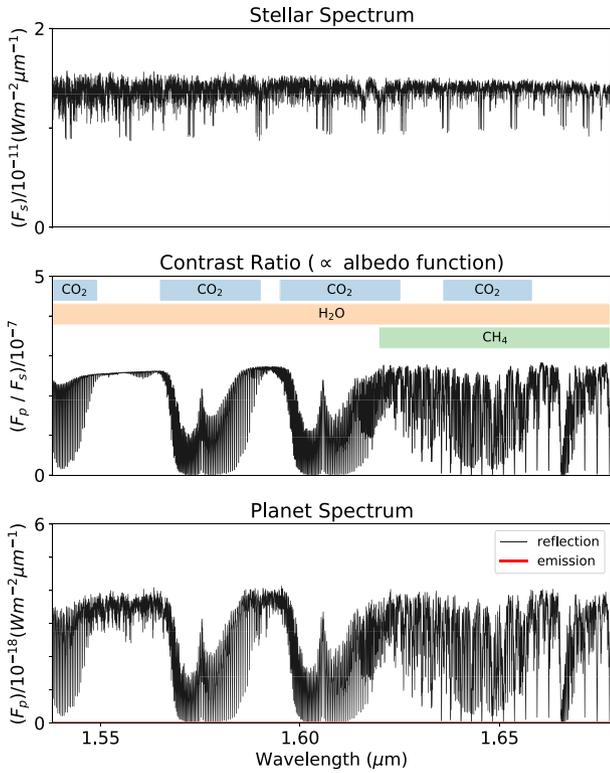


Figure 1. The spectra used in the simulation. Top: the stellar spectrum in units of intensity at Earth. Middle: the ratio of the exoplanet and stellar spectra ($4 \times 10^{-7} \sim 17$ mag). The features caused by different molecules in the planet’s atmosphere have been highlighted. Bottom: the exoplanet’s spectrum in units of intensity at Earth. In red is the thermal emission of the planet, which is virtually 0 at approximately 2.7×10^{-7} per cent of the planet’s flux at these wavelengths assuming an equilibrium temperature of 234 K.

2022) modulated by the planets geometric albedo, A_g , as shown in equation (1).

$$F_p(\lambda, v_{\text{Dop}}) = F_s(\lambda, v_{\text{Dop}}) \times A_g \times g(\alpha) \times (R_p/a)^2, \quad (1)$$

$$g(\alpha) = \frac{1 + \cos(\alpha)}{2}, \quad (2)$$

where $g(\alpha)$ is the phase function and α is the phase angle. We use a reflection spectrum which has been computed specifically for Proxima b from the Carl Sagan Institute (Lin & Kaltenegger 2020). We use the Earth-like 1 bar oxyc atmosphere model which assumes Earth-like mixing ratios for atmospheric gasses except for CO_2 which is more abundant by a factor of 100 to keep the planet from freezing. This model also assumes an Earth-like albedo for reflection of the planet’s surface and accounts for the higher planet mass, lower instellation, and different stellar spectral type compared to the Earth. The average geometric albedo over wavelength (1.538 – 1.678 μm) of this model is 0.23. Lin & Kaltenegger used a PHOENIX model (Husser et al. 2013) for the host star Proxima Centauri when computing the spectrum of Proxima b so we also use a PHOENIX model for the star with the parameters in Table 1. The spectra of Proxima Centauri and Proxima b are shown in Fig. 1.

The simulations include the Doppler shift, v_{Dop} , resulting from the barycentric, systemic, and orbital velocities of each object. Additionally, we multiply the planet’s flux by the illuminated fraction of the planet which is described by the phase function shown in

equation (2). This is simpler than Lambertian scattering which is typically assumed (e.g. Carrión-González et al. 2021; Spring et al. 2022) and results in the planet being slightly brighter at quadrature phases. A simpler function was chosen as the albedo and scattering properties of Proxima b are unknown at this time. Additionally, we do not include the rotational broadening, v_{broad} , of Proxima b’s spectrum as, due to the planet’s orbital period and slow stellar rotation period, the effect is insignificant (Spring et al. 2022).

2.3 Selecting observation times

Our simulations model the orientation of the Proxima system so the dates of the simulated observations must be picked considering the observability of the planet just like real observations. To identify suitable dates, we assume we a priori know Proxima b’s orbit (see Table 1) and check the following set of conditions at 10-min intervals between 2030 and 2032 January 1:

- (i) It must be nautical twilight or darker at Paranal.
- (ii) Proxima Centauri must be more than 45° in elevation above the horizon at Paranal (airmass < 1.4) for the AO to function well.
- (iii) Proxima b must not be behind the FPM at any time, as the throughput of the mask will reduce the reflected light signal too much for it to be detected.
- (iv) Proxima b must have at least half of its hemisphere illuminated as this leads to a higher reflected light signal.
- (v) Proxima b’s velocity must be at least 1 km s^{-1} different from Proxima Centauri’s and Earth’s as this prevents the spectral lines from being aligned which aids in the data reduction (see e.g. Lovis et al. 2017).

We then identify a list of dates on which an observation of a given length can be made, if the length of the observation is less than the time window the planet can be observed, then the start time is chosen to minimize the airmass of the observation. Additionally, we also compute the total time Proxima b could be observed. Due to Proxima b’s approximately 11-d orbital period, it can remain widely separated from Proxima Centauri over a whole night. However, the FPM can severely limit the length of the observing window. First, the sky rotation changes the region of the sky covered by the mask which could result in the mask covering the planet part way through the night. Second, with a smaller mask the atmospheric dispersion can increase the amount of light around the mask edge which can impose stricter restrictions on the airmass in order to avoid persistence.

2.4 Modelling Earth’s atmosphere

The Earth’s atmosphere will contaminate the spectra we observe and modelling its effect is important in determining the feasibility of these observations. The airmass of the system is calculated using the known on sky coordinates of Proxima Centauri which is used to calculate the telluric transmission using TelFit (Gullikson, Dodson-Robinson & Kraus 2014) and the telluric emission using SkyCalc (Noll et al. 2012; Jones et al. 2013). SkyCalc was not used for the telluric transmission as the discontinuities due to airmass interpolation caused artefacts in the simulation. The tellurics can be created for different weather conditions however, all the simulations presented here assume a surface pressure, surface temperature, and humidity as given in Table 2 which are consistent with average conditions at Paranal and therefore very similar to those at Armazones, the ELT site.

Table 2. Parameters used to simulate observations with HARMONI HCAO mode and accompanying references. See Table 1 for the parameters used to simulate the Proxima Centauri system. Havg indicates wavelength-dependent quantities that have been averaged over the *H*-High band in this table. The wavelength dependence is included in the simulation.

Instrumental mode	Value	Ref
Spaxel Sscale	3.88 mas	1,2
Spectral resolving power	17 385	1,2
Wavelength range	1.538 – 1.678 μm (<i>H</i> -High)	1,2
AO mode	HCAO – SP1 apodizer	3
Observing conditions	Value	Ref
Longitude	$-70^{\circ}24'18''$	4
Latitude	$-24^{\circ}37'39''$	4
Airmass	1.25–1.4	-
Seeing	0.57 arcsec (fixed)	4,5
Surface pressure	795 hPa	4
Temperature	283 K	4
Relative humidity	20 per cent	4
Instrumental parameters	Value	Ref
ELT transmission _{Havg}	0.755	2
ELT emission _{Havg}	3.8 photonss ⁻¹ m ⁻² μ ⁻¹ mas ⁻²	2
Atmospheric dispersion	32.6° (fixed)	3
Corrector angle		
Focal plane mask transmission	10 ⁻⁴	3
HARMONI transmission _{Havg}	0.438	2
HARMONI emission _{Havg} †	0.5 photonss ⁻¹ m ⁻² μ ⁻¹ mas ⁻²	2
Total throughput _{Havg} *	0.30	-
Quantum efficiency _{Havg}	0.9	2
Crosstalk	0.02 per adjacent pixel	2,3
Read noise	12e ⁻ pixel ⁻¹	2,3
Dark current	0.0053e ⁻ s ⁻¹ pixel ⁻¹	2,3
Thermal noise from cryostat	0.017e ⁻ s ⁻¹ pixel ⁻¹	2
Persistence limit	30000e ⁻	2
Focal plane masks	Value	Ref
FPM for SP1 apodizer (<i>H</i> band)	Ellipse: 50 mas × 58 mas	-
FPM for SP1 apodizer (<i>K</i> band)	Ellipse: 72 mas × 76 mas	-
FPM for SP2 apodizer	Ellipse: 96 mas × 96 mas	-

Notes. † This assumes the focal plane relay has a temperature of -10°C . In the current design, this temperature has increased to $+2^{\circ}\text{C}$ however this difference will not make an appreciable change to the noise and therefore the results presented here. * This excludes the FPM. 1: Thatte et al. (2021); 2: using information from HSI v310, Zieleniewski et al. (2015); 3: Houllé et al. (2021); 4: <https://www.eso.org/sci/facilities/paranal/astroclimate/site.html>; and 5: https://www.eso.org/sci/facilities/eelt/docs/ESO-193696.2_Observatory_Top_Level_Requirements.pdf.

2.5 Modelling HARMONI

Observing Proxima b will push HARMONI to the limits, therefore a detailed instrument simulation is required to determine the feasibility of such observations. In this work, we account for the throughput and emissivity of the ELT, the PSF of the combined ELT and HARMONI optics, the residual atmospheric dispersion, the FPM, the throughput and emissivity of HARMONI, and several noise sources from the detector and optics.

2.5.1 The throughput and emissivity of the ELT optics

Our simulation uses the pre-calculated transmission as a function of wavelength from HSI v310, while the thermal emission is assumed to be a non-ideal emitter, that is, a greybody with an emission temperature of 273 K and an emissivity equal to one minus the transmission of the ELT.

2.5.2 The PSF of the combined ELT and HARMONI optics

We use the method presented in Fétick et al. (2018) to compute the long exposure PSF (> 10 s to average highly time-variable phase aberrations, cf. Fétick et al. 2018, 2019) for a given seeing and wavelength using the power spectral density computed in Houllé et al. (2021). The sum of the PSF, sampled with HARMONI's spatial sampling, is normalized to unity. To reduce computational requirements, we assume a constant seeing of 0.57 arcsec (occurs approximately 30 percent of the time at Armazones³) and only generate the PSF for the central wavelength, ignoring the wavelength dependence. As the planet resides close the mask edge, better seeing are desirable to minimize contamination of the exoplanets spectrum. We use the same realization of the PSF for each observation. This results in a more optimistic and well-behaved PSF than would likely be achieved on sky. Houllé et al. (2021) have a more realistic treatment of the PSF and so in Section 3.4 we compare our results to theirs.

2.5.3 The residual atmospheric dispersion

HARMONI's HCAO mode uses an ADC with an optimal correction angle of 32.6° which will only partially correct the atmospheric dispersion. Therefore, there will still be dispersion in the altitude of a point source's position which we calculate using the equations presented in Schubert & Walterscheid (2000).

2.5.4 The focal plane mask

Table 2 lists the shapes of the currently planned FPMs. To generate new FPMs to study in our simulation, we calculate the fraction of a mask of a given shape covering each spaxel. This fraction is then multiplied by the throughput (10^{-4}) to create the template for the mask.

2.5.5 The throughput and emissivity of HARMONI

We compute the throughput and emissivity of each of the HARMONI components using information from HSI v310. The total throughput is the product of the throughput of the all individual components. Additionally, using the throughput and emissivity at the component level, the total thermal emission seen by the detector is computed.

2.5.6 Noise sources

The reflected light of Proxima b will be below the noise level in our simulation so we include a number of noise sources that might affect the recovery of the exoplanet's signal. The main source of noise comes from counting statistics, that is, Poisson noise. To calculate this, we include the pre-calculated quantum efficiency values in HSI v310 which vary slightly with wavelength as the detectors response is not perfectly uniform and assume the gain is unity. Additional noise sources included (see Table 2) are (i) the crosstalk; caused by charge leakage from neighbouring pixels, (ii) the read noise; caused by noise in the electronics, (iii) the dark current; caused by small currents in the detector present even when it is not exposed to light, and (iv) the thermal noise, caused by the thermal emission of several components within view of the detector that are not along

³https://www.eso.org/sci/facilities/eelt/docs/ESO-193696.2_Observatory_Top_Level_Requirements.pdf

the optical path and so not included in the emission of HARMONI (computed as in HSIM v310 assuming greybodies for each of the components in view). In our simulations where integration time is limited by the persistence limit, the Poisson noise and read noise contribute similar amounts to the noise on the exoplanet's spectrum.

2.5.7 Effects not included

In our simulations, we neglect the non-linear relationship between the number of photons absorbed by a pixel and the charge on that pixel as the saturation limit is reached. Proxima b's spectrum is not located on or near a pixel reaching this limit however, if significant saturation occurs, Proxima b's spectrum will be affected although this is not modelled in our simulations. We also neglect the persistence of the detector which is the limit beyond which the charge on a pixel cannot be completely discharged during a detector read. This causes a residual charge in the pixel which can last for the rest of the observation and possibly affect subsequent observations. However, all the simulations presented here are kept below the limit where persistence is noticeable. Lastly, the generated PSF does not include the additional scattering caused by the sharp edge of the FPM. HARMONI's optics past the FPM are significantly oversized, approximately 15 times larger than necessary, at the spatial scale used in this work, in order to accommodate the settings with larger spaxel scales. Thus, although the finite size of the optics means that, in principle, some of the scattered light is not reimaged back to the mask edge, the additional background contamination is not expected to be significant for HARMONI's high contrast mode. A quantitative estimate of the magnitude of contamination is complex and is beyond the scope of this work.

2.6 Simulating the observations

Ideally, each detector integration would be simulated separately as in Houllé et al. (2021) however this is very computationally intensive. In this work, we simulate groups of detector integrations creating one output observation for each group, for example, a group of 60 detector integrations, which are each 60 s, becomes a single 1 h observation. By simulating groups, hereafter referred to as 'subsimulations', we reduce the computation time and final data volume compared with simulating each detector integration separately. The noise is scaled appropriately such that it is equivalent to the noise (including read noise) that would be present if each detector integration was simulated separately. Due to computational limitations, the same realization of the PSF with 0.57 arcsec seeing is used for each observation. The subsimulations account for time-dependent changes in the motion of the planetary system and the airmass dependence in the tellurics making them a reasonable approximation to simulating all the detector integrations individually. It should be noted that no de-rotation is performed during the subsimulation so we limit the length of our subsimulations to 1 h (30 min in Section 3) to prevent the exoplanet's signal from being smeared out by more than 3 spaxels. These observations assume perfect flat fielding and wavelength calibration.

3 USING THE MOLECULE MAPPING TECHNIQUE

To first demonstrate the efficacy of our simulation, we simulate an optimally located exoplanet, assumed to have the same parameters as those in Table 1 but with a semi-major axis two times that of

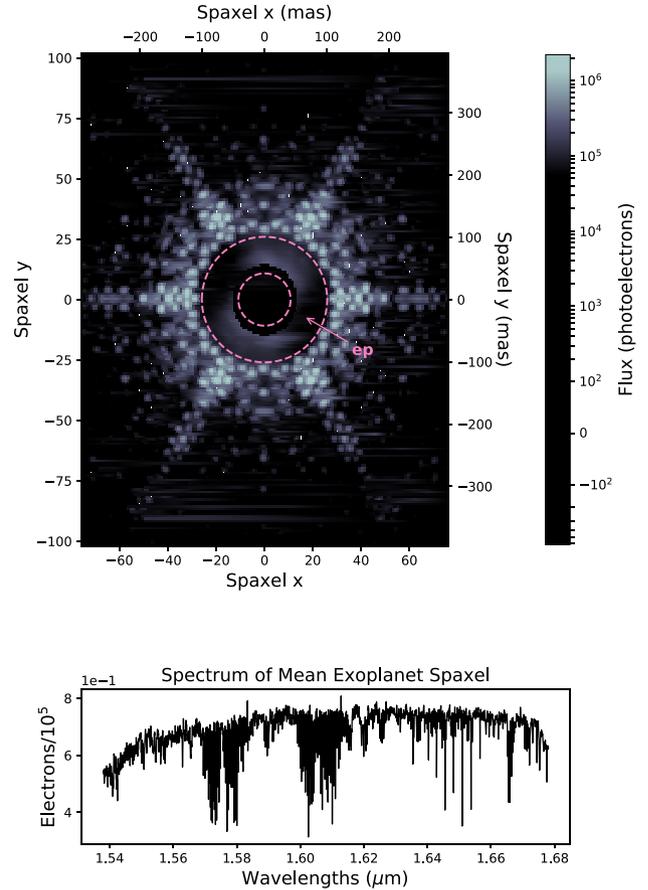


Figure 2. Fiducial simulation made with the currently planned FPM (the black ellipse in the centre of the top panel). The top panel shows the on-sky image at a single wavelength for 3 h of observations. The simulation contains an exoplanet at a separation of 68.3 mas – it is not at quadrature so its separation is less than 74.6 mas – from the star which puts it between the inner and outer working angles of the apodizer (dashed lines). We note the FPM is slightly larger than the inner working angle of the apodizer. The mean position of the planet is indicated by the ‘ep’ label, but the planet is too dim to be seen directly and is spread out due to sky rotation. The white diffuse emission inside the dark annulus is the wind-driven halo. The lower panel shows the spectrum of the ‘ep’ spaxel. It is largely dominated by tellurics and the stellar spectrum.

the real Proxima b, 0.097 au (74.6 mas), to put the exoplanet in the centre of the dark annulus (see Fig. 2). This is not a physically realistic system since the exoplanet's model spectrum is calculated for a planet with a semi-major axis of 0.0485 au (37.3 mas) but it serves as a demonstration of the technique.

3.1 Fiducial planet

We simulate observations with a spaxel size of 3.88 mas, using the *H*-High band grating of HARMONI at the highest spectral resolving power ($R = 17385$), and with the smallest FPM for SP1 apodizer (*H* band) which is 50 mas \times 58 mas in size. The detector integration time is 60 s so that the image is near but not at the persistence limit. A total integration time of 3 h is simulated per night, excluding overheads, which requires 6 subsimulations of 30 detector integrations (0.5 h each). Five nights of data are simulated, see Table 3 for details. It is worth noting that higher illumination fractions can only be observed at smaller star–planet separations resulting in a trade-off between

Table 3. The separations and fractional illuminations of the fiducial planet during the simulated observations.

Date	Average separation (mas)	Average fractional illumination
2030-04-02	68.3	0.70
2030-04-03	74.5	0.52
2030-04-09	74.0	0.56
2030-04-10	65.5	0.74
2030-04-13	65.9	0.73

increased flux and increased contamination. The simulation for the April 2, with all subsimulations stacked, is shown in Fig. 2.

3.2 Removing contaminating spectra

Despite the apodizer’s reduction of the stellar PSF, the exoplanet remains too faint to be directly visible. The stellar and telluric contamination were removed from each subsimulation using the following steps. First, the effect of crosstalk was removed to first order by subtracting the original spectrum of each adjacent pixel on the detector multiplied by the crosstalk (0.02). Without this first step, a detection is not possible due to significant residual stellar contamination. Next, the background spectrum was removed by subtracting the median spectrum of the 1000 spaxels with the lowest total flux (excluding spaxels within the FPM). Finally, the stellar and telluric contamination was removed using the method in Hoeijmakers et al. (2018) which subtracts the smoothed continuum of each spaxel multiplied by mean spectrum of the 10 000 spaxels with the highest flux. Such a large number was chosen through trial and error as it gave the best S/N out of the parameters tested. The data reduction as applied to the fiducial simulation is shown in Fig. 3.

3.3 Cross-correlation analysis

To recover the signal of the exoplanet in these reduced data we use cross-correlation analysis which combines the exoplanet’s signal spread out across wavelength. The cross-correlation coefficient is a measure of the degree of correlation (similarity) of the Doppler-shifted model and the reduced spectrum, like a normalized integration of the signal of the exoplanet over wavelength. Therefore, a spectrum containing only noise should produce a smaller correlation coefficient than one containing the exoplanet’s spectrum. For reflected light spectra, the exoplanet’s spectrum contains the stellar spectrum so the cross-correlation method is also sensitive to any residual stellar spectrum in these reduced data.

Each spaxel in the reduced simulation is cross-correlated with the model of the exoplanet’s spectrum described in Section 2.2. We use the Pearson cross-correlation coefficient which is defined as:

$$C(v) = \frac{\sum_{\lambda} (f_{\lambda}(v) - \bar{f}(v))(s_{\lambda} - \bar{s})}{\sqrt{\sum_{\lambda} (f_{\lambda}(v) - \bar{f}(v))^2 \sum_{\lambda} (s_{\lambda} - \bar{s})^2}}. \quad (3)$$

It is a function of the Doppler shift, v , of the model spectrum f . Here, s is the reduced spectrum of a spaxel in the subsimulation. The sum λ is over the wavelength bins and $\bar{f}(v)$ and \bar{s} indicate the average over wavelength of the model and reduced spectrum, respectively.

We cross-correlate each of the subsimulations at an array of Doppler shifts centred on the injected planet using the same model as the cross-correlation template yielding a 3D data cube of cross-correlation coefficients (hereafter ‘CCF cube’). These are then de-

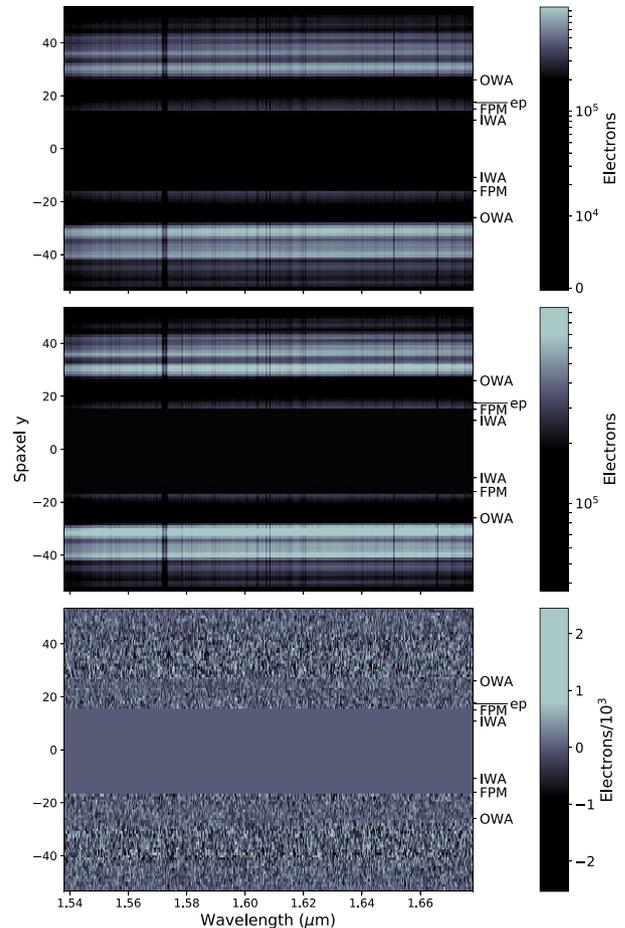


Figure 3. Data reduction applied to the fiducial simulation. The plot shows, at each stage in the data reduction, stacked subsimulation residuals for one night (3 h of integration time) for a slice along the spaxel $x = 0$. These have been de-rotated for visual purposes only so the exoplanet’s location is the same throughout the observation thereby showing the residuals at the exoplanet’s location. The top panel shows the original flux; the middle shows the residual after the cross-talk correction and background subtraction, and the bottom panel shows the residuals after the data reduction from Hoeijmakers et al. (2018) is performed. The bottom panel appears to only contain residual noise and the exoplanet’s spectrum is not visible. Along the side of each panel, the locations of the inner and outer working angles of the apodizer (IWA and OWA, respectively), the edges of the FPM and the position of the planet (ep) are indicated. The increase in the standard deviation in the noise outside the OWA is due to the increase in speckles. The region covered by the FPM is masked in the middle and bottom panels. Note the change in residual colour bar scales.

rotated so the exoplanet is in the same location in the interpolated grid and then added together to create the final CCF cube for the full integration time. This analysis requires knowledge of the planet’s orbit, however, as discussed in Section 5.1, if the orbit is unknown but all the observations are taken at approximately the same point in the planet’s orbit then the analysis can proceed as described here. This cube is converted to S/N by dividing the cross-correlation coefficients of each spaxel by the standard deviation of the coefficients. The standard deviation is calculated for each spaxel separately excluding velocities expected to include the main peaks in the model’s autocorrelation function. For these observations, this is a continuous region in velocity space 168 km s^{-1} wide centred on the velocity of the planet. Shown in Fig. 4 are two slices of the

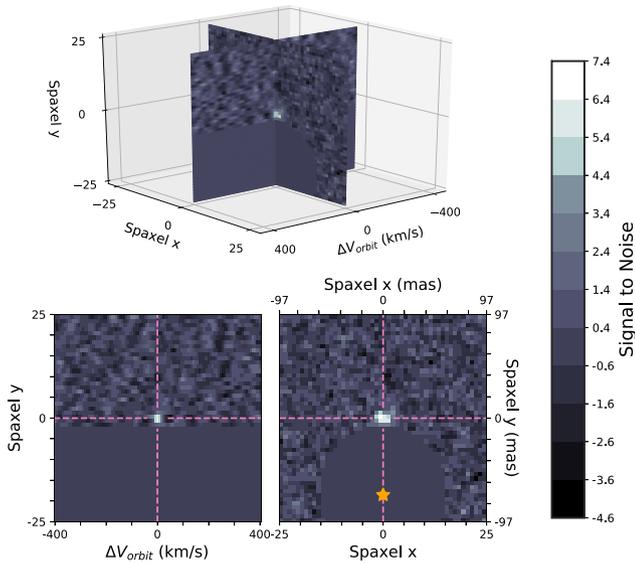


Figure 4. *S/N* of the fiducial planet simulation. The top panel shows two slices of the CCF cube, one in the plane on the sky and one along the velocity axis. The bottom panels show the same two slices separated for clarity with pink dashed lines indicating the expected position of the signal. The region covered by the FPM is greyed-out. The bottom left panel shows the *S/N* for the spaxels along spaxel $x = 0$ for different velocities relative to the exoplanet's velocity. The bottom right panel shows the *S/N* of all the spaxels at a Doppler shift equal to the exoplanet's velocity. The yellow star in the bottom right panel indicates the location of the star. Note that this injected fiducial exoplanet does not represent Proxima b.

final CCF cube created from the fiducial simulation. A signal with $S/N = 7.4$ is seen at the exoplanet's expected position and velocity, confirming we can recover planets of this contrast in the simulation. The signal is slightly spread out in the x -axis due to the sky rotation in the subsimulations.

3.4 Comparison with previous work

As mentioned in Section 2.5, our simulation uses an idealized PSF and simulates groups of integrations (subsimulations) rather than each detector integration separately. These simplifications are not made in Houllé et al. (2021) so a comparison between the two should in principle indicate whether they will significantly affect our results. Unfortunately, a direct comparison is not possible as we are unable to use their *S/N* metric as it requires individual detector integrations to be simulated. In addition, the *S/N* recovered could be affected by differences in the data reduction as, for example, we do not use principal component analysis. We create simulations using the same spectral models (ATMO model at $T_{\text{eff}} = 800$ K, $\log(g) = 4.0$; Phillips et al. 2020), Doppler shifts and airmasses as in Houllé et al. (2021), and compute an $S/N = 5$ detection contrast curve for 2 h of integration time using our metric. Our curve and its equivalent from Houllé et al. (2021) for a 5σ detection with 2 h of integration time are shown in Fig. 5. Due to the different metrics being used, the absolute values should not be compared, however the similarity in the shape and scale indicates that our simulation is valid and a reasonable approximation of previous work. We note, however, these observations will be pushing the limits of what HARMONI could achieve and it is ultimately very hard to predict how an instrument will behave prior to its operation. Ideally observations

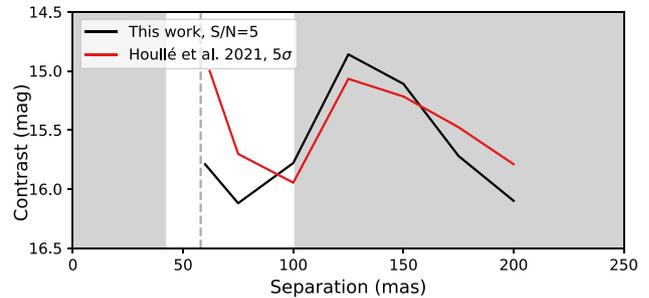


Figure 5. A contrast curve for an $S/N = 5$ detection of a T-type companion ($T_{\text{eff}} = 800$ K) with 2 h of integration time using the simulation process and analysis described in this work and its comparison 5σ detection curve from Houllé et al. (2021). The x -axis indicates the separation from the star in the centre of the field of view. The shaded regions are outside the inner and outer working angles for the apodizer. The FPM is 58 mas at its widest point, indicated by the dashed line, so we do not attempt to recover planet's closer than this. The curves cannot be directly compared as they use different *S/N* metrics although the scales and shapes broadly agree indicating our simulation is a reasonable approximation of previous work. The reduced detection efficiency around 125 mas is due to increased speckle noise at these separations which can be seen in Fig. 2.

of wider-separated and brighter planets would be used to determine HARMONI's performance prior to attempting these observations, however, any changes in instrument design required to facilitate these observations would have to be committed to hardware before HARMONI's true performance is known.

4 OBSERVING PROXIMA B WITH HARMONI

With molecule mapping, it is possible to push to within the inner working angle (e.g. Hoeijmakers et al. 2018) (~ 40 mas or $5\lambda/D$ at $1.538 \mu\text{m}$ for the SP1 apodizer), however even the smallest of the FPMs ($50 \text{ mas} \times 58 \text{ mas}$) will completely cover the orbit of Proxima b which has a maximum separation from Proxima Centauri of 37.3 mas. It is not possible to detect Proxima b when it is behind the FPM and, due to limited space, it is not possible to add additional apodizers and FPMs to HARMONI. We suggest and simulate here two solutions to this problem: offsetting the FPM, or replacing one of the FPMs with a smaller mask. For the latter case, a careful assessment on the impact of this change to other science cases compared with the benefits to this case would be needed to justify such a change.

It is possible that Proxima b's orbit will be well constrained before HARMONI observes it, therefore, in our simulations, we assume we already know the orbit of Proxima b (see Table 1) meaning we can predict it is on-sky position and Doppler shift. Proxima b is observable in all the observations simulated and the final CCF cubes are Doppler shifted and de-rotated to align the planet's signal. Later in Sections 4.5 and 5.1 we explore when such observability would occur.

4.1 Offsetting the mask

To observe Proxima b with the current instrument design, the star could be offset from the centre of the field of view so that the mask does not cover the on sky location of Proxima b. This should not affect the performance of the AO system. We create a simulation where the star is offset by 20 mas in azimuth (see panel 4 of Fig. 6). We assume we know the orbit of Proxima b and simulate 70 observations – each with a total of one hour integration time using a detector integration

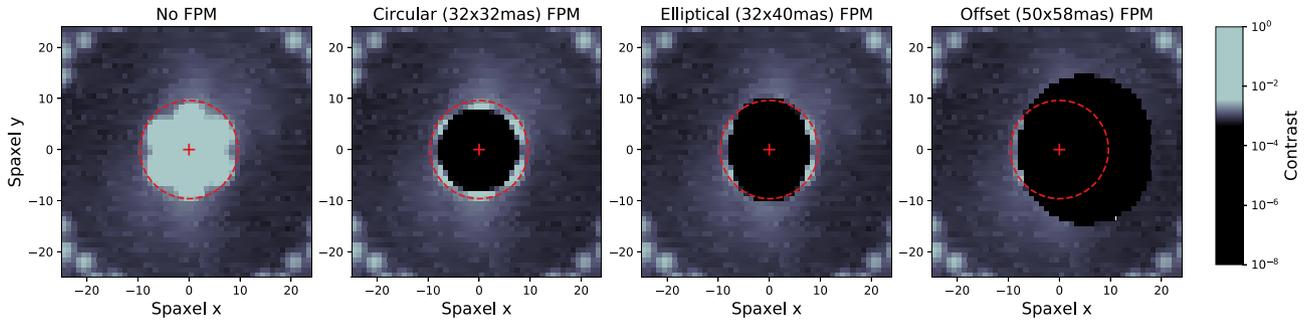


Figure 6. FPM’s analysed in this work displayed on a map of the stellar PSF. The red cross indicates the position of the star and the red dashed line is the maximum separation of Proxima b, that is Proxima b will always lie somewhere within this circle. Starlight leaking around the edge of the mask will scatter and increase the stray light in the instrument. This is not modelled in our simulation.

time of 60 s – spread out over two years in which Proxima b is not behind the FPM. We treat each observation separately in the data reduction due to the changes in relative positions and velocities of the star, planet, and Earth. The analysis is performed as in Section 3.1 which produces 70 CCF cubes. We de-rotate and Doppler shift these, assuming the known orbit, to align the exoplanet’s signal.

4.2 Decreasing the mask size

Ideally the orbit of Proxima b would need to be known so that the direction and magnitude of the offset could be calculated. If the orbit is unknown a guess for the offset could be used but this increases the number of observations required for a detection as discussed later in Section 5.4. An alternative would be to replace one of the FPMs with a smaller mask that does not completely cover Proxima b’s orbit. This could be accomplished during construction or operation; however, the latter would likely only occur during scheduled interventions approximately 5–10 yr after first light.

We analyse three different sizes and shapes for a new FPM to determine which would be best for observing Proxima b. We choose ‘No FPM’ mask, a ‘Circular FPM with radius 32 mas’ and an ‘Elliptical FPM with dimensions 32×40 mas’. The region covered by circular FPM will not change significantly which is ideal if the on-sky location of Proxima b is unknown but the elliptical mask better covers the central diffraction peak reducing the amount of star light leakage (see Fig. 6).

We create simulated observations for each of the FPMs assuming a detector integration time of 60 s so that the detector is near but not at the persistence limit in the circular and elliptical cases. This restricts the airmass of the observations due to leakage around the circular mask caused by atmospheric dispersion. This could be improved by decreasing the integration time but doing so would make the read noise the dominant noise source. In the no FPM simulation, the core of the PSF is over the persistence limit. In total, 56 h of integration time are simulated, on the same dates in each case, spread out over two years. The times selected are primarily driven by the elliptical mask due to its larger size. The restrictions imposed by our observing conditions limit the continuous time window for observations to around 2 h. We analyse each subsimulation as in Section 3 which yields 56 CCF cubes per FPM which we de-rotate and Doppler shift, assuming the known orbit, to align the exoplanet’s signal.

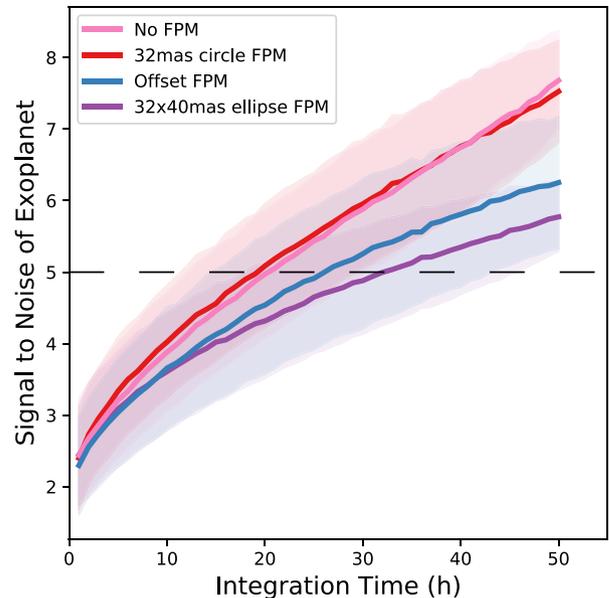


Figure 7. Average recovered S/N of Proxima b in our simulations using the planet absorption and stellar spectrum cross-correlation model for each FPM as a function of integration time. An S/N of 5 is indicated by the dashed line. The standard deviation in the recovered S/N is indicated by the shaded region. See Section 5.4 for a discussion of the implications of using these options and ultimately which is the most suitable.

4.3 Detecting Proxima b

To calculate the integration time necessary for a detection with a given mask, the CCF cubes are stacked and the S/N of the stack is computed as in Section 3.3. The S/N of the detection is taken as the maximum in the three-by-three grid of spaxels centred on the expected position of the exoplanet. The S/N for integration times less than the total time simulated is obtained by varying which cubes are stacked. This is repeated and the mean and standard deviation in the S/N recovered is shown for each of the FPM’s in Fig. 7. An S/N of 5 is used as the detection threshold as, when no exoplanet signal is present, $S/N \approx 4$ can still be obtained through the random combination of noise (see e.g. Cabot et al. 2019; Spring et al. 2022). A detection with an $S/N \geq 5$ will require at least 20 h of time on the ELT (for the assumed orbital orientation of Proxima b). Our simulations show significant variations in the signal obtained for different observations which leads to changes in the amount of time

required. In the simulations, as little as 12 or as much as 30 h could be necessary for a detection with the circular or no FPM, between 18 to 45 h for the elliptical mask and between 14 to 43 h for the offset mask. The variation in the S/N recovered is due to three effects. First, the exoplanet is at different on sky positions which changes the amount of stellar contamination. Second, the amount of Proxima b which is illuminated changes meaning the amount of light we receive from the planet is changing. Finally, the random nature of the noise can affect the S/N recovered even if everything else is kept the same. We note that the due to the difficulty with selecting common dates, the offset simulation is comprised of a different set of observations to the other three cases. However, the average separation – 35.5 mas for the offset mask and 36.9 mas for the other three – and illumination fraction – 0.63 for the offset mask and 0.56 for the other three – of Proxima b is similar in both cases.

We note that the S/N of the detection does not scale with the square root of the integration time. This is due to a number of effects, the most significant of which are (i) the read noise at the planet’s location is similar in magnitude to the photon noise and, (ii) there is residual stellar spectrum present in the noise which correlates with the planet’s spectrum. Less significant effects include (iii) the signal is smeared out slightly within a subsimulation due to the on sky rotation, (iv) the FPM’s effect on the background spectrum which reduces the efficiency of the data reduction near the edge of the mask and, (v) residuals from the telluric spectrum which can correlate with the planet’s spectrum as they contain the same species. A better data reduction may improve the S/N recovered, however, perfecting the data reduction is beyond the scope of this work. Even in this case where we perfectly know and control all sources of noise, the simulation does not scale as Poisson statistics. Careful and detailed simulations, particularly when close to the read noise, are needed for all future instrumentation for the ELTs to fully understand how they will respond for high-resolution spectroscopy (HRS) of exoplanet atmospheres.

4.4 Detecting Proxima b’s atmosphere

In Section 4.3, we used a cross-correlation model that is a perfect match to the planet’s spectrum in the simulated data, which contains features from the reflected stellar spectrum and from the atmospheric absorption of the planet. To determine if we are sensitive to the planet’s atmospheric absorption, we repeat the ‘no FPM’ simulation but cross-correlate with a model of the stellar spectrum only (no planet absorption features, cf. Hawker & Parry 2019) and with a model with only the planet absorption (no stellar features). We also cross-correlate with a model containing only the CO₂ lines and one with only the CH₄ lines. A comparison between the S/N recovered for the different cross-correlation models is shown in Fig. 8. When the stellar and the planetary absorption features are used as the cross-correlation model, a detection with an S/N of 5 is obtainable in approximately 20 h which increases to 40 h if only the planet’s absorption features are used. Of the planet’s absorption features, CH₄ lines contribute the most signal to the detection. CO₂ which has more spectral lines in this wavelength range is not well detected in 50 h. This is because CO₂ has strong aliases in its autocorrelation function in this wavelength regime meaning the telluric residuals create more noise in the CCF than they do for CH₄, hindering the detection. An improved data reduction might result in a stronger detection for CO₂. For the stellar spectrum only model no significant detection is made in 50 h. Again, this is due to the imperfect data reduction which leaves behind a small residual stellar spectrum in the data. The residual strongly correlates with the stellar spectrum only

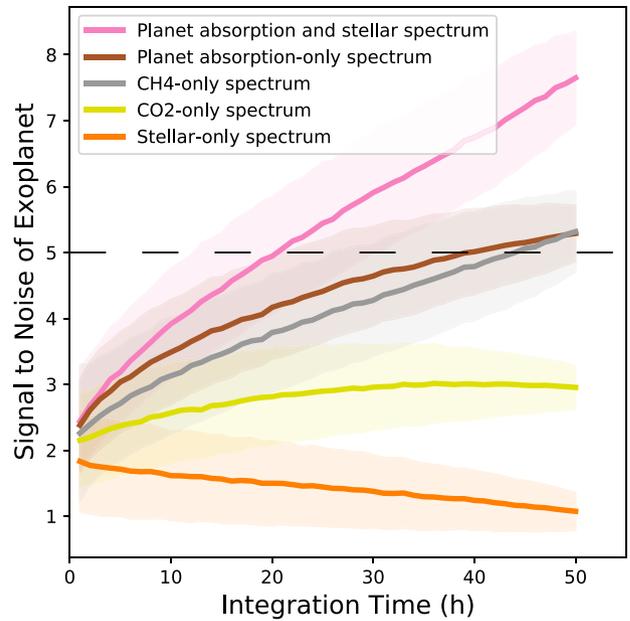


Figure 8. The average recovered S/N of Proxima b for the no FPM simulation as a function of integration time when cross-correlated with the stellar spectrum only model (orange), planet absorption only model (brown), the model planet spectrum (atmospheric absorption and reflected stellar lines, pink), a model containing only the CH₄ lines (grey), and a model containing only the CO₂ lines (yellow). The 1 σ variation in the recovered S/N is indicated by the shaded region.

model creating correlated noise in the CCF. The S/N of the residuals grows faster than S/N of the planet which prevents the detection of the planet’s signal.

4.5 Time available for observations

The amount of Proxima b’s orbit covered by each mask and therefore the amount of time it could be observed depends on the currently unknown shape and orientation of the orbit. We calculate the observation time available for different orbits between midday on the 2030 January 1 and mid-day on the 2031 January 1 for the observing criteria described in Section 2.3 with the additional conditions: (i) for ‘no FPM’, Proxima b’s is not on a spaxel which is above the persistence limit, and (ii) for the circular and elliptical FPMs, there are no spaxels above the persistence limit assuming an integration time of 60 s. The result of these calculations is illustrated in Fig. 9 where each plot shows time available for a range of inclinations and longitude of the ascending node of the orbit. For almost all orbital inclinations with the no FPM and circular FPM, there is at least 70 h of time available to observe Proxima b. For the elliptical mask, there is less time available for the orbits that more frequently align with the elongated direction of the mask. We do not calculate the amount of time available for the offset mask case as it will depend on the maximum allowable offset which is currently unknown.

5 DISCUSSION

5.1 What if Proxima b’s orbit is not well constrained?

It is impossible to constrain Proxima b’s orbit with radial velocities alone. *Gaia*’s astrometric precision makes it sensitive only to near face-on orbits but its observing cadance may not be sufficient to

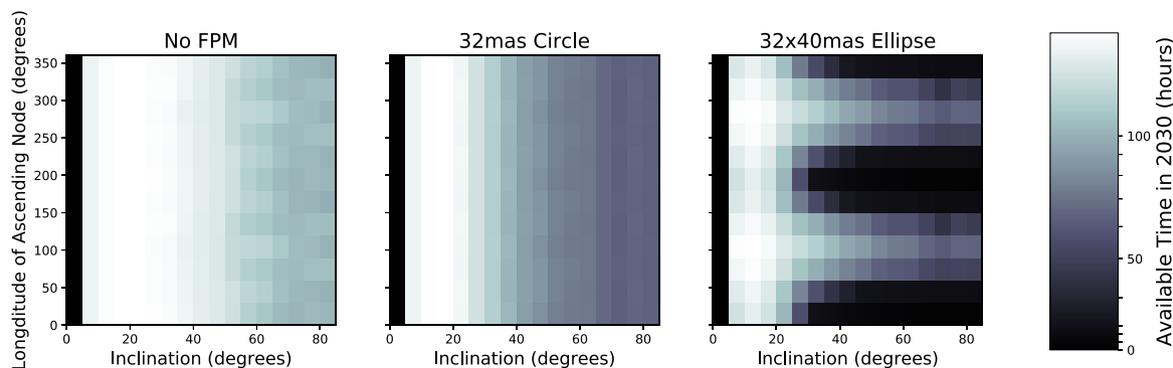


Figure 9. The amount of time available for which our observing conditions for Proxima b are met between 2030 and 2031 January 01 as a function of the inclination and longitude of the ascending node of Proxima b’s orbit. Each plot shows the results for the different FPMs.

measure the astrometric wobble in Proxima Centauri’s position induced by Proxima b. For Proxima b’s orbit to be known before these observations, it would have to be observed by another integral field or long-slit spectrograph as detection via direct imaging alone without cross-correlation is unlikely with current planned instruments for ELT. If the orbit of Proxima b is not well known then observations could be made when Proxima b is at quadrature, the time of which is known from radial velocity measurements. At quadrature, Proxima b’s separation from Proxima Centauri will be at its maximum, it will have a different Doppler shift to Proxima Centauri (if the orbit is not too close to face-on), and approximately half of its surface should be illuminated thus meeting our observing criteria from Section 2.3. Therefore, by observing within a small phase range around one of the quadrature points – approximately the same point in its orbit for each observation – the observations will only need to be aligned to celestial coordinates and Doppler shifted to remove the barycentric motion in order to align the planets signal for the analysis in Section 3.3. However, this technique may require more observations depending on whether the mask blocks the planet at quadrature.

5.2 Feasibility of the observations

Assuming only observations with the simulated seeing (0.57 arcsec) or better are made then around 30 per cent⁴ of the time available (see Fig. 9) can be used. Worse seeing could be used but these would contribute less to the detection of the exoplanet due to increased stellar contamination at the exoplanet’s location.

With the circular mask it is possible, in most cases, to obtain 20 h of integration time under the right conditions within ~ 1 yr with the exception of near face-on orbits. For the elliptical mask it may take longer depending on the alignment of Proxima b’s orbit. Near face-on orbits have very little time available due to the velocity criterion however, the inclinations where this effect is significant correspond to over a factor of 10 difference between the measured minimum mass and the true mass of Proxima b which changes the amount of reflected light and therefore time required significantly. It should be noted that this will not take up a large fraction of the telescope’s available time, merely that it will require a series of observations spread out over the course a few years due to the strict restrictions on when the observations can take place.

⁴https://www.eso.org/sci/facilities/eelt/docs/ESO-193696.2_Observatory_Top_Level_Requirements.pdf

5.3 Caveats of the simulation

Simulations rarely capture all of the nuances of real observations and the simulations presented here have a number of caveats that will affect our results. First, we use the same simplified PSF with no wavelength dependence for each observation. This results in the speckles behaving as white noise sources instead of $1/f$ noise. This simplification decreases the amount of time required for a detection. Secondly, we do not include scattering caused by the sharp edge of the FPM. Although this effect is not expected to be significant, increased light leakage around the mask may increase the amount of integration time required. Since Proxima b can only be observed close to the mask edge, it will be pushing the limits of what HARMONI can do. Proof will ultimately be realized on sky, and greatly aided by a known orbit for Proxima b.

5.4 Selecting a mask

5.4.1 Observing Proxima b with no FPM

Fig. 7 indicates that observing without a FPM would be ideal for characterizing Proxima b, however, our simulations do not include a realistic treatment of the effects of persistence in the detector. In reality, it will not be possible to use 60 s integrations without a FPM as the star will cause persistence that may severely impact these and subsequent observations, particularly of faint targets. To observe without a FPM, the integration time would have to be reduced to ~ 0.5 s resulting in a poor duty cycle and drastically increased the read noise which would strongly hinder the retrieval of the exoplanet’s spectrum.

5.4.2 Using the circular FPM with radius 32 mas

The next best performing mask as indicated by Fig. 7 is the circular FPM with radius 32 mas. However as seen in Fig. 6, of the remaining masks, this has the largest amount of light leaking around its edge which may impact the detection. Additionally, to avoid persistence with 60 s integrations, the observations are limited to low airmass.

5.4.3 Observing Proxima b by offsetting the currently planned FPM

Offsetting the mask does not result in as strong a detection as the no FPM and circular FPM cases. Additionally, if the orbit of Proxima b is not well constrained as it will not be possible to predict what offset to use to detect the exoplanet, even if observations are made at

quadrature. This increases the amount of telescope time needed for the offset mask as trial and error would be required to find the right offset drastically lowering the efficiency of these observations.

5.4.4 Using the elliptical FPM with dimensions 32×40 mas

The elliptical FPM does not perform as well as the other masks as the planet is on average closer to its edge however, given the caveats discussed this is likely the most viable option. None the less, there is still leakage around the mask edge and, due to its elongation, the mask could cover the orbit of Proxima b even at quadrature. If Proxima b's orbit is unknown, this would lower the efficiency as the planet could be behind the mask during some observations.

5.4.5 Changing the apodizer

Reducing the light leakage around the mask edge would likely benefit these observations. While not studied in this work, one way to potentially achieve this is to change the apodizer to decrease the size of the central core of the PSF. This would allow the FPM to be decreased in size, whilst still protecting the detector from saturation and persistence, and making the observations more robust against pointing errors. However, as with changing the FPM, changing the apodizer requires careful consideration of its effect on other science cases.

5.5 Other instruments

HARMONI is not the only instrument that could be used to observe this target. The introduction lists a number of instruments that might also be able to detect the atmosphere of Proxima b. However, HARMONI will be one of the first instruments available and therefore one of the first that could make these observations. Other instruments that could potentially detect the atmosphere of Proxima b at around the same time are METIS@ELT (Brandl et al. 2021), GMagAO-X@GMT (Males et al. 2022), and IRIS@TMT (Wright et al. 2016). Of these, GMagAO-X and IRIS will both be sensitive to the reflected light of Proxima b like HARMONI however owing to smaller primary mirrors, they have lower spatial resolutions. Careful consideration would be needed to determine if these instruments could observe and characterize Proxima b. METIS will be sensitive to the thermal emission ($3\text{--}5\ \mu\text{m}$) of Proxima b and has a higher spectral resolving power than HARMONI ($R = 100\,000$), although its spaxel scale is larger ($8.2\ \text{mas} \times 21\ \text{mas}$; Brandl et al. 2021), Proxima b is resolvable with this instrument (λ/D at $4\ \mu\text{m}$ is $21\ \text{mas}$).

With the potential of all these instruments to observe Proxima b, we have the opportunity to obtain one of the most detailed spectra of an Earth-like exoplanet to date, spanning both the reflection and thermal emission of this world. Although one could argue that each instrument could be sensitive to similar atmospheric properties, given this planet could potentially host a habitat similar to Earth, the extra degree of certainty and complementary overlap would be ideal. Additionally, having access to both the thermal emission and reflection of this planet may give us additional information on its atmospheric composition, temperature distribution, cloud and haze properties, and energy balance (e.g. Crossfield 2013; Morley et al. 2015; Steinrueck et al. 2023), for a full, holistic study.

5.6 Other temperate terrestrial exoplanets

We have only considered the temperate terrestrial exoplanet Proxima b in this work as, of the known exoplanets of this type, it is the easiest to observe in reflected light. The next best known temperate exoplanet to observe is Wolf 1061 c which has an on sky separation, also inside the IWA, of approximately $20\ \text{mas}$ (although this exoplanet is close to the boundary between rocky and gas giant exoplanets so it may not be terrestrial). This exoplanet's separation is too small to observe with HARMONI unless the apodizer is changed. It is possible that there are temperate terrestrial exoplanets orbiting nearby stars with larger on sky separation that we have yet to identify. However, for an Earth-like planet to be bright enough compared to its star for current instrumentation to detect, it must orbit close to the star which limits suitable targets to nearby M-dwarfs. Proxima Centauri is the closest M-dwarf to the Solar system and as such Proxima b is almost certainly the best target we will have for these observations.

6 CONCLUSIONS

We simulate observations made with the HCAO mode of HARMONI@ELT to determine the viability of using the molecule mapping technique to characterize the atmosphere of the terrestrial exoplanet Proxima b in reflected light. HARMONI's HCAO mode uses an apodizer to suppress the diffracted star light in a ring around the star and an FPM to suppress the central diffraction peak. If Proxima Centauri is observed on axis using the apodizer with the smallest inner working angle and the smallest FPM, Proxima b's orbit will be fully obscured by the FPM.

Here, we explored relatively minor modifications to the current design of HARMONI to counteract this. The design change required depends on how well the orbit of Proxima b is constrained and how large of an impact the change will have on other science cases. The instrument's design will likely have to be committed to hardware before more information on the planet's orbit is available. If Proxima b's orbit will be well known at the time of the observations, then no changes may be required as the star could be offset from the centre of the field of view allowing the exoplanet to be unobscured by the FPM. Our simulations show a detection could be possible with this set up but do not account for the increased stray light due to the star being close to the edge of the mask. If the orbit will not be well known then the current FPM could be replaced by a smaller one. This work indicates that with our caveats, doing so should allow characterization of Proxima b, requiring at least $20\ \text{h}$ and ideally at least $30\ \text{h}$ of integration time for an $S/N \geq 5$ detection assuming an orbital inclination of 45° . The masks investigated in this work typically limit observations to $2\ \text{h}$ per night so around 10 such observations would be needed which, for inclination of 45° , could be obtained over a period as short as 4 months. The S/N of this detection is dominated by the atmospheric features in the planet's spectrum and is particularly sensitive to the biosignature CH_4 . This is highlighted when the star-only template is used as the cross-correlation model. In this case there is no significant peak in the cross-correlation coefficients at the expected position and velocity of the planet. This is due to correlated noise from the residual stellar contamination which creates signals in the cross-correlation stronger than the planet's signal inhibiting the detection. Finally, while not investigated here, changing both the FPM and modifying the apodizer to have a smaller central core, would likely improve the detection of Proxima b with HARMONI. This would help mitigate potential issues with stray light and may allow other temperate terrestrial

exoplanets to be characterized depending on the new inner working angle.

As changing the mask will require removing one of the current masks, and changing the apodizer would change the range of separations the HCAO mode can be used for, careful consideration would be required as to how these changes effect other science cases.

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DATA AVAILABILITY

The data underlying this article will be shared on reasonable request to the corresponding author. This work has made use of NUMPY (Harris et al. 2020), SCIPY (Virtanen et al. 2020), MATPLOTLIB (Hunter 2007), and ASTROPY,⁵ a community-developed core PYTHON package and an ecosystem of tools and resources for astronomy (Astropy Collaboration 2013, 2018, 2022).

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